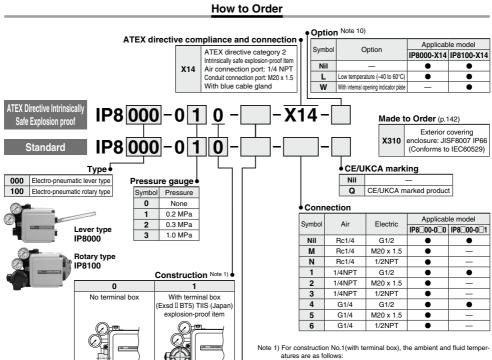
Electro-Pneumatic Positioner (CA (Lever type/Rotary type)

IP8000/8100 Series

- Enclosure: JISF8007 IP65 (conforms to IEC 60529)
- Monitoring function (Opening current transmission 4 to 20 mA DC, Accessory J, JR)
- Explosion-proof construction/Electro-pneumatic positioner: TIIS explosion-proof construction (Exd II BT5), ATEX intrinsically safe explosion-proof construction (II 2G Ex h ib IICT5/T6 Gb)



- Exd II BT5 −20 to 60°C
- Non-explosion proof (non hazardous locations only) -20 to 80°C
 The positioner body is EXd II BT5 labeled.

Note 2) If two or more accessories are required, the part numbers should be made according to alphabetical order. (ex. IP8100-010-AG)

Note 3) "A" is applied to approx 90cm3-capacity actuator.

"B" is applied to approx 90cm³-capacity actuator.

Note 4) Fork lever-type fitting MX (Connection thread: M6 x 1) for IP8100-0\[Display\)-\[Display\)-X14. Note 5) Fork lever-type fitting SX (Connection thread: M6 x 1) for IP8100-0\[Display\)-\[Display\)-X14.

Note 6) Standard lever is not attached.

Note 7) It is to be used together with "A" or "B" when tending to overshoot by the use of "A" or "B".

It is mounted to the body as a replacement of the standard compensation spring.

Note 8) For side mounting, select a model with internal opening indicator plate (IP810-0□□□□□-X318 for standard type, X14-W for ATEX intrinsically safe explosion-proof type).

Note 9) Symbol J/JR is with terminal box, non-explosion proof specification. Select 1 for Construction. Positive operation signifies clockwise rotational direction by the main actuator shaft when positioner cover is viewed from the front.

Note 10) Combination of L and W is not available.

Accessories Note 2) Applicable model Symbol Accessories IP8000 IP8100 None (Standard) ø0.7 Output restriction with pilot valve Note 3) Α ø1.0 Output restriction with pilot valve Note 3) R Fork lever-type fitting M Note 4) C Fork lever-type fitting S Note 5) D Ε For stroke 35 to 100 mm with lever unit Note 6 For stroke 50 to 140 mm with lever unit Note 6) G Compensation spring (A) Note 7) With external scale plate Note 8) н • With opening current transmission (4 to 20 mA DC)/Positive operation Note 9 With opening current transmission (4 to 20 mA DC))/Reverse operation Note 9)

Smart Positioner (Lever type/Rotary type)

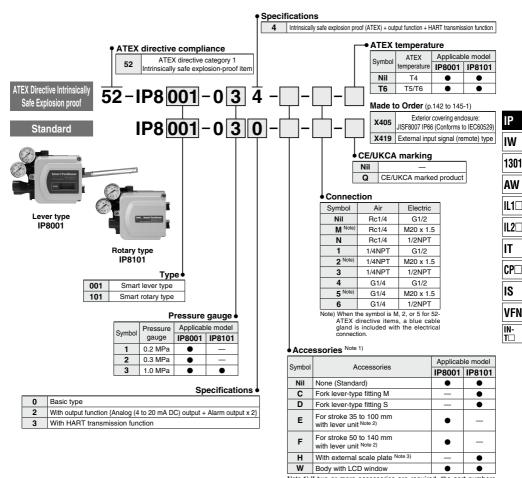
C E UK

IP8001/8101 Series

Auto calibration

- HART transmission function
- Enclosure: JISF8007 IP65(conforms to IEC 60529)
 - Monitoring function
- Explosion-proof construction/ATEX intrinsically safe explosion-proof construction (II 1G Ex h ia IICT4/T5/T6 Ga)

How to Order



Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. (ex. IP8101-010-CH)

Note 2) Standard lever is not attached.

Note 3) For side mounting, select "-W" and check the control position by viewing the LCD display value.



Specifications Note 1)

Туре	IP8	000	IP8	100	IP8001	IP8101	
		Electro-Pneum	natic Positioner		Smart Po	ositioner	
	Lever type lever feedback Rotary type cam feedback		am feedback	Lever type	Rotary type		
Item	Single action	Double action	Single action	Double action	Single action /	Double action	
Input current				4 to 20 mA DC	(Standard) Note 2)		
Min. operating current		-	_		3.85 mA D	C or more	
Intra-terminal voltage		-	_		12 V DC (equivalent to 600 Ω i	nput resistance, at 20 mA DC)	
Max. supplied power		-	_		1 W (Imax: 100 mA [DC, Vmax: 28 V DC)	
Input resistance		235 ±15 Ω (4	to 20 mA DC)		_	_	
Supply air pressure				0.7 MPa		0.3 to 0.7 MPa	
Standard stroke	10 to 85 mm (Allowable of	deflection angle 10 to 30°)	60 to 10	0° Note 3)	10 to 85 mm (Allowable deflection angle 10 to 30°)	60 to 100° Note 3)	
Sensitivity Note 4)	Within 0.1% F.S.		Within 0.5% F.S		Within 0.	2% F.S.	
Linearity Note 4)	Within ±1% F.S.		Within ±2% F.S		Within ±	1% F.S.	
Hysteresis Note 4)	Within 0.75% F.S.		Within 1% F.S.		Within 0.5% F.S.		
Repeatability Note 4)				Within ±0	±0.5% F.S.		
Coefficient of temperature		Within 0.1	% F.S./°C		Within 0.05% F.S./°C		
Supply pressure fluctuation		Within 0.3% F.S./0.01 MPa			Note 5)		
Output flow Note 6)		80 L/min (A	NR) or more (SI	JP = 0.14 MPa)	200 L/min (ANR) or more (SUP = 0.4 MPa)		
Air consumption Note 6)	5 L/min (ANR) or less (SUP = 0.14 MPa)			MPa)	2 L/min (ANR) or less (SUP = 0.14 MPa)	11 L/min (ANR) or less	
All consumption	11 L/min (ANR) or less (SUP = 0.4 MPa)			ЛРа)	4 L/min (ANR) or less (SUP = 0.4 MPa)	(SUP = 0.4 MPa)	
	General structure: -20 to 80°C						
Ambient and fluid	TIIS explosion-proof: -20 to 60°C						
temperature	ATEX intrinsically safe explosion-proof: —20 to 80°C (T5)				ATEX intrinsically safe explosion-proof -20 to 80°C (T4/T5)		
				–20 to 60°C (T6)			
			. , ,,	perature specification			
Explosion proof construction Note 7)		explosion-proof co			ATEX intrinsically safe exp		
	,	afe explosion-proof			(II 1G Ex h ia II	,	
ATEX intrinsically safe explosion-proof	'	Ji ≤ 28 V, Ii ≤ 12		V	Ui ≤ 28 V, Ii ≤ 10		
parameter (current circuit)		Ci ≤ 0 nF,			Ci ≤ 12.5 nF,	LI ≤ I.5 MH	
Exterior covering enclosure Note 8)			JISF80	007, IP65 (conto	orms to IEC Pub.60529) HART transmission		
Transmission method Note 7)				NDT 4/4 f-			
Air connection port Note 9)					male thread, G 1/4 female thread		
Electrical connection port Note 9)				.,	nale thread, NPT 1/2 female thre	ao	
Material/coating	0.4 km (\400)				inish with denatured epoxy resin	les.	
Weight	2.4 kg (With	nout terminal bo	c)/∠.6 kg (vvith te	erriinai box)	2.6 kg		

Note 1) Specification values are given at normal temperature (20°C).

Note 2) 1/2 Split range (Standard). For operation with 1/2 split range, the linearity and

hysteresis should be 1% higher than the above specifications.

Note 3) Stroke adjustment: 0 to 60% 0 to 100°

Note 4) Characteristics relating to accuracy differ depending on combination with other constituent loop equipment, such as positioners and actuators.

Note 5) While there is no output changes due to pressure fluctuations, when the pressure supply setting is changed following calibration, once again adjust balance current and perform calibration.

Note 6) Air consumption is due to exhaust from nozzle. And (ANR) indicates JIS B0120 standard air.

Note 7) Model selection required for explosion proof construction and HART transmission. Note 8) For IP66 compliant products, refer to pages 142 to 145.

Note 9) Thread type can be specified by model selection.

Optional Specifications

	Туре	IP8100-0□1-J/JR (Non-explosion proof)	IP8□01-0□2 (Non-explosion proof)	52-IP8□01-0□4			
Item		Electro-Pneumatic Positioner	Smart Positioner				
	Wiring		2-line				
	Output signal	4 to 20 mA DC					
Analog	Power supply voltage	12 to 35 V DC	10 to 28	3 V DC			
output	Load resistance	(Power supply voltage -12 V) ÷ 20 mA DC or less	0 to 7	'50 Ω			
	Accuracy	±2% F.S. or less Note 1)	±0.5% F.S. or less Note 2)				
	Hysteresis	Within 1% F.S.	_				
	Wiring	_	— 2-line				
	Applicable standards	_	_	DIN19234/NAMUR Standard			
	Power supply voltage	_	10 to 28 V DC	5 to 28 V DC			
Alarm output 1, 2	Load resistance	_	10 to 40 mA DC	(Constant current output)			
output 1, 2	Alarm ON	_	R = 350 Ω ±10%	≥ 2.1 mA DC			
	Alarm OFF (Leakage current)	_	0.5 mA DC or less	≤ 1.2 mA DC			
	Response time	_	50 msed	or less			

Note 1) Indicates analog output accuracy with respect to actuator angle.

Note 2) Indicates analog output accuracy with respect to LCD display position value (P value).



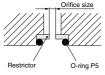
Accessory/Option

Pilot valve with output restriction (IP8000/8100)

In general, mounting on a small-size actuator may cause hunting. For prevention, a pilot valve with a built-in output restriction is available. The restriction is removable.

Actuator capacity	Orifice size	Part number	Pilot unit part number	Model selection accessory
90 cm ³	ø0.7	P36801080	P565010-18	Α
180 cm ³	ø1	P36801081	P565010-19	В

Note) Output orifice not required for Smart Positioner regardless of actuator capacity





Restrictor mounting diagram

Pilot valve bottom view

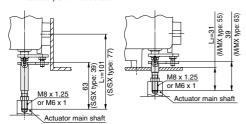
Fork lever-type fittings (IP8100/8101)

2 kinds of rotary type IP8100/8101 fork lever-type fittings, that differ by installation dimensions dependent on bracket installation method, and 2 kinds of installation portion thread sizes, are available

When installing on the side surface, using fork lever assembly M provides interchangeability with the installation dimensions of SMC IP610 positioner. When installing on the rear surface, using fork lever assembly S also provides interchangeability with the installation dimensions of SMC IP610 positioner.

Part name	Unit number	Installation portion thread size	Model selection accessory
Fork lever assembly M	P368010-24	M8 x 1.25	С
Fork lever assembly S	P368010-25	IVIO X 1.25	D
Fork lever assembly MX	P368010-36	M6 x 1	C Note)
Fork lever assembly SX	P368010-37	IVIOXI	D Note)

Note) Installation portion thread size is M6 x 1 for IP8100-0□0-X14 when accessory C or D are selected.



Side mounting with the fork lever assembly M/MX

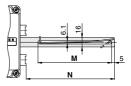
Rear mounting with the fork lever assembly S/SX

External feedback lever (IP8000/8001)

Different feedback levers are available dependent upon valve strokes. Order according to the valve stroke.

Feedback lever types

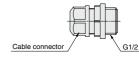
Stroke	Unit n	Size M	Cino N	Model selection	
Stroke	IP8000	IP8001	SIZE IVI	Size IN	accessory
10 to 85 mm	P368010-20	P565010-323	125	150	Standard accessory
35 to 100 mm	P368010-21	P565010-324	110	195	E
50 to 140 mm	P368010-22	P565010-325	110	275	F
6 to 12 mm	P368010-260	P565010-329	75	75	Available as special order



Resin connector (Non-explosion proof specification)

Optional cable connectors are available for different cable sizes. These are not for explosion proof applications. Recommended for use with indoor applications.

Part name	Part number	Suited cable outer diameter
Resin-made cable clamp unit (A)	P368010-26	ø7 to ø9
Resin-made cable clamp unit (B)	P368010-27	ø9 to ø11



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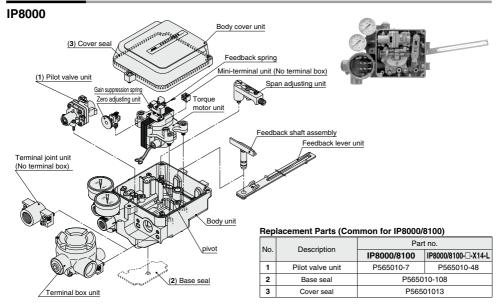
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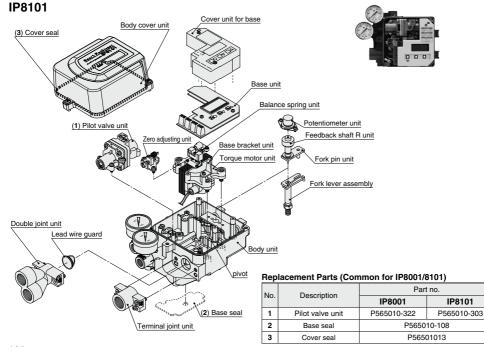
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IP8□ Series

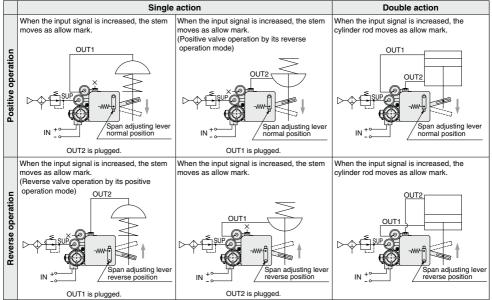
Exploded View



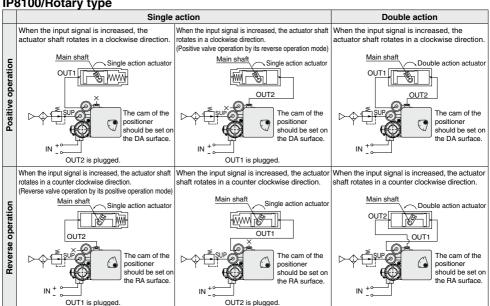


Piping Note) When the input signal is discontinued, the pressure of OUT1 decreases, and the pressure of OUT2 increases.

IP8000/Lever type



IP8100/Rotary type



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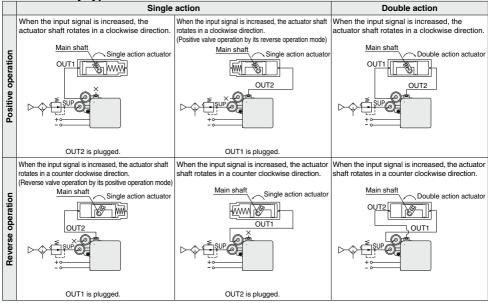


Piping Note) When the input signal is discontinued, the pressure of OUT1 decreases, and the pressure of OUT2 increases. Caution is also similarly required when changing the control direction in parameter mode.

IP8001/Lever type

	Single	action	Double action
	When the input signal is increased, the stem moves as allow mark.	When the input signal is increased, the stem moves as allow mark. (Positive valve operation by its reverse	When the input signal is increased, the cylinder rod moves as allow mark.
Positive operation	OUT1	operation mode)	OUT2 OUT2
	OUT2 is plugged.	OUT1 is plugged.	
	When the input signal is increased, the stem moves as allow mark. (Reverse valve operation by its positive	When the input signal is increased, the stem moves as allow mark.	When the input signal is increased, the cylinder rod moves as allow mark.
Reverse operation	operation mode) OUT2	OUT1	OUT2 OUT1 SUP
	OUT1 is plugged.	OUT2 is plugged.	

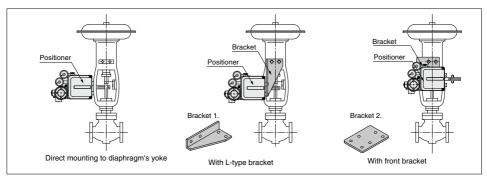
IP8101/Rotary type



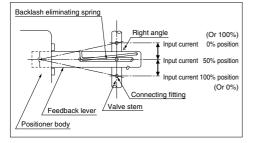
Installation

IP8000/8001 (Lever type)

1. Create brackets that are appropriate for the positioner and diaphragm valve mounting methods, and affix it firmly using the mounting hole on the side or rear surface.



2. The feedback lever that detects the displacement of valve stems should be mounted at a position so that the lever is at right angles to the valve stem for an input current of 50%. The figure is the configuration viewed from the front.



3. Brackets for lever type positioners, which are compliant with NAMUR and DIN/IEC 60534-6-1 are now available.

Part no.

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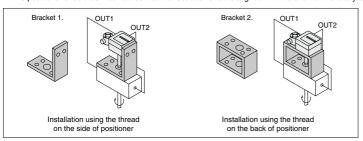
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Description

	·			
Bracket (NAMUR cor	Bracket (NAMUR compliant) single unit			
12	110			
8	55			
4	21.5 21.5	.9 .		
		24.5		
		~ ~		
4				
			1	
	80 0	5 5	135	
I ∥ .		2	ا ا	
I ∥ <u>+</u>			<u> </u>	
			+ +	
2 × 10	20	₂₀ සි	4	
'	20 70			
Bracket - (NAMUR compliant)	<u>-~+ - </u>	INI-2	224-0-56	
(

IP8100/8101 (Rotary type)

1. The positioner should be mounted so that the feedback shaft is aligned with the shaft of the rotary actuator.



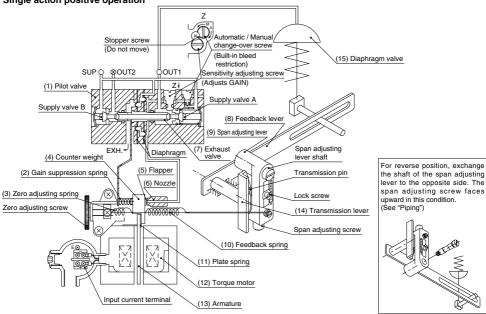


Principle of Operation

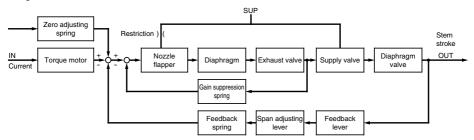
IP8000/Lever type

When the input current increases, (11) the plate spring of (12) the torque motor will work as a pivot, (13) armature will receive a counter clockwise torque, (4) the counter weight will be pushed to the left, the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases and (15) the diaphragm moves downwards. The motion of (15) the diaphragm acts on (10) the feedback spring through (8) the feedback lever, (14) the transmission lever and (9) the span adjustment lever to rest at the balance position generated by the input current. (2) The gain suppression spring is for direct feedback of the motion of (7) the exhaust valve to (4) the counter weight to increase the stability of the loop. The zero point should be adjusted by change of (3) the zero adjustment spring tension.

Single action positive operation

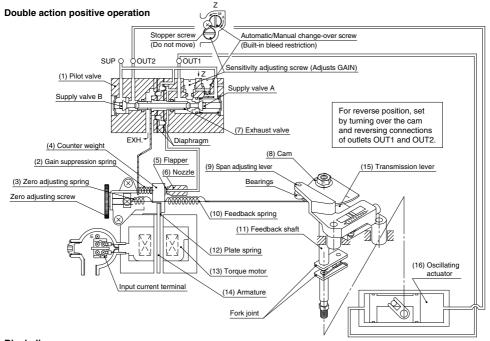


Block diagram

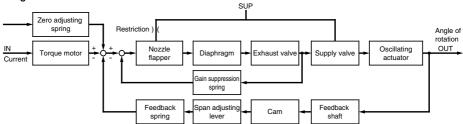


IP8100/Rotary type

When the input current increases, (12) the plate spring of (13) the torque motor will work as a pivot, (14) armature will receive a counter-clockwise torque, (4) the counter weight will be pushed to the left and the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases that of OUT2 decreases and (16) the rotary actuator moves. The motion of (16) the actuator acts on (10) the feedback spring through (11) the feedback shaft, (8) the cam, (9) the span adjustment lever and (15) transmission lever to rest at the balance position generated by the input current. (8) the cam is set on the DA surface and operates positively while (16) the oscillating actuator shaft rotates in a clockwise direction when the input signal is increased. (2) The gain suppression spring is for direct feedback of the motion of (7) the exhaust valve to (4) the counter weight to increase the stability of the loop. The zero point should be adjusted by change of (3) the zero adjustment spring tension.



Block diagram



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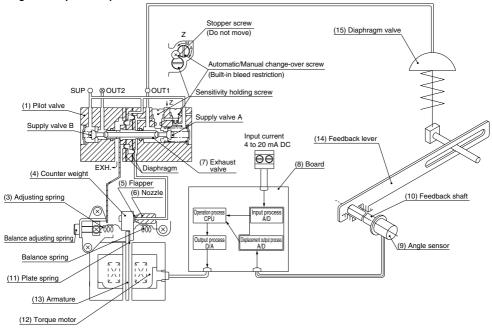


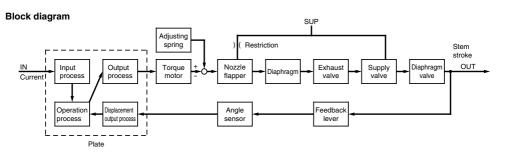
Principle of Operation

IP8001/Lever type

When the input current increases, the electrical current inside (12) the torque motor coil will change through (8) the plate's input process, operation process and output process, and (13) the armature will oscillate, with (11) the plate spring as its base. As a result, the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases and causes (15) the diaphragm valve to move. The motion of (15) the diaphragm valve is transmitted to the displacement output process of (8) the board through (14) the feedback lever, (10) the feedback shaft and (9) angle sensor, and the calculated output position will match the input current.

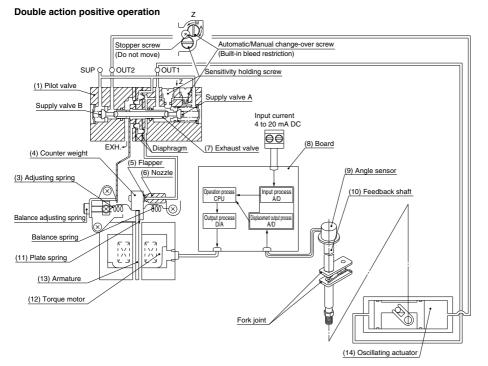
Single action positive operation

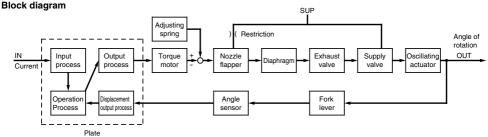




IP8101/Rotary type

When the input current increases, the electrical current inside (12) the torque motor coil will change through (8) the plate's input process, operation process and output process, and (13) the armature will oscillate, with (11) the plate spring as its base. As a result, the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases and causes the output pressure of OUT2 to decrease, causing (14) the oscillating actuator to move. The motion of (14) the oscillating actuator is transmitted to the fork lever-type fitting, (10) the feedback shaft (9) angle sensor, and the displacement output process of (8) the board, and output position will match the input current.





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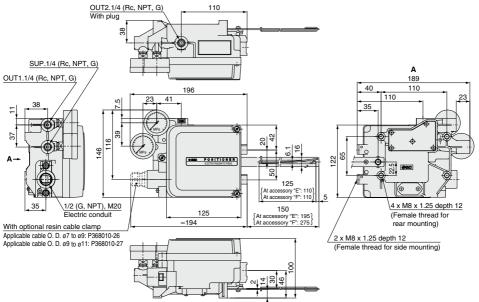
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VFN IN-T□

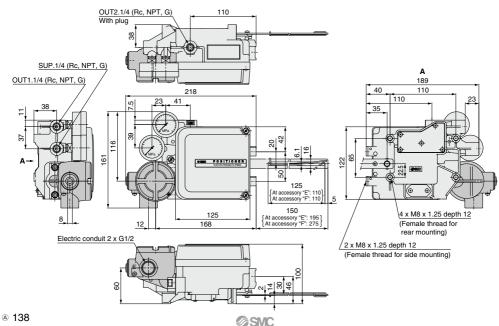
IP8□ Series

Dimensions/IP8000 (Lever type)

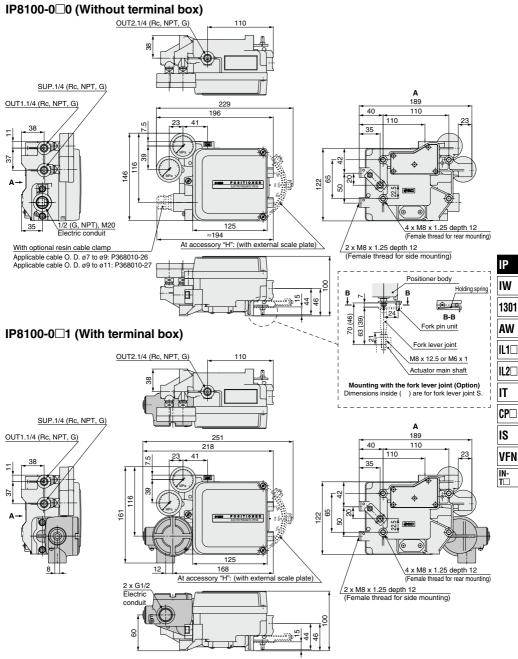
IP8000-0□0 (Without terminal box)



IP8000-0□1 (With terminal box)



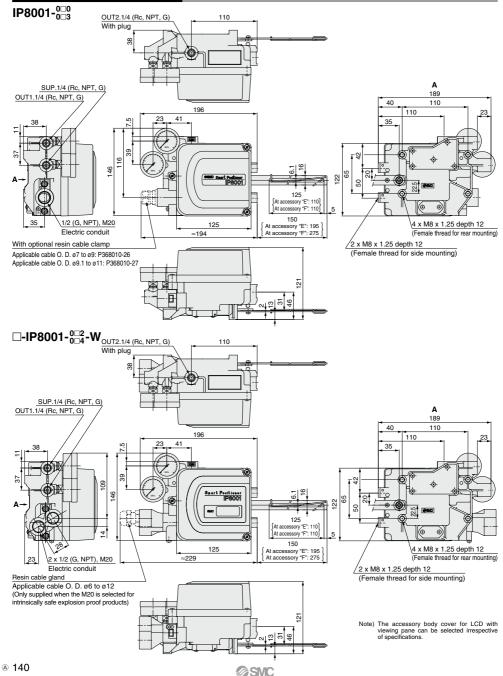
Dimensions/IP8100 (Rotary type)



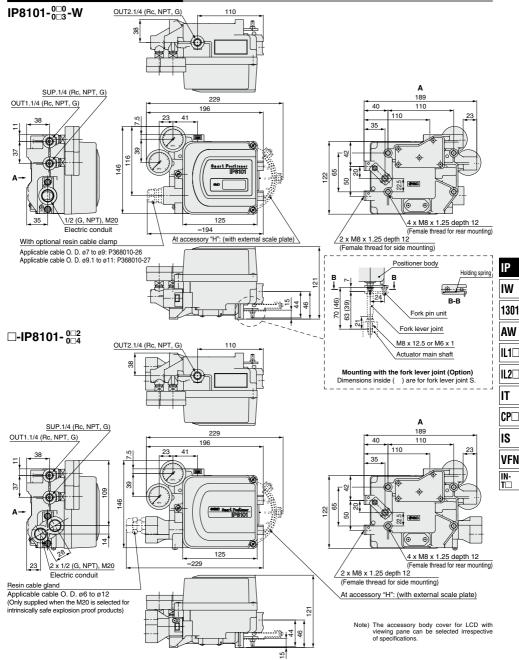
SMC

IP8□ Series

Dimensions/IP8001 (Lever type)



Dimensions/IP8101 (Rotary type)



SMC

Electro-Pneumatic Positioner (Lever type/Rotary type)

Made to Order

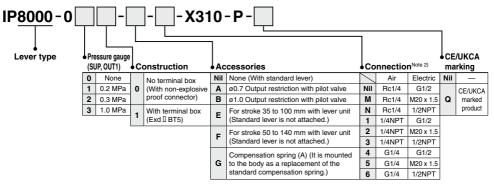
Please contact SMC for detailed dimensions, specifications and lead times.

Water Resistant Type

1 Exterior Covering Enclosure: JISF8007 IP66 (Conforms to IEC60529)

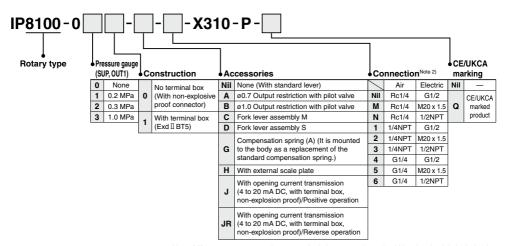
* Same as the standard, other than the IP66 compliant protective cover.

How to Order IP8000/Lever type



Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. Note 2) If 1 is selected for Construction, M, N, 2, 3, 5, 6 cannot be selected for Connection.

IP8100/Rotary type



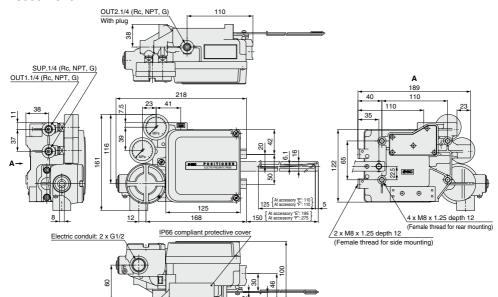
Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order.

Note 2) Symbol J/JR is with terminal box, non-explosion proof specification. Select 1 for Construction.

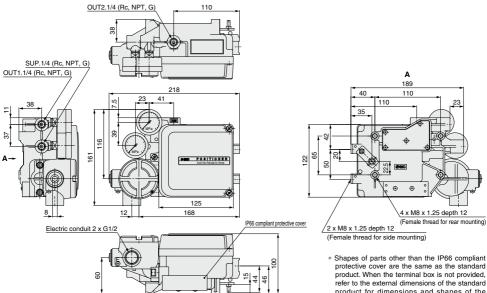
Note 3) If 1 is selected for Construction, M, N, 2, 3, 5, 6 cannot be selected for Connection.

Dimensions

P8000-X310-P



IP8100-X310-P



SMC

* Shapes of parts other than the IP66 compliant protective cover are the same as the standard product. When the terminal box is not provided, refer to the external dimensions of the standard product for dimensions and shapes of the electric wiring parts.

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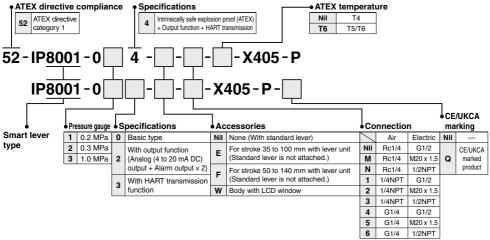


Water Resistant Type

2 Exterior Covering Enclosure: JISF8007 IP66 (Conforms to IEC60529)

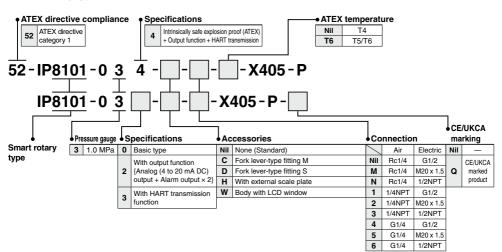
* Same as the standard, other than the IP66 compliant protective cover.

How to Order IP8001/Lever type



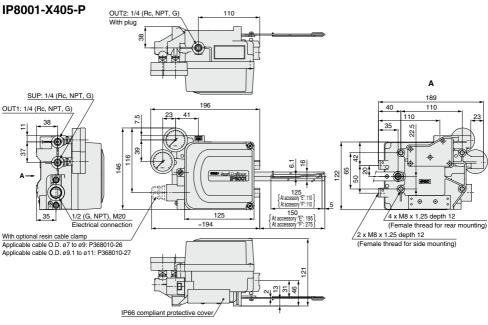
Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. Note 2) If a connecting port is $M20 \times 1.5$, a blue cable gland is included.

IP8101/Rotary type

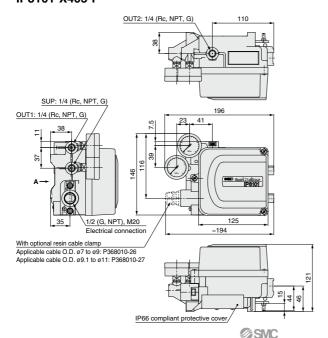


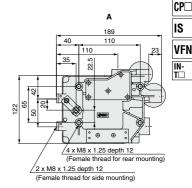
Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. Note 2) If a connecting port is $M20 \times 1.5$, a blue cable gland is included.

Dimensions



IP8101-X405-P





Shapes of parts other than the IP66 compliant protective cover are the same as the standard product. When the terminal box is not provided, refer to the external dimensions of the standard product for dimensions and shapes of the electric wiring parts. 1301

AW

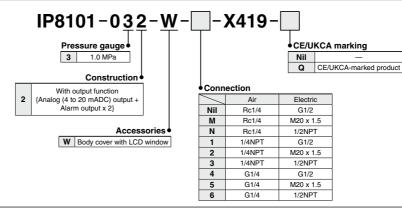
lIL1□

IL2□ IT



3 External Input Signal (Remote) Type

How to Order



Positioner Specifications

Specifications

Input current	4 to 20 mADC*1 (2-line, Separate power source unnecessary)
Input feedback signal	4 ±1 to 20 ±1 mADC
Piping length	10 m or less
Tubing size	O.D.: 8 mm, I.D.: 5 mm
Min. operating current	3.85 mADC or more
Voltage between terminals	12 VDC (Equivalent to 600 Ω input resistance, at 20 mADC)
Max. supply power	1 W*2 (Imax: 100 mADC, Vmax: 28 VDC)
Supply air pressure	0.3 to 0.7 MPa
Sensitivity	Within ±0.2% F.S.*3
Linearity*3	Within ±1% F.S. (Noise interference-free environment) Within ±8% F.S. (For "-Q"/use in an environment with noise interference)
Hysteresis	Within 0.5% F.S.*3
Repeatability	Within ±0.5% F.S.*3
Temperature coefficient	Within 0.05% F.S./°C*3
Max. output flow	200 L/min (ANR) or more (SUP = 0.4 MPa)*4
Air consumption	Within 11 L/min (ANR) (SUP = 0.4 MPa)*4
Ambient and fluid temperatures	-20°C to 80°C (Non-explosion proof)*5, *6
Enclosure	JIS F 8007 IP65 (Compliant with IEC 60529)
Air connection port*7	1/4 (Rc, NPT, G) female thread
Electrical connection port*7	1/2 (G, NPT) female thread, M20 x 1.5 female thread
Material	Body/Cover: Aluminum diecast (Coating: Baking finish with epoxy resin)
iviater iai	Thread: Stainless steel
Weight	Approx. 2.6 kg

- *1 A 1/2 split range can be selected using the split range setting (Parameter code: 300).
 *2 <Example> If an input current of 80 mADC is input by mistake, damage will not occur as long as the input power supply voltage is below 12.5 VDC. Max. supply power = 80 mADC x 12.5 V = 1W

*3 The linearity value was confirmed with no load using an SMC inspection device (the device with a built-in sensor shown in the table below). The positioner cannot be used independently; it is meant for use as a part of a loop which includes actuating equipment such as valves, actuators, distributed control systems, etc. Therefore, the values in the table may vary depending on the loop conditions. The temperature coefficient of the external sensor is not included in the temperature coefficient

The linearity value of ±8% F.S. or less is based on measurement during EMC-testing under certain electrical noise conditions.

- When using in an environment where noise interference is present, we recommend the "-Q" option, not the CE/UKCA-compliant option "Nil."
- *4 (ANR) indicates JIS B 0120 standard air.
- *5 The LCD display may be difficult to see at low temperatures, but this does not affect positioner operation.
- *6 Be aware that temperature fluctuations may affect the voltage between terminals.
- *7 The connection port type can be selected during model selection.

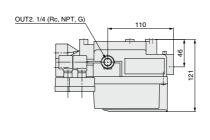
External Sensor Specifications (Reference)

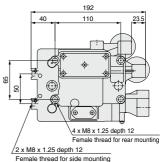
Linearity	±0.05% F.S. or less	
Resolution	0.01% F.S. or less	
Repeatability	±0.01% F.S. or less	
Output signal	4 ±1 to 20 ±1 mADC	

^{*} Be sure to ground the product to prevent malfunction caused by noise or damage caused by static electricity.

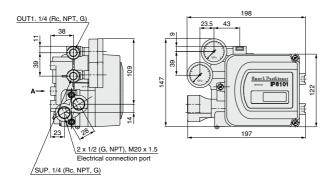
Dimensions [mm]

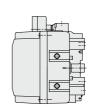
IP8101-032-W-□-X419-□





View A





IP IW

1301

AW IL1□

IL2□ IT

CP IS

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Technical data

Explosion proof

1. TIIS explosion-proof construction

The electro-pneumatic positioner IP8000/8100 becomes explosion proof, as certified by TIIS, according to the model selected. The explosion-proof grade has the following approval: Exd $\, \mathbb{I} \,$ BT5.

Take extra care when handling the positioner as explosion-proof equipment

To use as Exd II BT5

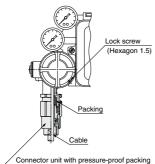
A) Pressure-proof packing

As shown below in the chart, use "Cable gland" (Option).

B) Metal piping

Attach the sealant fitting bracket near the cable port.

(For details, refer to "The guideline on electric equipment explosion proof" published by the Technology Institution of Industrial Safety).



Cable gland with pressure proof packing (Option)

Description	Unit product no.	Applicable outside diameter
Connector unit with	P368010-32	ø7.0 to ø10.0
pressure proof packing	P368010-33	ø10.1 to ø12.0

2. ATEX Intrinsically safe explosion-proof construction

Pneumatic positioners IP8000/8100 and IP8001/8101 Smart Positioners are ATEX compliant, intrinsically safe and explosion proof, as certified by DEKRA, the accreditation body for explosion-proof products. Take extra care when handling these explosion-proof products.

In regards to explosion-proof grades,

The Smart Positioner IP8□01 meets the II 1G Ex h ia IICT4/T5/T6 Ga. Check the positioner's specifications and explosion-proof grades and use in the most optimal environment.

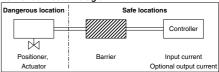
Wiring

When using the positioner as an intrinsically safe explosion-proof product, always set up a barrier in a <u>safe environment</u>, and perform each positioner's wiring through the barrier. Simultaneously, use the provided cable gland (M20 x 1.5) as the extension for the lead wire. If a connecting port other than M20 x 1.5 is selected, the cable gland will not be provided, so use a cable gland with the same or greater explosion-proof grades than this positioner.

Barrier

Connect the barrier as shown in the diagram below. Moreover, the user must select a barrier that is suitable for each function, based on the ATEX intrinsically safe explosionproof parameters (current circuit). For IP8001/8101 type smart positioners, use a linear resistant type barrier that is based on the explosion-proof parameters.

Barrier connection diagram



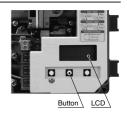
Moreover, at SMC, the barriers listed in the chart below are used to check operations. To purchase, please contact PEPPER + FUCHS Inc. (Germany).

Recommended barriers

	Manu-	anu- Model	Note	Applicable model	
	facturer	Model	Note	IP8□00-X14	52-IP8□01
For input signal (non HART transmission)	DEDDEDI	KFD2-CD-Ex1.32	_	0	0
For input signal (for HART transmission)		KFD2-SCD-Ex1.LK KCD2-SCD-Ex1	_	_	0
For analog output	+	KFD2-STC4-Ex1	_	_	0
	FUCHS (Germany)	KFD2-SOT2-Ex2	Transistor Output passive type	_	0
For alarm output		KFD2-ST2-Ex2	Transistor Output passive type	_	0
		KFD2-SR2-Ex2.W	Relay output	_	0

HART transmission

With smart positioners IP8001/8101, the user can operate the positioner using buttons and change parameter settings by viewing the LCD display (shown the right). Furthermore, depending on the model selected, the same button operation and parameter settings, and monitoring is possible from a remote location via HART transmission.



The table below lists an example of applications that are compatible with smart positioner IP8001/8101. Application selection must be made by the user. Please contact Emerson Process Management for further details.

HART transmission compatible application

Product name Note)	Manufacturer
AMS™ Suite : Intelligent Device Manager ®	Emerson Process
375/475 Field Communicator	Management (US)

Note) AMS™ Suite: Intelligent Device Manager® is a registered trademark of Emerson Flectric Co.

