Electro-Pneumatic Transducer Series IT600

- The air pressure in proportion to the current signal can be output. Can be used as input pressure signal in combination with the pneumatic-pneumatic positioner.
- Wide output pressure range/0.02 to 0.6 MPa The maximum pressure can be set freely through the span adjustment.

Fast response

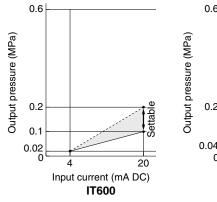
The pilot valve capacity is large and the large flow can be obtained. Therefore, the response is excellent when operating the actuator directly or controlling the inner pressure of the tank with a large capacity.

 Independent electric unit/Explosion-proof (flameproof) construction The span adjustment, zero-point adjustment, and inspection maintenance can be performed with the body cover removed even in a hazardous place where the explosion or fire may occur.

• Easy span adjustment

As the span adjustment mechanism uses a vector mechanism, the span adjustment can be performed smoothly.

Output pressure setting range



20 Input current (mA DC) IT601

0.6

0.2

0

Positioners

Regulators

Relays/Valves

Electro-Pneumatic

Fransducers

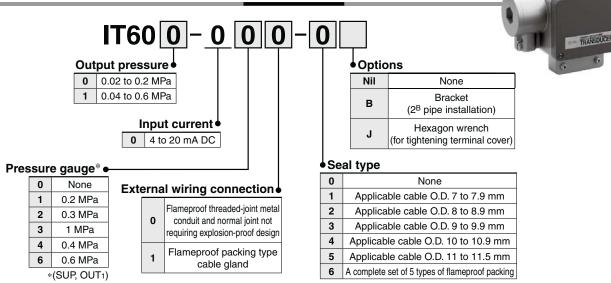
Actuators

Conversion Unit

Solenoid Valves

Detection

Settable



GSMC

How to Order

Specifications

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Model	IT600	IT601	
Item	Low pressure	High pressure	
Input current	4 to 20 mA DC		
Input impedance	235 Ω (4 to 20 mA, 20°C)		
Supply air pressure	0.14 to 0.24 MPa	0.24 to 0.7 MPa	
Output pressure	0.02 to 0.1 MPa (Max. 0.2 MPa)	0.04 to 0.2 MPa (Max. 0.6 MPa)	
Linearity	Within ±1.0% F.S.		
Hysteresis	Within 0.75% F.S.		
Repeatability	Within ±0.5% F.S.		
Air consumption	7 L/min (ANR) (SUP = 0.14 MPa)	22 L/min (ANR) (SUP = 0.7 MPa)	
Ambient and fluid temperature	-10 to 60°C		
Air connection port	Rc1/4 female thread		
Electrical connection	Rc1/2 female thread		
Explosion-proof construction	Explosion-proof (flameproof) construction d2G4 (Certificate no. T28926)		
Material	Aluminum die-cast body		
Weight	3 kg		

Replacement Parts			
Part no.	Description	Note	
P255010-1	Pilot valve unit	IT600	
P255010-19	Pilot valve unit	IT601	

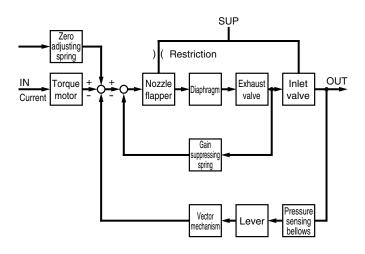
Series IT600

Principle of Operation

When the input current increases, armature ① in the torque motor will be subjected to a clockwise torque, pushing flapper lever ② to the left. As a result, the clearance of nozzle flapper ③ will increase and the nozzle back pressure will decrease. This moves exhaust valve ⑩ of pilot valve ⑤ to the left, causing the output air pressure of OUT1 to increase.

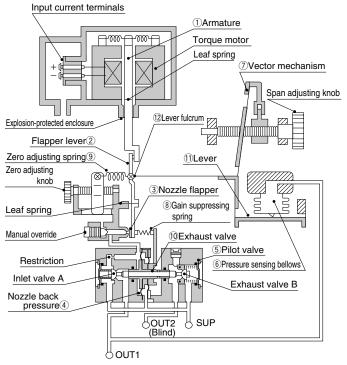
The output pressure thus increased is passed through the path inside the pilot valve to pressure sensing bellows (6), where it is converted to the force. This force acts on vector mechanism (7) via lever (1). Because the force will balance the force

Block diagram illustrating operating principle

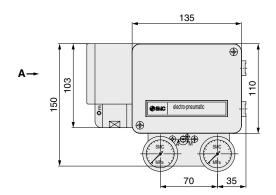


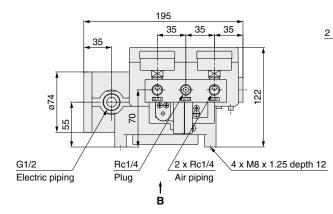
generated by means of the input current at lever fulcrum (2), the output air pressure proportional to the input current will be obtained.

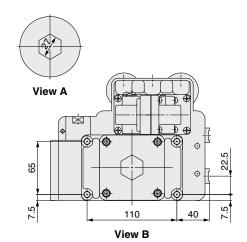
Gain suppression spring (8) functions to immediately feedback the movement of the exhaust valve to the flapper lever, thereby contributing to loop stability. Zero point and span adjustments are performed by varying the tension force of zero adjusting spring (9) and the angle of the vector mechanism, respectively.

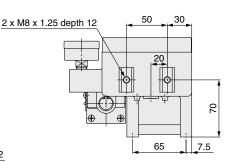


Dimensions









SMC