

Step Motor Driver LECPA Series





How to Order

∧ Caution

[CE-compliant products]

- ① EMC compliance was tested by combining the electric actuator LE series and the LECPA series. The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, compliance with the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify compliance with the EMC directive for the machinery and equipment as a whole.
- ② For the LECPA series (step motor driver), EMC compliance was tested by installing a noise filter set (LEC-NFA).
 - Refer to page 736 for the noise filter set. Refer to the LECPA Operation Manual for installation.

[UL-compliant products]

When compliance with UL is required, the electric actuator and driver should be used with a UL1310 Class 2 power supply.

LECP AN 1 - LEFS16B-100

Driver type

AN	Pulse input type (NPN)
AP	Pulse input type (PNP)

I/O cable length [m]

Nil	None
1	1.5
3	3*1
5	5* ¹

*1 Pulse input usable only with differential. Only 1.5 m cables usable with open collector.

Oriver mounting

Driver mounting									
Nil	Screw mounting								
D *1	DIN rail								

*1 The DIN rail is not included. It must be ordered separately.

Actuator part number

Without cable specifications and actuator options Example: Enter "LEFS16B-100"

for the LEFS16B-100B-R1AN1D.

BC Blank controller*1

*1 Requires dedicated software (LEC-BCW)

- $* \ \ When \ controller \ equipped \ type \ is \ selected \ when \ ordering \ the \ LE \ series, \ you \ do \ not \ need \ to \ order \ this \ driver.$
- * When pulse signals are open collector, order the current limiting resistor (LEC-PA-R-□) separately.

The driver is sold as single unit after the compatible actuator is set.

Confirm that the combination of the driver and actuator is correct.

<Check the following before use.>

- ① Check the actuator label for the model number. This number should match that of the driver.
- ② Check that the Parallel I/O configuration matches (NPN or PNP).
- LEFS16B-100
 NP).
- Refer to the operation manual for using the products. Please download it via our website: https://www.smcworld.com

Precautions for blank controllers (LECPA□□-BC)

A blank controller is a controller to which the customer can write the data of the actuator it is to be combined and used with. Use the dedicated software (LEC-BCW) for data writing.

- Please download the dedicated software (LEC-BCW) via our website.
- Order the communication cable for controller setting (LEC-W2A-C) separately to use this software.

SMC website: https://www.smcworld.com

Specifications

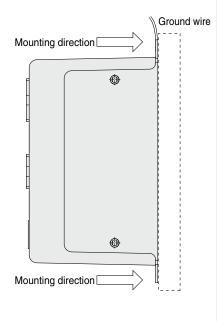
Item	LECPA			
Compatible motor	Step motor (Servo/24 VDC)			
Dawar aventu*1	Power voltage: 24 VDC ±10%*2			
Power supply*1	[Including motor drive power, control power, stop, lock release]			
Parallel input	5 inputs (Except photo-coupler isolation, pulse input terminal, COM terminal)			
Parallel output	9 outputs (Photo-coupler isolation)			
Dulce signal input	Maximum frequency: 60 kpps (Open collector), 200 kpps (Differential)			
Pulse signal input	Input method: 1 pulse mode (Pulse input in direction), 2 pulse mode (Pulse input in differing directions)			
Compatible encoder Incremental A/B phase (Encoder resolution: 800 pulse/rotation)				
Serial communication	RS485 (Modbus protocol compliant)			
Memory	EEPROM			
LED indicator	LED (Green/Red) one of each			
Lock control	Forced-lock release terminal*3			
Cable length [m]	I/O cable: 1.5 or less (Open collector), 5 or less (Differential), Actuator cable: 20 or less			
Cooling system	Natural air cooling			
Operating temperature range [°C]	0 to 40 (No freezing)			
Operating humidity range [%RH]	90 or less (No condensation)			
Storage temperature range [°C]	-10 to 60 (No freezing)			
Storage humidity range [%RH]	90 or less (No condensation)			
Insulation resistance [MΩ]	Between the housing and SG terminal: 50 (500 VDC)			
Weight [g]	120 (Screw mounting), 140 (DIN rail mounting)			

- *1 Do not use the power supply of "inrush current prevention type" for the driver power supply. When compliance with UL is required, the electric actuator and driver should be used with a UL1310 Class 2 power supply.
- *2 The power consumption changes depending on the actuator model. Refer to the specifications of actuator for more details.
- *3 Applicable to non-magnetizing locks

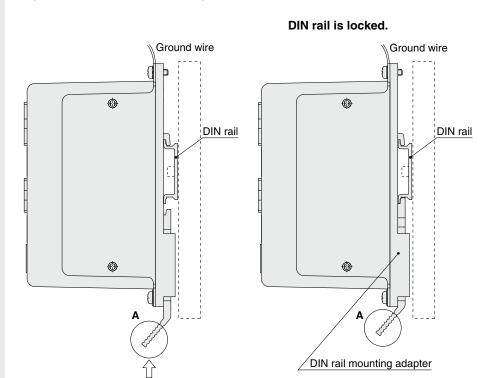


Step Motor Driver LECPA Series

How to Mount



b) DIN rail mounting (LECPA D- (Installation with the DIN rail)

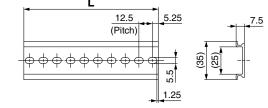


Hook the driver on the DIN rail and press the lever of section ${\bf A}$ in the arrow direction to lock it.

 $\ast\,$ The space between the drivers should be 10 mm or more.

DIN rail AXT100-DR-□

* For □, enter a number from the No. line in the table below. Refer to the dimension drawings on page 733 for the mounting dimensions.



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No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
L	23	35.5	48	60.5	73	85.5	98	110.5	123	135.5	148	160.5	173	185.5	198	210.5	223	235.5	248	260.5
No.	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
L	273	285.5	298	310.5	323	335.5	348	360.5	373	385.5	398	410.5	423	435.5	448	460.5	473	485.5	498	510.5

DIN rail mounting adapter

LEC-2-D0 (with 2 mounting screws)

This should be used when the DIN rail mounting adapter is mounted onto a screw mounting type driver afterward.

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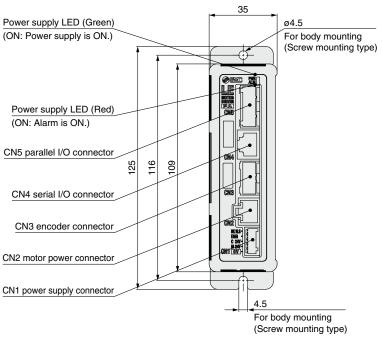
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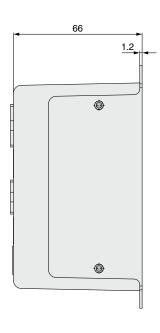
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LECPA Series

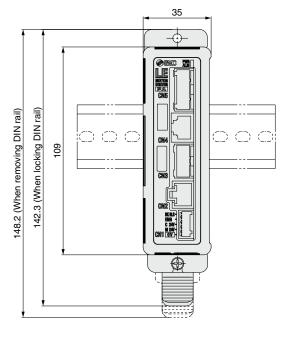
Dimensions

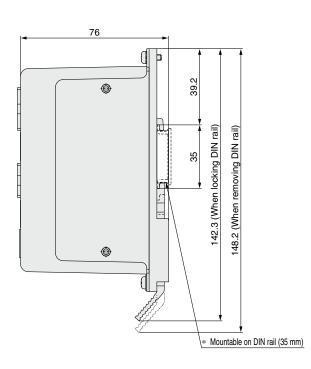
a) Screw mounting (LECPA□□-□)





b) DIN rail mounting (LECPA□□D-□)





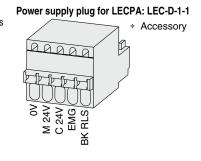
Wiring Example 1

Power Supply Connector: CN1 * The power supply plug is an accessory.

Applicable cable size> AWG20 (0.5 mm²), cover diameter 2.0 mm or less

CN1 Power Supply Connector Terminal for LECPA (PHOENIX CONTACT FK-MC0.5/5-ST-2.5)

Terminal name	Function	Details
0V	Common supply (-)	The M 24V terminal, C 24V terminal, EMG terminal, and BK RLS terminal are common (-).
M 24V	Motor power supply (+)	Motor power supply (+) supplied to the driver
C 24V	Control power supply (+)	Control power supply (+) supplied to the driver
EMG	Stop (+)	Input (+) for releasing the stop
BK RLS	Lock release (+)	Input (+) for releasing the lock





Wiring Example 2

Parallel I/O Connector: CN5 * When you connect a PLC to the CN5 parallel I/O connector, use the I/O cable (LEC-CL5-□).

* The wiring changes depending on the type of parallel I/O (NPN or PNP).

LECPAN□□-□ (NPN)

	CN5		Power supply 24 VDC +10%
Terminal name	Function	Pin no.	for I/O signal
COM+	24 V	1	
COM-	0 V	2	
NP+	Pulse signal	3	
NP-	Pulse signal	4	
PP+	Pulse signal	5	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
PP-	Pulse signal	6	
SETUP	Input	7	
RESET	Input	8	
SVON	Input	9	
CLR	Input	10	
TL	Input	11	
TLOUT	Output	12	Load
WAREA	Output	13	Load
BUSY	Output	14	Load
SETON	Output	15	Load
INP	Output	16	Load
SVRE	Output	17	Load
*ESTOP*2	Output	18	Load
*ALARM*2	Output	19	Load
AREA	Output	20	Load
	FG	Round terminal 0.5-5	

- st 1 For pulse signal wiring method, refer to the "Pulse Signal Wiring Details."
- *2 Output when the power supply of the driver is ON. (N.C.)

Input Signal

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Details
Connects the power supply 24 V for input/output signal
Connects the power supply 0 V for input/output signal
Instruction to return to origin
Alarm reset
Servo ON instruction
Deviation reset
Instruction to pushing operation

LECPAP□□-□ (PNP)

	CN5							Power supp
Terminal name	Function	Pin no.	7-5		,			for I/O sign
COM+	24 V	1						→ ⊢
COM-	0 V	2		+				\rightarrow
NP+	Pulse signal	3			-)		
NP-	Pulse signal	4	- 11.					
PP+	Pulse signal	5		<u> </u>	-	· *1		
PP-	Pulse signal	6	- 11.)		
SETUP	Input	7		\leftarrow				→
RESET	Input	8		.	:			→
SVON	Input	9	- 11					→
CLR	Input	10		.	-			→
TL	Input	11			-			_
TLOUT	Output	12	Н.				Load	
WAREA	Output	13		\leftarrow			Load	
BUSY	Output	14	- 1 1 .	.			Load	
SETON	Output	15					Load	
INP	Output	16) +	-		Load	
SVRE	Output	17					Load	
*ESTOP*2	Output	18	 	.	-		Load	
*ALARM*2	Output	19					Load -	
AREA	Output	20		 			Load	
	FG	Round terminal 0.5-5	J					

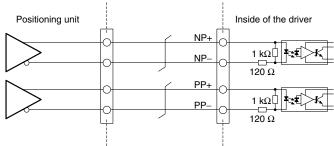
Output Signal

Name	Details
BUSY	Outputs when the actuator is moving
SETON	Outputs when returning to origin
INP	Outputs when target position is reached
SVRE	Outputs when servo is ON
*ESTOP*3	OFF when EMG stop is instructed
*ALARM*3	OFF when alarm is generated
AREA	Outputs within the area output setting range
WAREA	Outputs within W-AREA output setting range
TLOUT	Outputs during pushing operation
.O. Nasiativa la	nia (N.C.) aivavit airmal

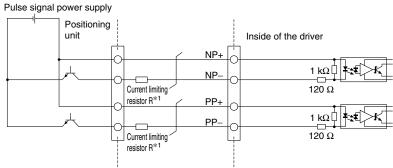
^{*3} Negative-logic (N.C.) circuit signal

Pulse Signal Wiring Details

• Pulse signal output of positioning unit is differential output



• Pulse signal output of positioning unit is open collector output



*1 Connect the current limiting resistor R in series to correspond to the pulse signal voltage.

Pulse signal	Current limiting resistor R	Current limiting resistor	
power supply voltage	specifications	part no.	
24 VDC ±10%	3.3 kΩ ±5% (0.5 W or more)	LEC-PA-R-332	
5 VDC ±5%	390 Ω ±5% (0.1 W or more)	LEC-PA-R-391	



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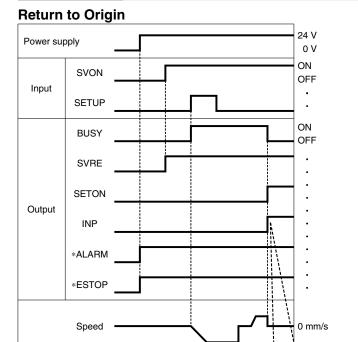
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LECPA Series

Signal Timing

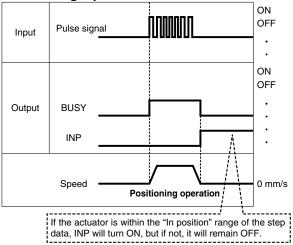


If the actuator is within the "In position" range of the basic parameter, INP will turn ON, but if not, it will remain OFF.

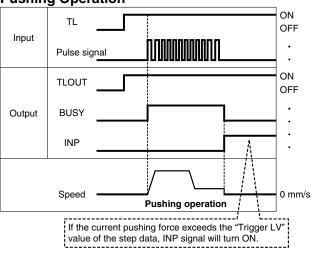
Return to origin

* "*ALARM" and "*ESTOP" are expressed as negative-logic circuits.

Positioning Operation

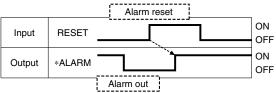


Pushing Operation



* If pushing operation is stopped when there is no pulse deviation, the moving part of the actuator may pulsate.

Alarm Reset

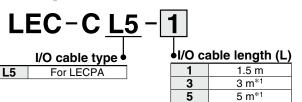


* "*ALARM" is expressed as a negative-logic circuit.

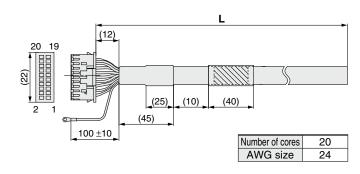


Options

[I/O cable]



*1 Pulse input usable only with differential. Only 1.5 m cables usable with open collector



Insulation	Dot	Dot
color	mark	color
Light brown		Black
Light brown		Red
Yellow		Black
Yellow		Red
Light green		Black
Light green		Red
Gray		Black
Gray		Red
White		Black
White		Red
Light brown		Black
	Light brown Light brown Yellow Yellow Light green Light green Gray Gray White White	Light brown Light brown Yellow Yellow Light green Light green Gray Gray White White

Pin	Insulation	Dot	Dot
no.	color	mark	color
12	Light brown		Red
13	Yellow		Black
14	Yellow		Red
15	Light green		Black
16	Light green		Red
17	Gray		Black
18	Gray		Red
19	White		Black
20	White		Red
Round terminal 0.5-5	Green		

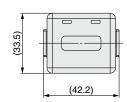
Weight

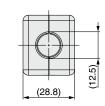
Product no.	Weight [g]
LEC-CL5-1	190
LEC-CL5-3	370
LEC-CL5-5	610

[Noise filter set]
Step Motor Driver (Pulse Input Type)

LEC-NFA

Contents of the set: 2 noise filters
(Manufactured by WURTH ELEKTRONIK: 74271222)





 $\ast\,$ Refer to the LECPA series Operation Manual for installation.

[Current limiting resistor]

This optional resistor (LEC-PA-R- \square) is used when the pulse signal output of the positioning unit is open collector output.

LEC-PA-R-

Current limiting resistor

Symbol	Resistance	Pulse signal power supply voltage
332	3.3 kΩ ±5%	24 VDC ±10%
391	390 Ω ±5%	5 VDC ±5%

- Select a current limiting resistor that corresponds to the pulse signal power supply voltage.
- * For the LEC-PA-R-□, two pieces are shipped as a set.
- For pulse signal wiring details, refer to page 734.

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