

Wide Type Parallel Style Air Gripper

MHL2 Series

ø10, ø16, ø20, ø25, ø32, ø40



How to Order

MHL 2 - 16 □ D □ Z - M9BW □ - □

Wide type

Number of fingers

2	2
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Bore size

10	10 mm
16	16 mm
20	20 mm
25	25 mm
32	32 mm
40	40 mm

Port thread type

Symbol	Type	Cylinder bore
Nil	M thread	ø10 to ø25
	Rc	ø32 to ø40
TN	NPT	
TF	G	

Action

D	Double acting
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Made to order
Refer to page 4 for details.

Number of auto switches

Nil	2
S	1
n	n

Auto switch

Nil	Without auto switch (Built-in magnet)
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* For applicable auto switches, refer to the table below.

Opening/Closing stroke [mm]

	Symbol	ø10	ø16	ø20	ø25	ø32	ø40
Short: MHL2-□D	Nil	20	30	40	50	70	100
Medium: MHL2-□D1	1	40	60	80	100	120	160
Long: MHL2-□D2	2	60	80	100	120	160	200

Applicable Auto Switches/Refer to the Web Catalog or Best Pneumatics for further information on auto switches.

Type	Special function	Electrical entry	Indicator/light	Wiring (Output)	Load voltage		Auto switch model		Lead wire length [m] ^{*1}				Pre-wired connector	Applicable load		
					DC	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5 (Z)		IC circuit	Relay, PLC	
Solid state auto switch	Diagnostic indication (2-color indicator)	Grommet	Yes	3-wire (NPN)	24 V	5 V, 12 V	—	M9NV	M9N	●	●	●	○	○	IC circuit	Relay, PLC
				3-wire (PNP)				M9PV	M9P	●	●	●	○	○		
				2-wire				M9BV	M9B	●	●	●	○	○		
				3-wire (NPN)				M9NWV	M9NW	●	●	●	○	○		
				3-wire (PNP)				M9PWV	M9PW	●	●	●	○	○		
				2-wire				M9B WV	M9B W	●	●	●	○	○		
	Water resistant (2-color indicator)	Grommet	No	3-wire (NPN)	24 V	5 V, 12 V	—	M9NAV ^{*2}	M9NA ^{*2}	○	○	●	○	○	IC circuit	Relay, PLC
				3-wire (PNP)				M9PAV ^{*2}	M9PA ^{*2}	○	○	●	○	○		
				2-wire				M9BAV ^{*2}	M9BA ^{*2}	○	○	●	○	○		
				2-wire				M9BAV ^{*2}	M9BA ^{*2}	○	○	●	○	○		

*1 Lead wire length symbols: 0.5 m..... Nil (Example) M9NW
 1 m..... M (Example) M9NWM
 3 m..... L (Example) M9NWL
 5 m..... Z (Example) M9NWZ

*2 Water resistant type auto switches can be mounted on the above models, but SMC cannot guarantee water resistance.

* Solid state auto switches marked with "○" are produced upon receipt of order.

* When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the air gripper.

Long stroke

One unit can handle workpieces with various diameters.

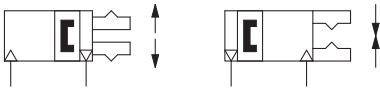
A large amount of gripping force is provided, through the use of a double piston mechanism, while maintaining a compact design.

Double-end type oil-impregnated resin bearings are used for all shafts.



Symbol

Double acting: Internal grip Double acting: External grip



Made to Order
(For details, refer to pages 17 to 24.)

Symbol	Specifications
-X4	Heat resistant (-10 to 100°C)
-X5	Fluororubber seal
-X28	With bolt for adjusting the closing width
-X50	Without magnet
-X53	Ethylene propylene rubber seal (EPDM)
-X63	Fluorine grease
-X79	Grease for food processing machines: Fluorine grease
-X79A	Grease for food processing machines: Aluminum complex soap base grease
-X85	Fine-particle proof specification
-X86	With heavy duty scraper + Stable lubrication function (Lube-retainer) (Seal material: NBR, Fluororubber)

Refer to pages 14 and 15 for cylinders with auto switches.

- Auto Switch Installation Examples and Mounting Positions
- Auto Switch Hysteresis

Specifications

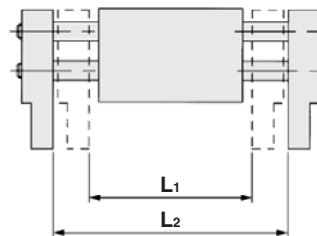
Bore size [mm]	10	16	20	25	32	40
Fluid	Air					
Action	Double acting					
Operating pressure [MPa]	0.15 to 0.6		0.1 to 0.6			
Ambient and fluid temperatures	-10 to 60°C (No freezing)					
Repeatability	±0.1					
Lubricant	Non-lube					
Effective gripping force [N]*1 at 0.5 MPa	14	45	74	131	228	396

*1 Gripping point distance = Bore size 10, 16, 20, 25: 40 mm, Bore size 32, 40: 80 mm

Model/Stroke

Model	Bore size [mm]	Max. operating frequency [c.p.m]	Opening/Closing stroke [mm] (L2-L1)	Closing width [mm] (L1)	Opening width [mm] (L2)	Weight [g]
MHL2-10DZ	10	60	20	56	76	280
MHL2-10D1Z		40	40	78	118	355
MHL2-10D2Z			60	96	156	430
MHL2-16DZ	16	60	30	68	98	525
MHL2-16D1Z		40	60	110	170	725
MHL2-16D2Z			80	130	210	845
MHL2-20DZ	20	60	40	82	122	940
MHL2-20D1Z		40	80	142	222	1335
MHL2-20D2Z			100	162	262	1520
MHL2-25DZ	25	60	50	100	150	1565
MHL2-25D1Z		40	100	182	282	2295
MHL2-25D2Z			120	200	320	2525
MHL2-32DZ	32	30	70	150	220	2875
MHL2-32D1Z		20	120	198	318	3770
MHL2-32D2Z			160	242	402	4585
MHL2-40DZ	40	30	100	188	288	5230
MHL2-40D1Z		20	160	246	406	6760
MHL2-40D2Z			200	286	486	7825

* The opening and closing widths represent the value when gripping the exterior of a workpiece.



⚠ Specific Product Precautions

Be sure to read this before handling the products. Refer to page 25 for details.

MHL2 Series

Model Selection

Step 1 Check the gripping force.

Step 2 Check the gripping point.

Step 1 Check the gripping force.

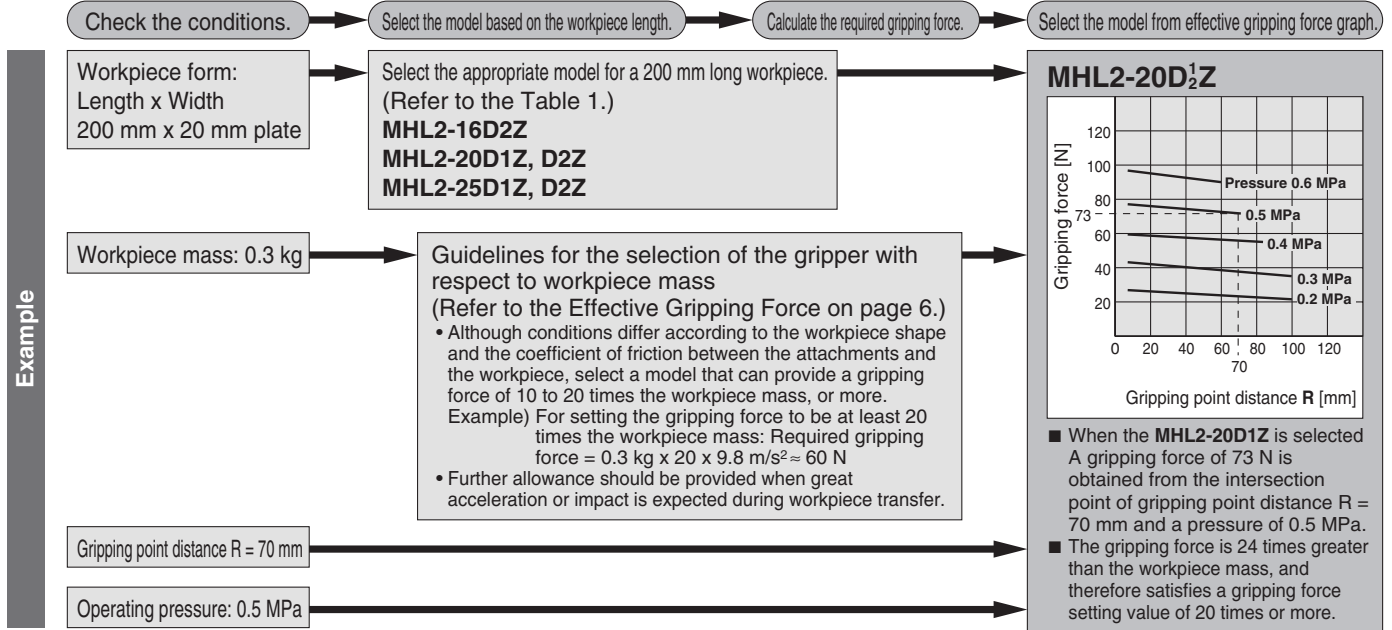
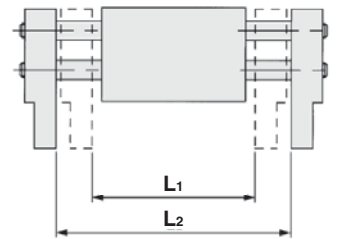


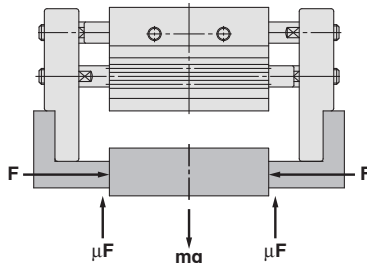
Table 1

Model	Bore size [mm]	Closing width [mm] (L1)	Opening width [mm] (L2)	Model	Bore size [mm]	Closing width [mm] (L1)	Opening width [mm] (L2)
MHL2-10DZ	10	56	76	MHL2-25DZ	25	100	150
MHL2-10D1Z		78	118	MHL2-25D1Z		182	282
MHL2-10D2Z		96	156	MHL2-25D2Z		200	320
MHL2-16DZ	16	68	98	MHL2-32DZ	32	150	220
MHL2-16D1Z		110	170	MHL2-32D1Z		198	318
MHL2-16D2Z		130	210	MHL2-32D2Z		242	402
MHL2-20DZ	20	82	122	MHL2-40DZ	40	188	288
MHL2-20D1Z		142	222	MHL2-40D1Z		246	406
MHL2-20D2Z		162	262	MHL2-40D2Z		286	486



* The opening and closing widths represent the value when gripping the exterior of a workpiece.

Calculation of Required Gripping Force



“Gripping force at least 10 to 20 times the workpiece weight”

• The “10 to 20 times or more of the workpiece weight” recommended by SMC is calculated with a margin of “a” = 4, which allows for impacts that occur during normal transportation, etc.

When $\mu = 0.2$	When $\mu = 0.1$
$F = \frac{mg}{2 \times 0.2} \times 4$	$F = \frac{mg}{2 \times 0.1} \times 4$
$= 10 \times mg$	$= 20 \times mg$

10 x Workpiece weight

20 x Workpiece weight

When gripping a workpiece as in the figure to the left, and with the following definitions,

F: Gripping force [N]

μ : Coefficient of friction between the attachments and the workpiece

m: Workpiece mass [kg]

g: Gravitational acceleration (= 9.8 m/s²)

mg: Workpiece weight [N]

the conditions under which the workpiece will not drop are

$$2 \times \mu F > mg$$

Number of fingers

and therefore,

$$F > \frac{mg}{2 \times \mu}$$

With “a” representing the margin, “F” is determined by the following formula:

$$F = \frac{mg}{2 \times \mu} \times a$$

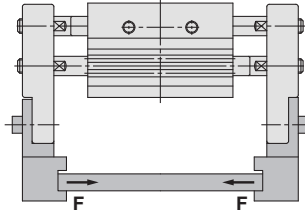
* Even in cases where the coefficient of friction is greater than $\mu = 0.2$, for reasons of safety, select a gripping force which is at least 10 to 20 times greater than the workpiece weight, as recommended by SMC.
• If high acceleration or impact forces are encountered during motion, a further margin should be considered.

Effective Gripping Force

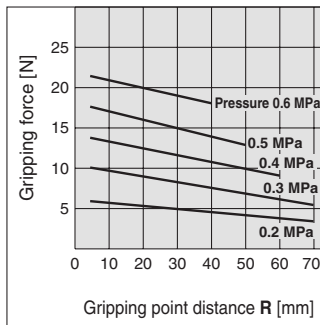
● Indication of effective gripping force

The gripping force shown in the tables represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.

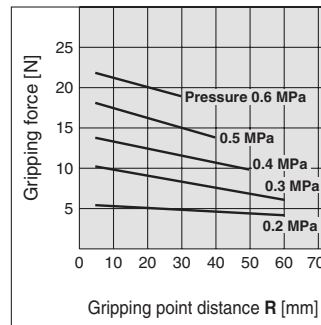
F = One finger thrust



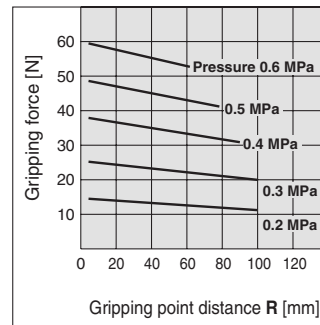
MHL2-10DZ



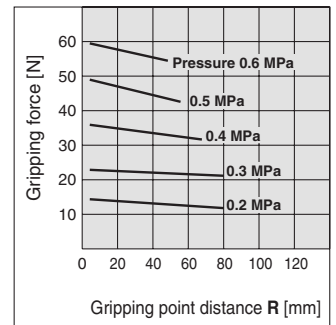
MHL2-10D₂Z



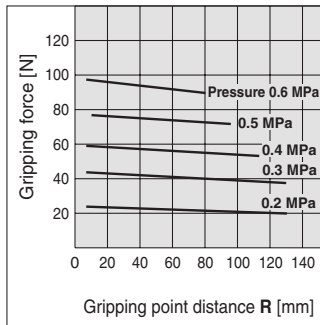
MHL2-16DZ



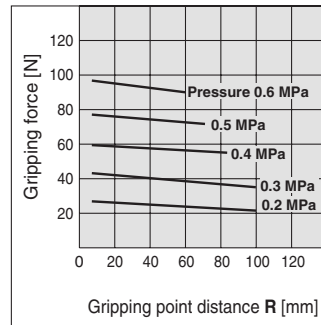
MHL2-16D₂Z



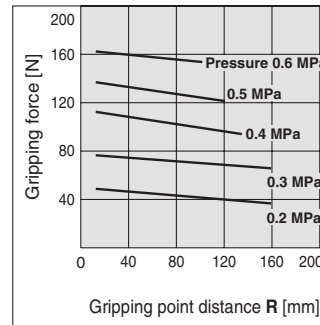
MHL2-20DZ



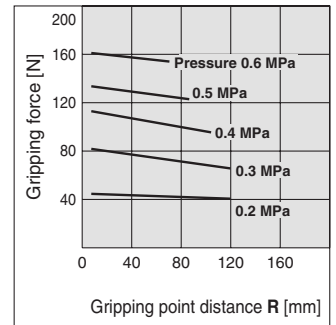
MHL2-20D₂Z



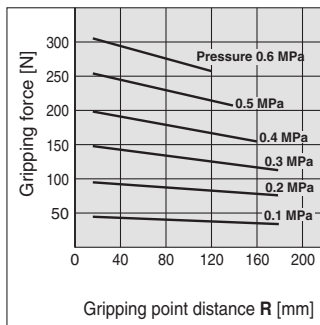
MHL2-25DZ



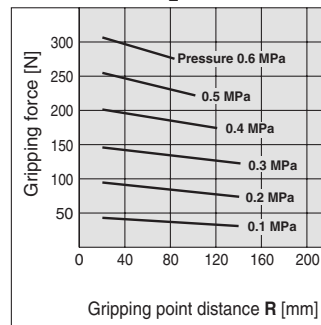
MHL2-25D₂Z



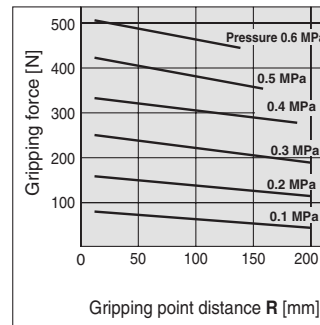
MHL2-32DZ



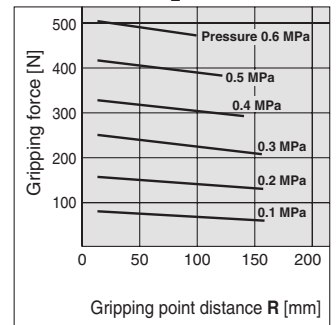
MHL2-32D₂Z



MHL2-40DZ

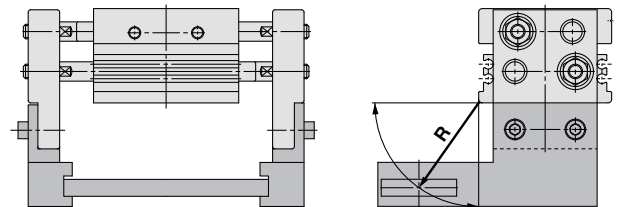


MHL2-40D₂Z



Step 2 Check the gripping point.

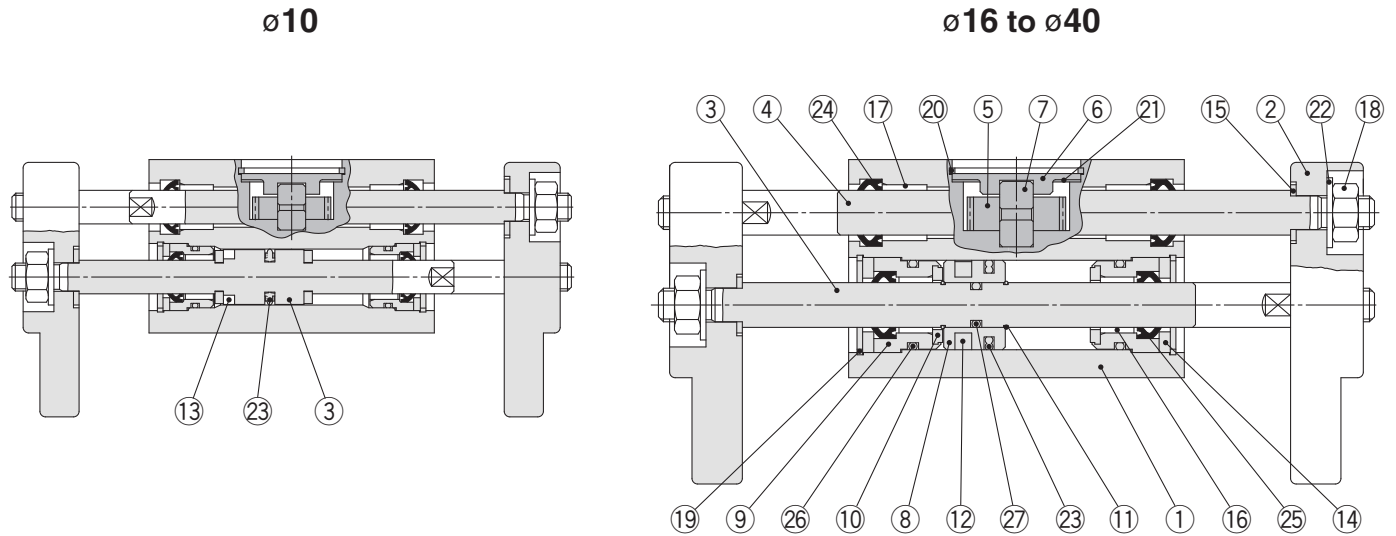
- The workpiece gripping point distance should be within the gripping force ranges given for each pressure in the effective gripping force graphs above.
- If operated with the workpiece gripping point beyond the indicated ranges, the load that will be applied to the fingers or the guide will become excessively unbalanced. As a result, the fingers could become loosened and adversely affect the service life of the unit.



R: Gripping point distance [mm]

MHL2 Series

Construction



Component Parts

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Finger	Aluminum alloy	Hard anodized
3	Piston rod	Stainless steel	
4	Rack	Stainless steel	
5	Pinion	Carbon steel	
6	Pinion cover	Carbon steel	Electroless nickel plating
7	Pinion axis	Stainless steel	
8	Piston	Aluminum alloy	Hard anodized
9	Rod cover	Aluminum alloy	Trivalent chromated
10	Bumper	Urethane rubber	
11	Clip	Stainless steel spring wire	
12	Rubber magnet	Synthetic rubber	
13	Magnet	—	Nickel plating
14	Rod seal cover B	Cold rolled carbon steel sheet	Electroless nickel plating

No.	Description	Material	Note
15	Washer	Stainless steel	
16	Bearing	Oil containing polyacetal	
17	Bearing	Oil containing polyacetal	
18	U-nut	Carbon steel	Trivalent chromated
19	Inverted internal retaining ring	Carbon steel	Phosphate coating
20	C type retaining ring	Carbon steel	Phosphate coating
21	Wave washer	Steel for spring	Phosphate coating
22	Conical spring washer	Carbon steel	
23	Piston seal	NBR	
24	Rod seal	NBR	
25	Rod seal	NBR	
26	Gasket	NBR	
27	Gasket	NBR	

Replacement Parts

Description	MHL2-10□Z	MHL2-16□Z	MHL2-20□Z	MHL2-25□Z	MHL2-32□Z	MHL2-40□Z	Contents	
Seal kit	MHL10-PS	MHL16-PS	MHL20-PS	MHL25-PS	MHL32-PS	MHL40-PS	23, 24, 25, 26, 27	
Piston assembly	MHL2-□□DZ	MHL-AA1001	MHL-AA1601	MHL-AA2001	MHL-AA2501	MHL-AA3201	MHL-AA4001	$\varnothing 10$: 3, 10, 13, 23
	MHL2-□□D1Z	MHL-AA1002	MHL-AA1602	MHL-AA2002	MHL-AA2502	MHL-AA3202	MHL-AA4002	$\varnothing 16$ to $\varnothing 40$: 3, 8, 11, 12, 23, 27
	MHL2-□□D2Z	MHL-AA1003	MHL-AA1603	MHL-AA2003	MHL-AA2503	MHL-AA3203	MHL-AA4003	
Rack	MHL2-□□DZ	MHL-AA1004	MHL-AA1604	MHL-AA2004	MHL-AA2504	MHL-AA3204	MHL-AA4004	
	MHL2-□□D1Z	MHL-AA1005	MHL-AA1605	MHL-AA2005	MHL-AA2505	MHL-AA3205	MHL-AA4005	4
	MHL2-□□D2Z	MHL-AA1006	MHL-AA1606	MHL-AA2006	MHL-AA2506	MHL-AA3206	MHL-AA4006	
Rod cover assembly	MHL-AA1007	MHL-AA1607	MHL-AA2007	MHL-AA2507	MHL-AA3207	MHL-AA4007	$\varnothing 10$: 9, 14, 16, 19, 25, 26 $\varnothing 16$ to $\varnothing 40$: 9, 10, 14, 16, 19, 25, 26	
Finger assembly	MHL-AA1008	MHL-AA1608	MHL-AA2008	MHL-AA2508	MHL-AA3208	MHL-AA4008	2, 15, 18, 22	
Pinion assembly	MHL-AA1009	MHL-AA1609	MHL-AA2009	MHL-AA2509	MHL-AA3209	MHL-AA4009	5, 6, 7, 20, 21	
Nut set	MHL-A1017	MHL-A1617	MHL-A2017	MHL-A2517	MHL-A3217	MHL-A4017	15, 18, 22	
U-nut assembly	MHL-A1017A	MHL-A1617A	MHL-A2017A	MHL-A2517A	MHL-A3217A	MHL-A4017A	18, 22	

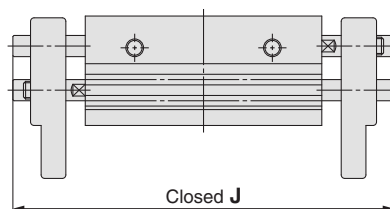
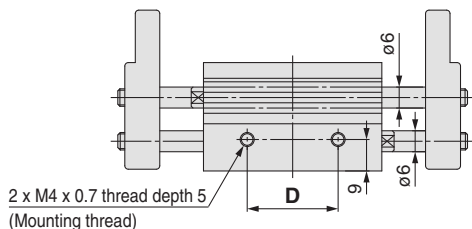
- * Order one finger assembly, pinion assembly, nut set and U-nut assembly per unit.
- * For piston assembly and rack, order 2 pieces per unit.
- * For rod cover assembly, order 4 pieces per unit.
- * The seal kit does not include a grease pack. Order it separately.

Replacement Parts/Grease Pack Part Nos.

MHL2-□□DZ ($\varnothing 10$ to $\varnothing 20$)	GR-S-010 (10 g)
MHL2-□□DZ ($\varnothing 25$, $\varnothing 32$)	GR-S-010 (10 g)
MHL2-□□DZ ($\varnothing 40$)	GR-S-020 (20 g)
MHL2-□□D1Z ($\varnothing 10$, $\varnothing 16$)	GR-S-010 (10 g)
MHL2-□□D1Z ($\varnothing 20$, $\varnothing 25$)	GR-S-010 (10 g)
MHL2-□□D1Z ($\varnothing 32$, $\varnothing 40$)	GR-S-020 (20 g)
MHL2-□□D2Z ($\varnothing 10$, $\varnothing 16$)	GR-S-010 (10 g)
MHL2-□□D2Z ($\varnothing 20$, $\varnothing 25$)	GR-S-010 (10 g)
MHL2-□□D2Z ($\varnothing 32$, $\varnothing 40$)	GR-S-010 (10 g), GR-S-020 (20 g) (1 pack each)

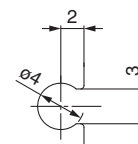
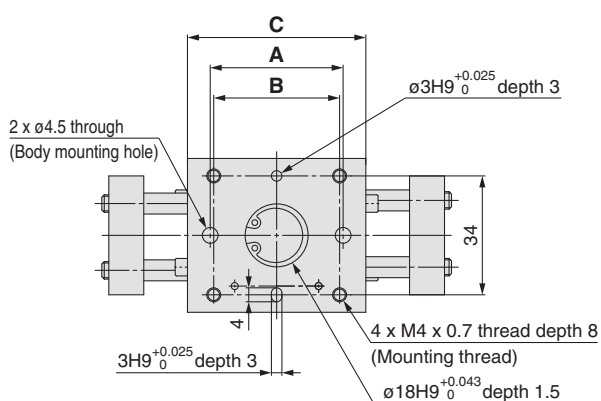
Dimensions

MHL2-10D□Z

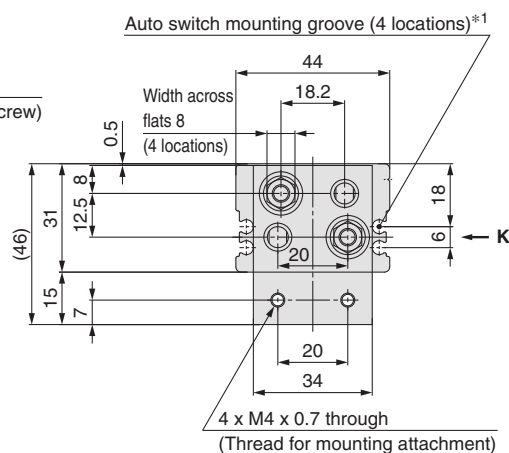
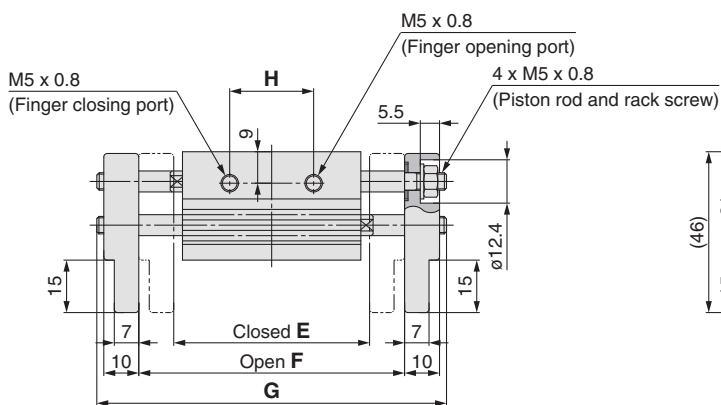


View K (Fingers closed)

* The above figure shows the MHL2-10D1Z/10D2Z.



***1 Dimensions of auto switch mounting groove (Enlarged view)**



Model	A	B	C	D	E	F	G	H	J
MHL2-10DZ	38	36	51	26	56	76	100	24	80
MHL2-10D1Z	54	52	67	42	78	118	142	39	108
MHL2-10D2Z	72	70	85	60	96	156	180	57	146

* J-dimension is at fully closed.

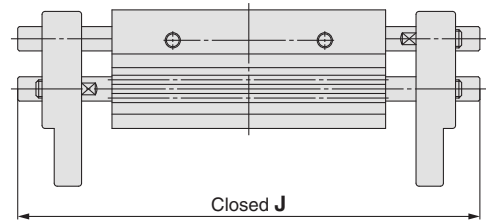
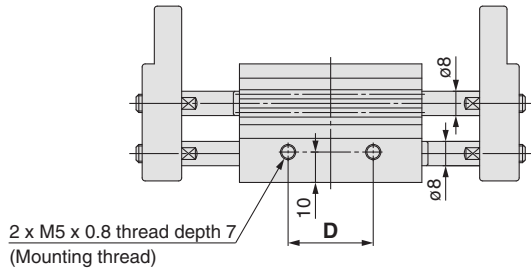
* D1Z is different from D2Z at finger closed because shaft is ejected from finger end.

J-dimension is different from the value which is subtracted stroke from G-dimension.

MHL2 Series

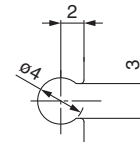
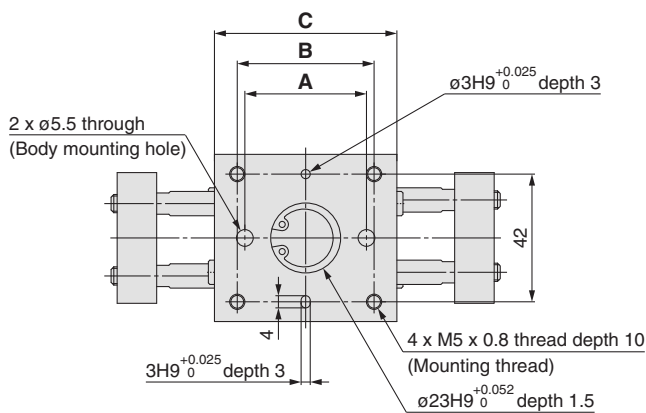
Dimensions

MHL2-16D□Z

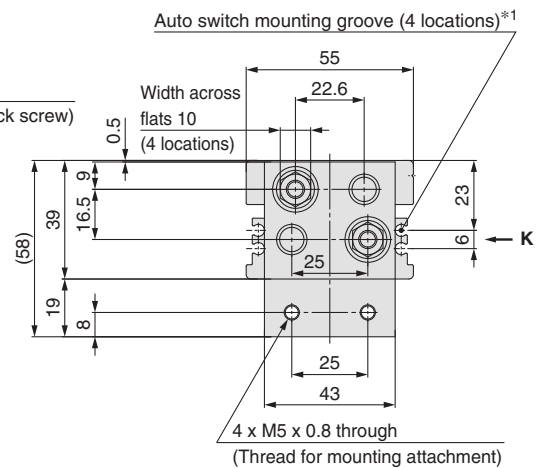
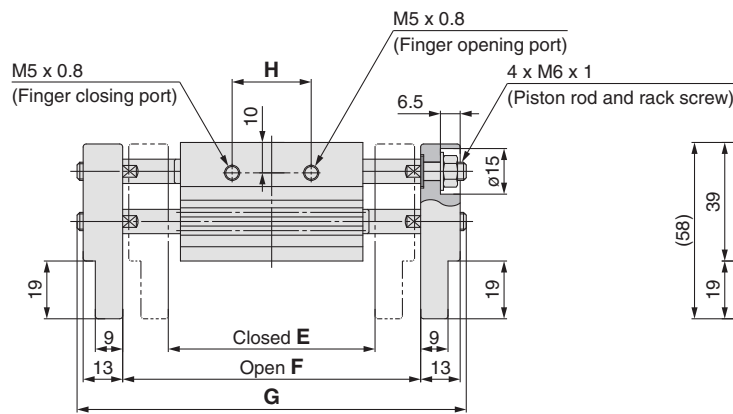


View K (Fingers closed)

* The above figure shows the MHL2-16D1Z/16D2Z.



***1 Dimensions of auto switch mounting groove (Enlarged view)**



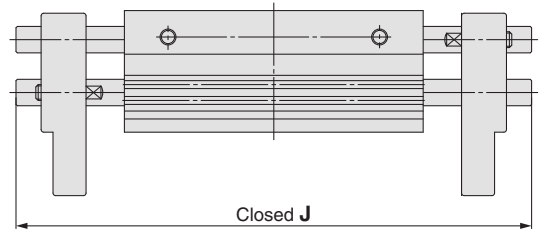
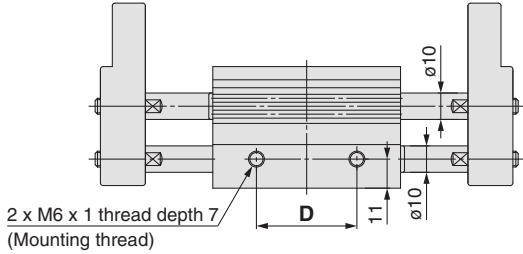
Model	A	B	C	D	E	F	G	H	J
MHL2-16DZ	40	45	60	28	68	98	128	26	98
MHL2-16D1Z	70	75	90	58	110	170	200	50	152
MHL2-16D2Z	90	95	110	78	130	210	240	70	192

* J-dimension is at fully closed.

* D1Z is different from D2Z at finger closed because shaft is ejected from finger end.
J-dimension is different from the value which is subtracted stroke from G-dimension.

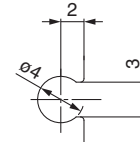
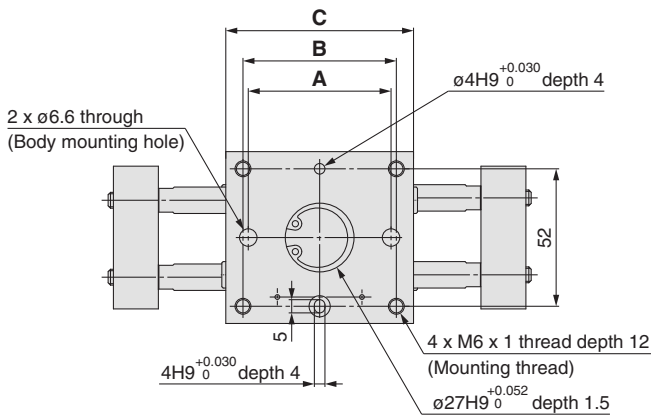
Dimensions

MHL2-20D□Z

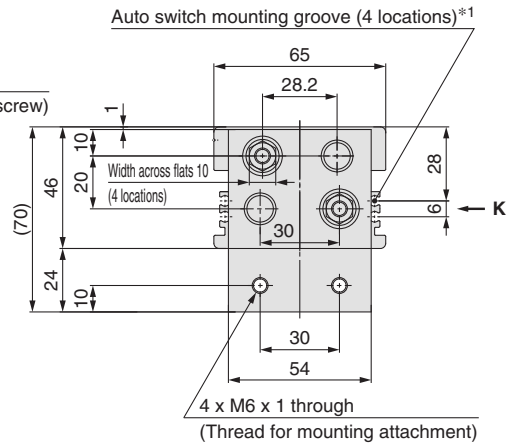
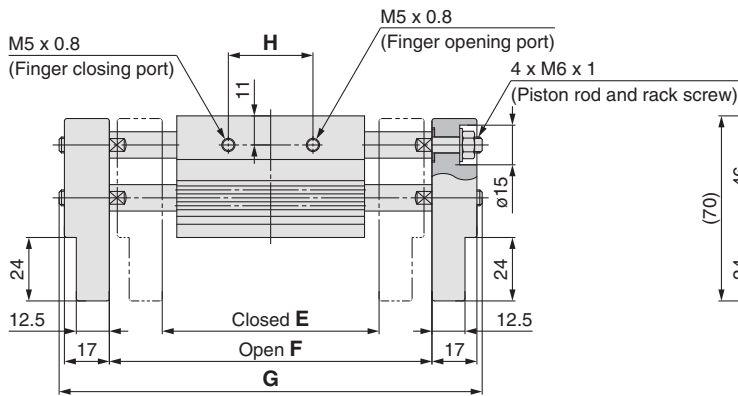


View K (Fingers closed)

* The above figure shows the MHL2-20D1Z/20D2Z.



***1 Dimensions of auto switch mounting groove (Enlarged view)**



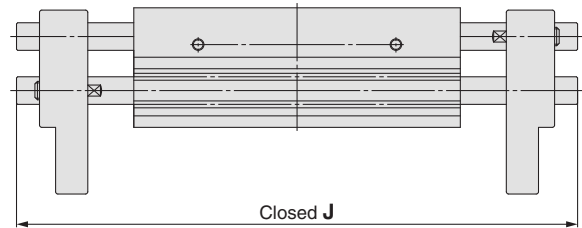
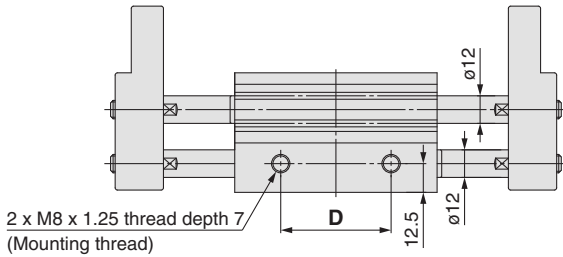
Model	A	B	C	D	E	F	G	H	J
MHL2-20DZ	54	58	71	38	82	122	160	32	120
MHL2-20D1Z	96	100	113	80	142	222	260	68	195
MHL2-20D2Z	116	120	133	100	162	262	300	88	235

* J-dimension is at fully closed.
 * D1Z is different from D2Z at finger closed because shaft is ejected from finger end.
 J-dimension is different from the value which is subtracted stroke from G-dimension.

MHL2 Series

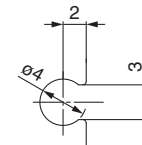
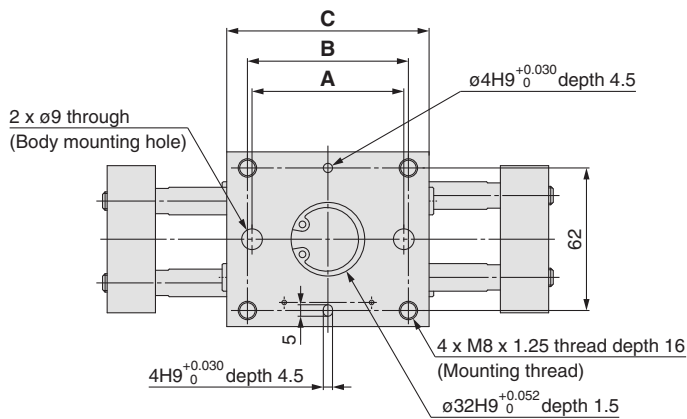
Dimensions

MHL2-25D□Z

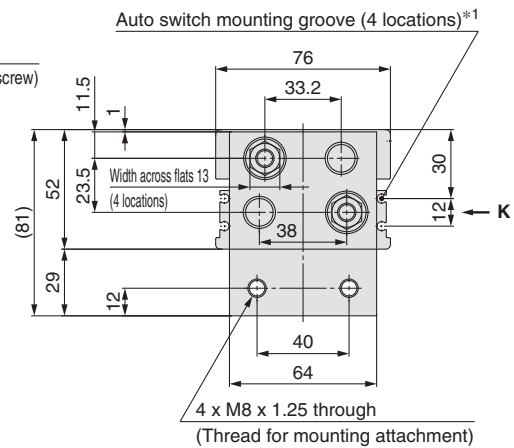
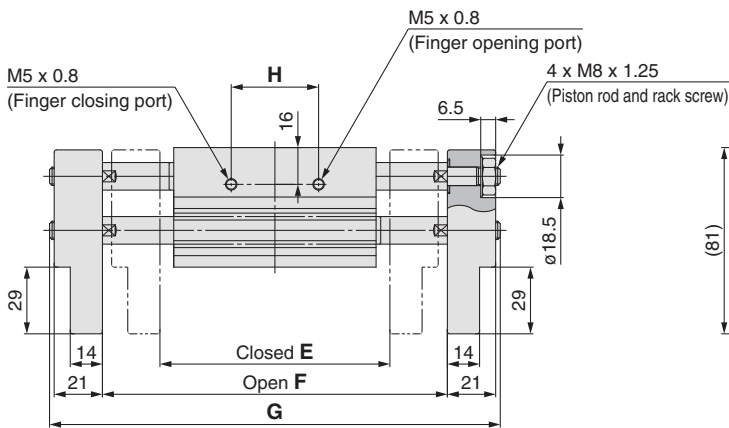


View K (Fingers closed)

* The above figure shows the MHL2-25D1Z/25D2Z.



*1 Dimensions of auto switch mounting groove (Enlarged view)



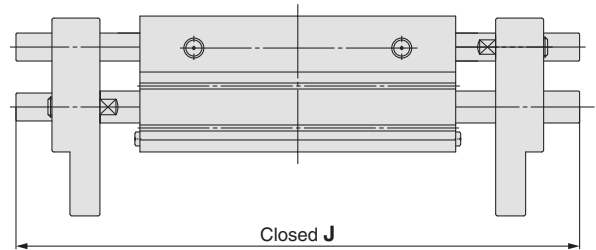
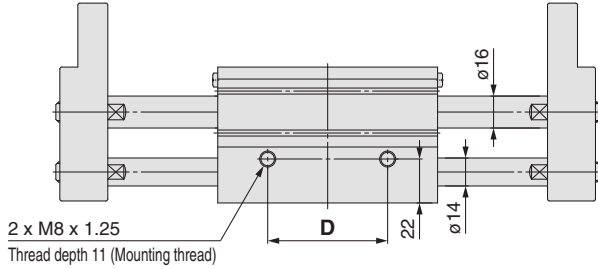
Model	A	B	C	D	E	F	G	H	J
MHL2-25DZ	66	70	88	48	100	150	196	38	146
MHL2-25D1Z	120	124	142	102	182	282	328	86	244
MHL2-25D2Z	138	142	160	120	200	320	366	104	282

* J-dimension is at fully closed.

* D1Z is different from D2Z at finger closed because shaft is ejected from finger end.
J-dimension is different from the value which is subtracted stroke from G-dimension.

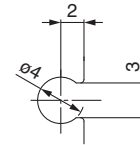
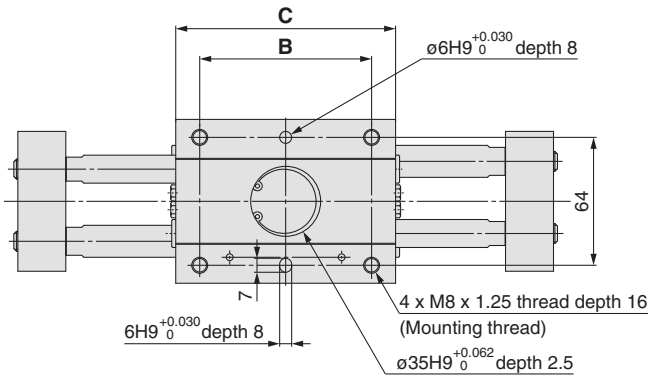
Dimensions

MHL2-32D□Z

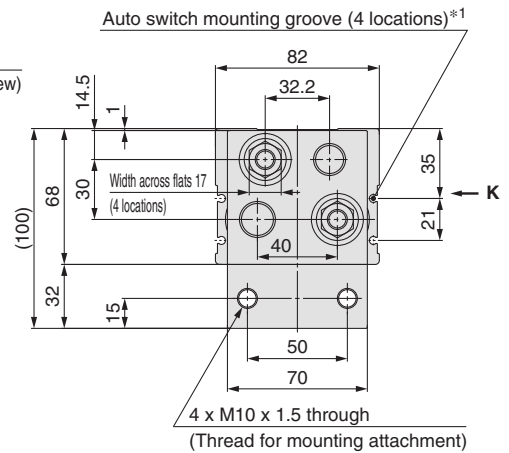
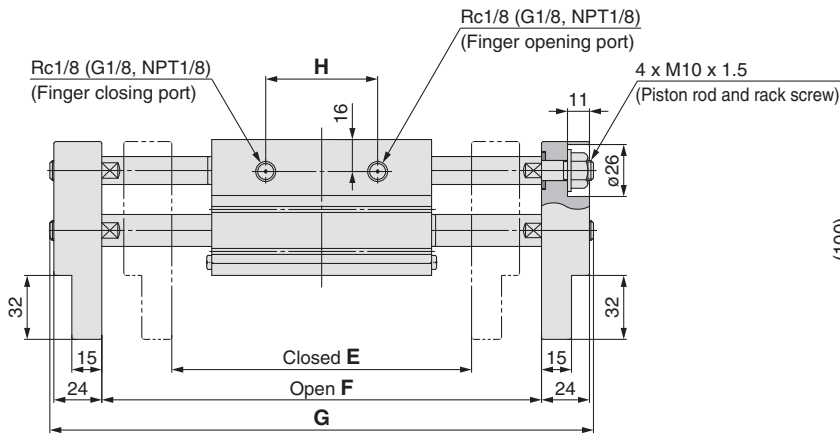


View K (Fingers closed)

* The above figure shows the MHL2-32D1Z/32D2Z.



*1 Dimensions of auto switch mounting groove (Enlarged view)



Model	B	C	D	E	F	G	H	J
MHL2-32DZ	86	110	60	150	220	272	56	202
MHL2-32D1Z	134	158	108	198	318	370	104	282
MHL2-32D2Z	178	202	152	242	402	454	148	366

* J-dimension is at fully closed.

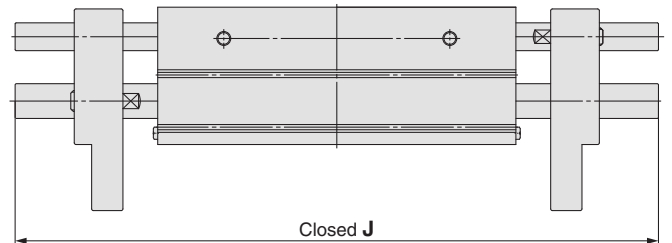
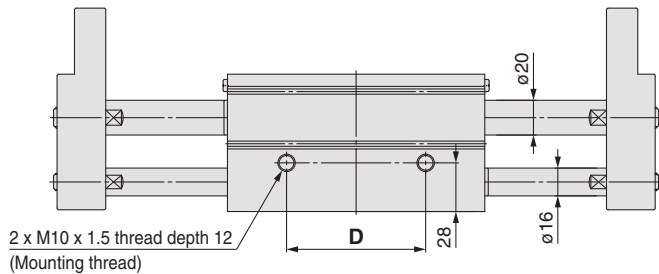
* D1Z is different from D2Z at finger closed because shaft is ejected from finger end.

J-dimension is different from the value which is subtracted stroke from G-dimension.

MHL2 Series

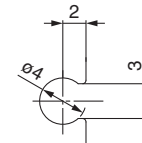
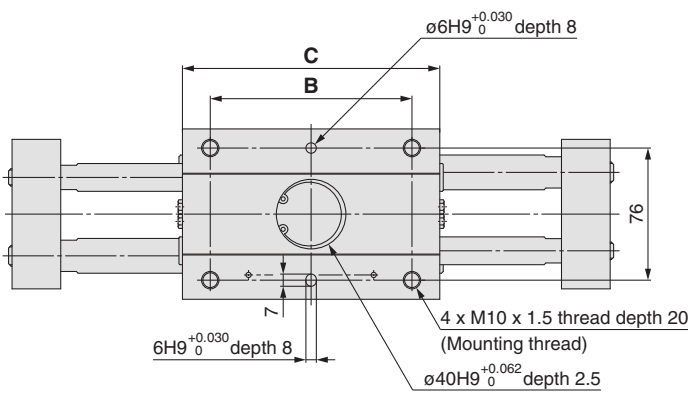
Dimensions

MHL2-40D□Z

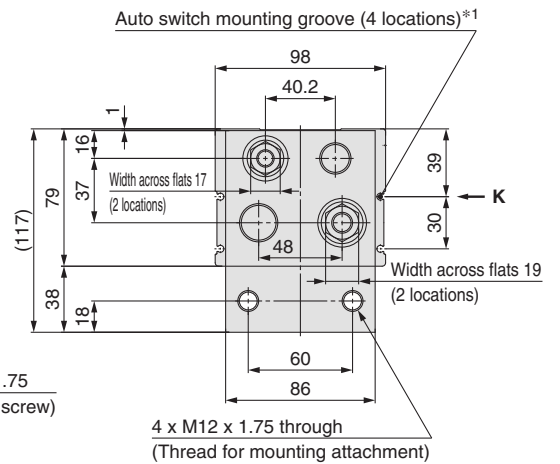
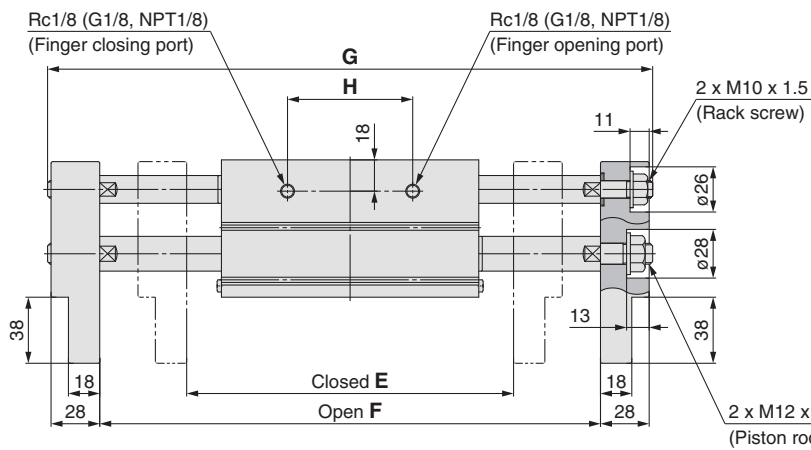


View K (Fingers closed)

* The above figure shows the MHL2-40D1Z/40D2Z.



*** 1 Dimensions of auto switch mounting groove (Enlarged view)**



Model	B	C	D	E	F	G	H	J
MHL2-40DZ	116	148	80	188	288	348	72	252
MHL2-40D1Z	174	206	138	246	406	466	130	370
MHL2-40D2Z	214	246	178	286	486	546	170	450

* J-dimension is at fully closed.

* D1Z is different from D2Z at finger closed because shaft is ejected from finger end.

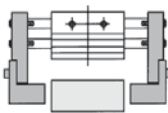
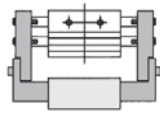
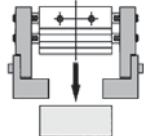
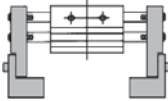
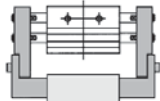
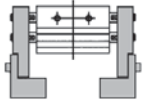
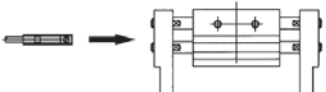

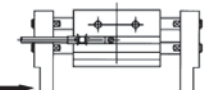

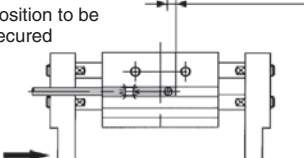
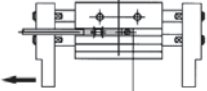

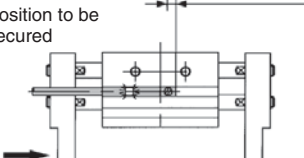
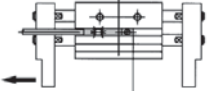

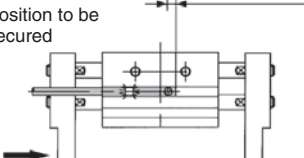
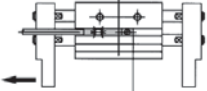

J-dimension is different from the value which is subtracted stroke from G-dimension.

MHL2 Series

Auto Switch Installation Examples and Mounting Positions

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

1) Detection when Gripping Exterior of Workpiece

Detection example		① Confirmation of fingers in reset position	② Confirmation of workpiece held	③ Confirmation of workpiece released
Position to be detected		Position of fingers fully open 	Position when gripping a workpiece 	Position of fingers fully closed 
Operation of auto switch		When fingers return: Auto switch to turn ON (Light ON)	When gripping a workpiece: Auto switch to turn ON (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light ON)
Detection combinations	One auto switch * One position, any of ①, ② and ③ can be detected.	●	●	●
	Two auto switches * Two positions of ①, ② and ③ can be detected.	Pattern A	●	—
		Pattern B	—	●
Pattern C	●	—	●	
How to determine auto switch installation position		Step 1) Fully open the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully close the fingers. 
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.		Step 2) Insert the auto switch into the auto switch mounting groove from the direction of the arrow. 		
		Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. Position where light turns ON 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. 	Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out. 
		Position to be secured 	Step 5) Slide the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. Position where light turns ON 	Position to be secured 
		Position to be secured 	Position where light turns ON 	Position to be secured 
		Position to be secured 	Position where light turns ON 	Position to be secured 

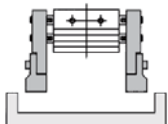
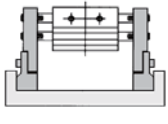
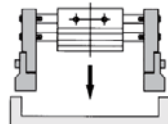
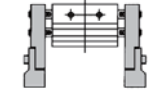
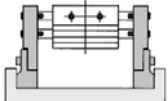
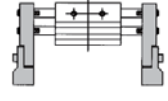
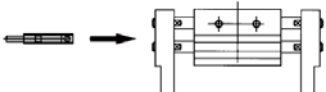
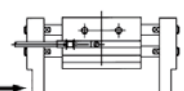
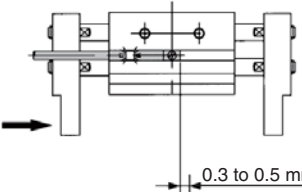
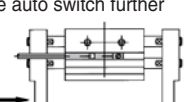
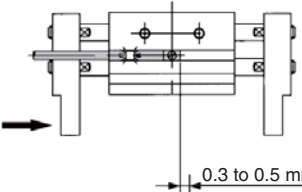
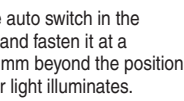
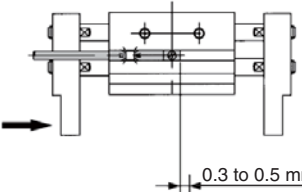
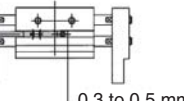
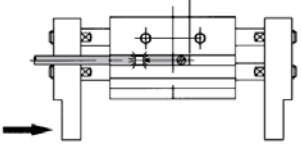
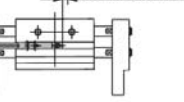
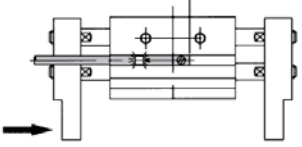
- * It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
- * When holding a workpiece close at the end of opening/closing stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

MHL2 Series

Auto Switch Installation Examples and Mounting Positions

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

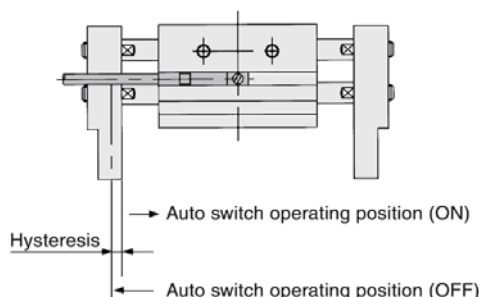
2) Detection when Gripping Interior of Workpiece

Detection example		① Confirmation of fingers in reset position	② Confirmation of workpiece held	③ Confirmation of workpiece released
Position to be detected		Position of fingers fully closed 	Position when gripping a workpiece 	Position of fingers fully open 
Operation of auto switch		When fingers return: Auto switch to turn ON (Light ON)	When gripping a workpiece: Auto switch to turn ON (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light ON)
Detection combinations	One auto switch * One position, any of ①, ② and ③ can be detected.	●	●	●
	Two auto switches * Two positions of ①, ② and ③ can be detected.	Pattern A	●	—
		Pattern B	—	●
Pattern C	●	—	●	
How to determine auto switch installation position		Step 1) Fully close the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully open the fingers. 
		Step 2) Insert the auto switch into the auto switch mounting groove from the direction of the arrow. 		
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.		Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. 	
		Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out. 	Position where light turns ON 	
		Step 5) Slide the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. 	Position where light turns ON 	
		Position where light turns ON 	Position to be secured 	
		Position to be secured 	Position to be secured 	

- * It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
- When holding a workpiece close at the end of opening/closing stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

Auto Switch Hysteresis

The auto switch hysteresis is shown in the table. Refer to the table as a guide when setting auto switch positions.



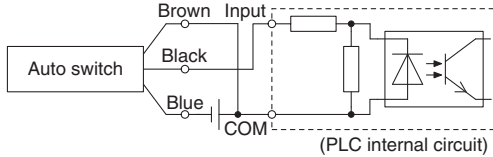
Air gripper model	Auto switch model	[mm]	
		D-M9□(V)	D-M9□W(V) D-M9□A(V)
MHL2-10D□Z		0.2	
MHL2-16D□Z		0.5	
MHL2-20D□Z		0.4	
MHL2-25D□Z		0.4	
MHL2-32D□Z		0.9	
MHL2-40D□Z		0.7	

Prior to Use

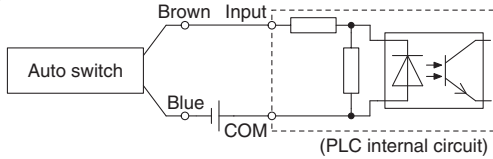
Auto Switch Connections and Examples

Sink Input Specifications

3-wire, NPN

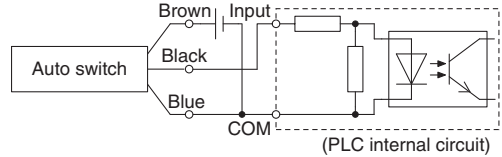


2-wire

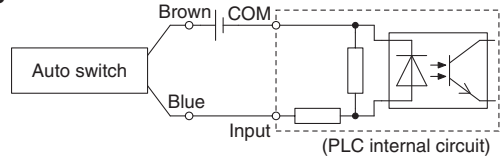


Source Input Specifications

3-wire, PNP



2-wire

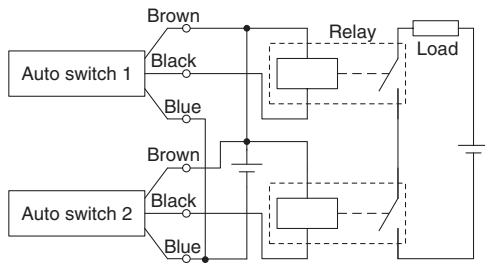


Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.

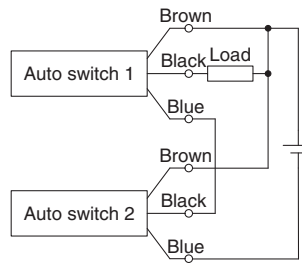
Examples of AND (Series) and OR (Parallel) Connections

* When using solid state auto switches, ensure the application is set up so the signals for the first 50 ms are invalid. Depending on the operating environment, the product may not operate properly.

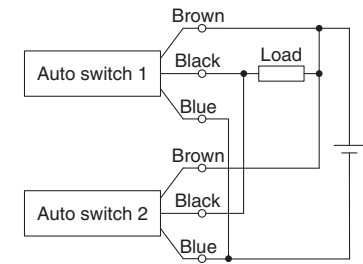
3-wire AND connection for NPN output (Using relays)



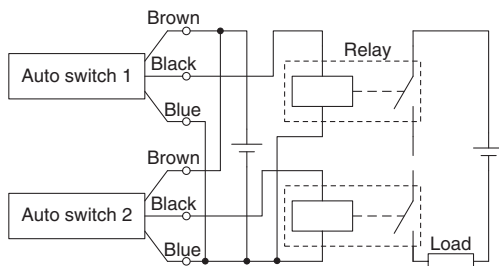
(Performed with auto switches only)



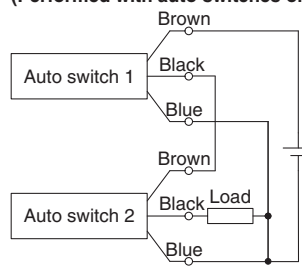
3-wire OR connection for NPN output



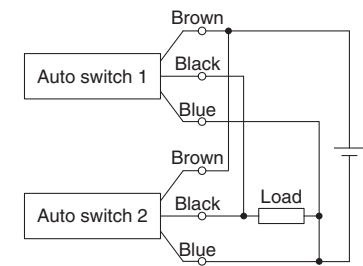
3-wire AND connection for PNP output (Using relays)



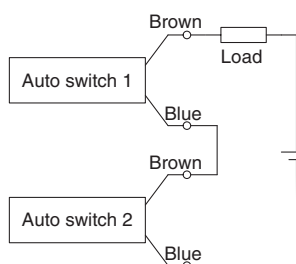
(Performed with auto switches only)



3-wire OR connection for PNP output



2-wire AND connection

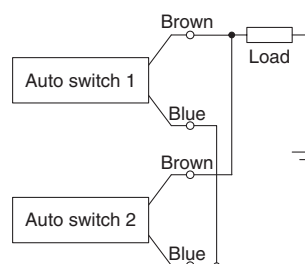


When two auto switches are connected in series, a load may malfunction because the load voltage will decline when in the ON state. The indicator lights will light up when both of the auto switches are in the ON state. Auto switches with a load voltage less than 20 V cannot be used.

$$\begin{aligned} \text{Load voltage at ON} &= \text{Power supply voltage} - \\ &\quad \text{Residual voltage} \times 2 \text{ pcs.} \\ &= 24 \text{ V} - 4 \text{ V} \times 2 \text{ pcs.} \\ &= 16 \text{ V} \end{aligned}$$

Example: Power supply is 24 VDC
Internal voltage drop in auto switch is 4 V.

2-wire OR connection



(Solid state)
When two auto switches are connected in parallel, malfunction may occur because the load voltage will increase when in the OFF state.

(Reed)
Because there is no current leakage, the load voltage will not increase when turned OFF. However, depending on the number of auto switches in the ON state, the indicator lights may sometimes grow dim or not light up, due to the dispersion and reduction of the current flowing to the auto switches.

$$\begin{aligned} \text{Load voltage at OFF} &= \text{Leakage current} \times 2 \text{ pcs.} \times \\ &\quad \text{Load impedance} \\ &= 1 \text{ mA} \times 2 \text{ pcs.} \times 3 \text{ k}\Omega \\ &= 6 \text{ V} \end{aligned}$$

Example: Load impedance is 3 k Ω .
Leakage current from auto switch is 1 mA.

MHL2 Series

Made to Order



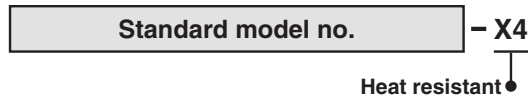
1 -X4	Heat Resistant (–10 to 100°C)	Page 18
2 -X5	Fluororubber Seal	Page 18
3 -X28	With Bolt for Adjusting the Closing Width	Page 19
4 -X50	Without Magnet	Page 19
5 -X53	Ethylene Propylene Rubber Seal (EPDM)	Page 19
6 -X63	Fluorine Grease	Page 20
7 -X79	Grease for Food Processing Machines: Fluorine Grease	Page 20
8 -X79A	Grease for Food Processing Machines: Aluminum Complex Soap Base Grease	Page 21
9 -X85	Fine-particle Proof Specification	Page 21
10 -X86□	With Heavy Duty Scraper + Stable Lubrication Function (Lube-retainer) (Seal Material: NBR, Fluororubber)	Page 23

1 Heat Resistant (-10 to 100°C)

Symbol
-X4

Seal material and grease have been changed so that the product can be used at temperatures between -10 up to 100°C.

How to Order



- * Magnet is built-in, but when using an auto switch, the acceptable temperature range becomes -10 to 60°C.
- * For lubrication, specialized grease GR-F is recommended.

Specifications

Ambient temperature range	-10°C to 100°C (No freezing)
Seal material	Fluororubber
Grease	Heat-resistant grease (GR-F)
Specifications/dimensions other than the above	Same as the standard type

Replacement Parts: Seal Kit

Seal kit part number
MHL□□-PS-X4

- * Enter the cylinder bore size into □□ of the seal kit part number. Refer to page 7 for the replacement parts.
- * The seal kit does not include a grease pack. Order it separately.
Grease pack part number: GR-F-005 (5 g)

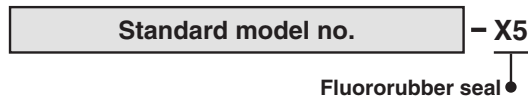
Warning Precautions

Be aware that smoking cigarettes after your hands have come into contact with the grease used for this product can create a gas that is hazardous to humans.

2 Fluororubber Seal

Symbol
-X5

How to Order



- * Please contact SMC, since the type of chemical and the operating temperature may not allow the use of this product.
- * Since the standard type magnet is built-in, please contact SMC for the product's adaptability to the operating environment.

Specifications

Seal material	Fluororubber
Specifications/dimensions other than the above	Same as the standard type

MHL2 Series

3 With Bolt for Adjusting the Closing Width Symbol -X28

Finger closing stroke can be fine-tuned by an adjustment bolt.

How to Order

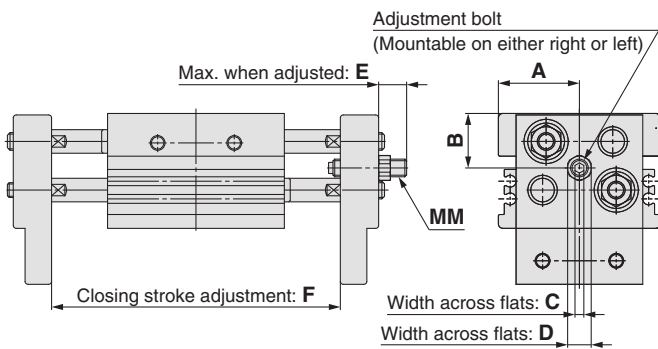
Standard model no. - X28
 With bolt for adjusting the closing width ●

Specifications

Adjustment range/ Adjustment bolt position	Refer to the dimensions below.
Specifications other than the above	Same as the standard type
Dimensions	Refer to the dimensions below.

* Please contact SMC for ø40.
 * The bumper at the end of the adjustment bolt is not heat resistant. Combination with high temperature type is only available with a metal stopper.

Dimensions (The dimensions other than specified below are the same as the standard type.)



Model	A	B	C	D	E	F	MM
MHL2-10DZ-X28	22	15.5	2.5	7	4	2	M5 x 0.8
MHL2-10D1Z-X28					11	16	
MHL2-10D2Z-X28					11	16	
MHL2-16DZ-X28	27.5	18.5	3	8	9.5	9	M6 x 1
MHL2-16D1Z-X28					13.5	20	
MHL2-16D2Z-X28					13.5	20	
MHL2-20DZ-X28	32.5	21	4	12	7.5	7	M8 x 1
MHL2-20D1Z-X28					8.5	9	
MHL2-20D2Z-X28					8.5	9	
MHL2-25DZ-X28	38	26	5	14	7.5	7	M10 x 1
MHL2-25D1Z-X28				15	18	M10 x 1.5	
MHL2-25D2Z-X28				15	18		
MHL2-32DZ-X28	41	32	6	19	32.5	51	M12 x 1.75
MHL2-32D1Z-X28					32.5		
MHL2-32D2Z-X28					32.5		

4 Without Magnet Symbol -X50

How to Order

Standard model no. - X50
 Without magnet ●

Specifications

Magnet	None
Specifications/dimensions other than the above	Same as the standard type

5 Ethylene Propylene Rubber Seal (EPDM) Symbol -X53

Seal material has been changed to ethylene propylene (EPDM), and grease to fluorine grease.

How to Order

Standard model no. - X53
 Ethylene propylene rubber seal ●

* For lubrication, specialized grease GR-F is recommended.
 Grease pack part number: GR-F-005 (5 g)

Specifications

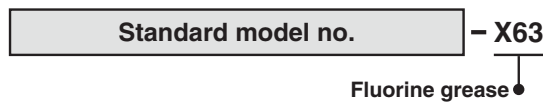
Seal material	Ethylene propylene rubber (EPDM)
Grease	Fluorine grease (GR-F)
Specifications/dimensions other than the above	Same as the standard type

Warning Precautions

Be aware that smoking cigarettes after your hands have come into contact with the grease used for this product can create a gas that is hazardous to humans.

6 Fluorine Grease **Symbol -X63**

How to Order



* For lubrication, specialized grease GR-F is recommended.
Grease pack part number: GR-F-005 (5 g)

Warning Precautions

Be aware that smoking cigarettes after your hands have come into contact with the grease used for this product can create a gas that is hazardous to humans.

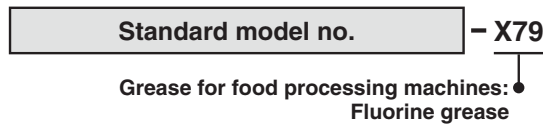
Specifications

Grease	Fluorine grease (GR-F)
Specifications/dimensions other than the above	Same as the standard type

7 Grease for Food Processing Machines: Fluorine Grease **Symbol -X79**

Use grease for food processing machines (NSF-H1 certified/fluorine grease).

How to Order



* For lubrication, specialized grease GR-H is recommended.
Grease pack part number: GR-H-010 (10 g)

Warning Precautions

Be aware that smoking cigarettes after your hands have come into contact with the grease used for this product can create a gas that is hazardous to humans.

Caution

Do not use air grippers in a food-related environment.

<Not installable>

Food zone Food may directly contact with air grippers, and is treated as food products.

<Installable>

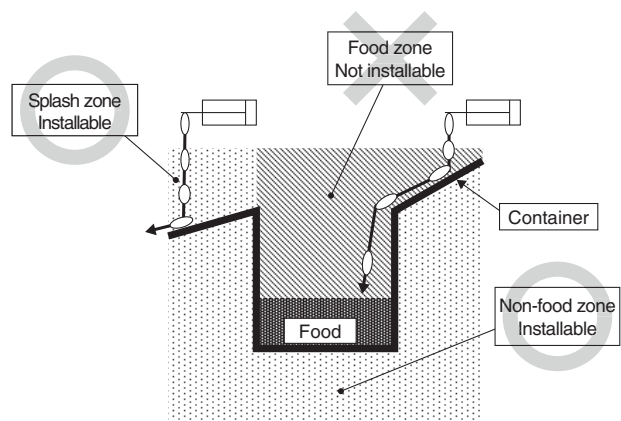
Splash zone Food may directly contact with air grippers, but is not treated as food products.

Non-food zone Air grippers do not directly contact food.

Specifications

Grease	Grease for food processing machines (NSF-H1 certified)/Fluorine grease
Specifications/dimensions other than the above	Same as the standard type

* If the fluorine grease is not applicable to the working environment, use “-X79A.”



8 Grease for Food Processing Machines: Aluminum Complex Soap Base Grease Symbol -X79A

Use grease for food processing machines (NSF-H1 certified).

How to Order

Standard model no. - X79A

Grease for food processing machines:
Aluminum complex soap base grease

⚠ Caution

Do not use air grippers in a food-related environment.

<Not installable>

Food zone Food may directly contact with air grippers, and is treated as food products.

<Installable>

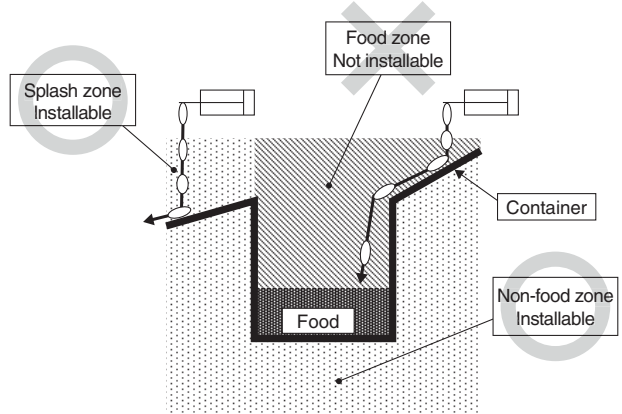
Splash zone Food may directly contact with air grippers, but is not treated as food products.

Non-food zone Air grippers do not directly contact food.

* For lubrication, specialized grease GR-R is recommended.
Grease pack part number: GR-R-010 (10 g)

Specifications

Grease	Grease for food processing machines (NSF-H1 certified)/Aluminum complex soap base grease
Specifications/dimensions other than the above	Same as the standard type



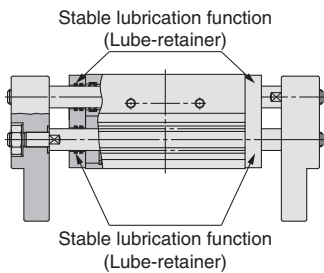
9 Fine-particle Proof Specification Symbol -X85

Applicable for environments with flying micro-powder (10 to 100 μm) such as ceramic powder, toner powder, paper powder, and metallic powder (excluding weld spatter)
A grease film is formed on the rod by the Lube-retainer which maintains lubrication for longer increasing gripper endurance.

How to Order

Standard model no. - X85

Fine-particle proof specification



Specifications

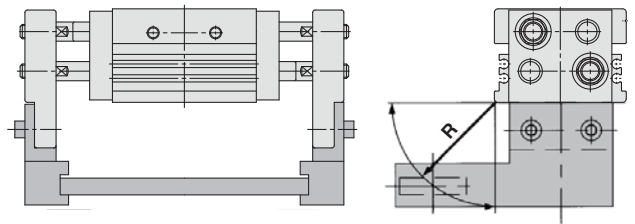
Bore size [mm]	10	16	20	25	32	40
Dust prevention method	Stable lubrication function (Lube-retainer) type (8 locations)					
Operating pressure [MPa]	0.4 to 0.6		0.3 to 0.6			
Repeatability	±0.1					
Effective gripping force [N] ^{*1} at 0.5 MPa	14	45	74	131	228	396

*1 Gripping point distance: 40 mm

Specifications other than the above	Same as the standard type
Dimensions	Refer to the dimensions on page 23.

Gripping Point

- The workpiece gripping point distance should be within the gripping force ranges given for each pressure in the effective gripping force graphs on the next page.
- If operated with the workpiece gripping point beyond the indicated ranges, the load that will be applied to the fingers or the guide will become excessively unbalanced. As a result, the fingers could become loosened and adversely affect the service life of the unit.



R: Gripping point distance [mm]

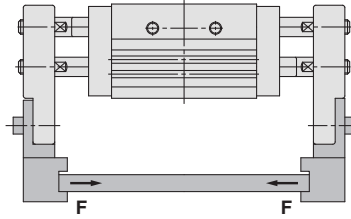
9 Fine-particle Proof Specification

Effective Gripping Force

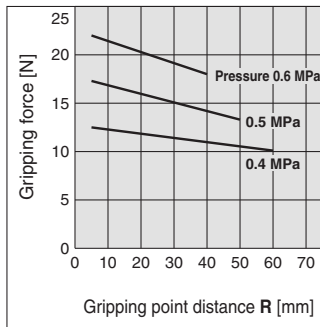
● **Indication of effective gripping force**

The gripping force shown in the tables represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.

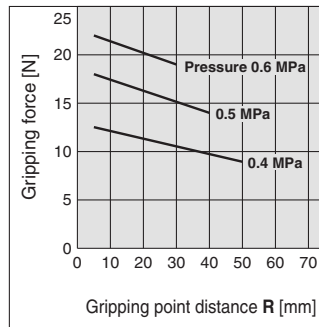
F = One finger thrust



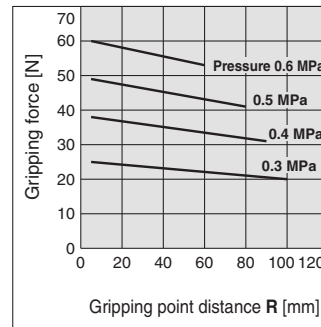
MHL2-10DZ-X85



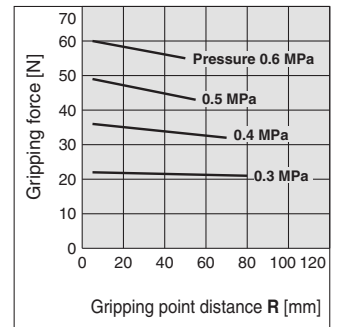
MHL2-10D₂Z-X85



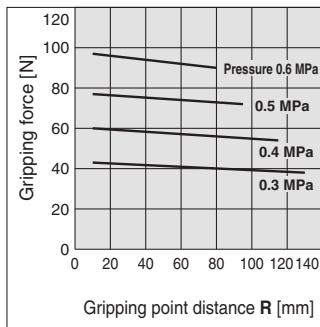
MHL2-16DZ-X85



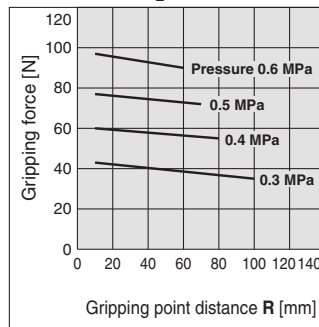
MHL2-16D₂Z-X85



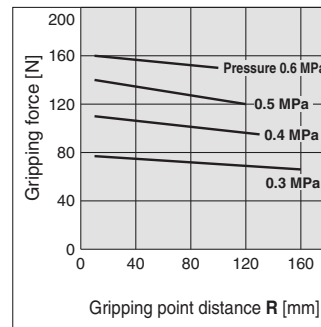
MHL2-20DZ-X85



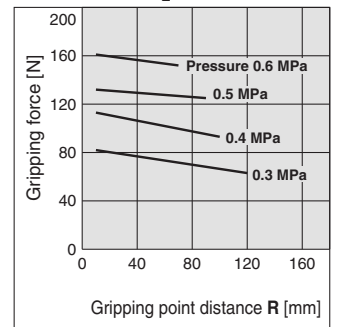
MHL2-20D₂Z-X85



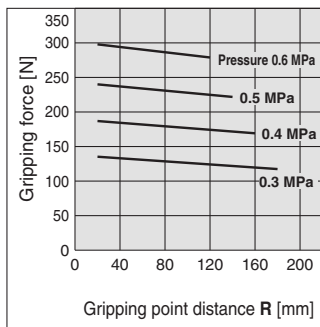
MHL2-25DZ-X85



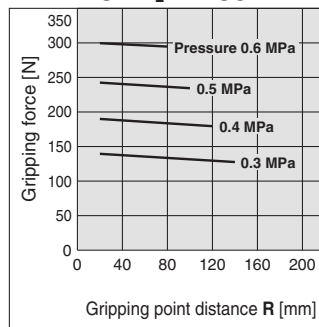
MHL2-25D₂Z-X85



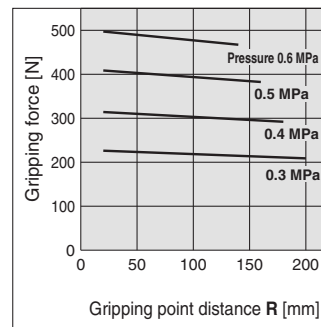
MHL2-32DZ-X85



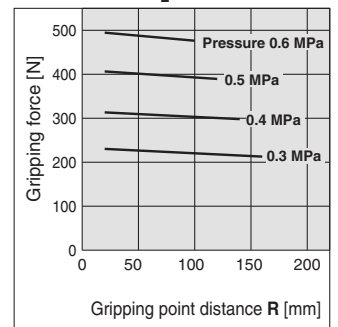
MHL2-32D₂Z-X85



MHL2-40DZ-X85



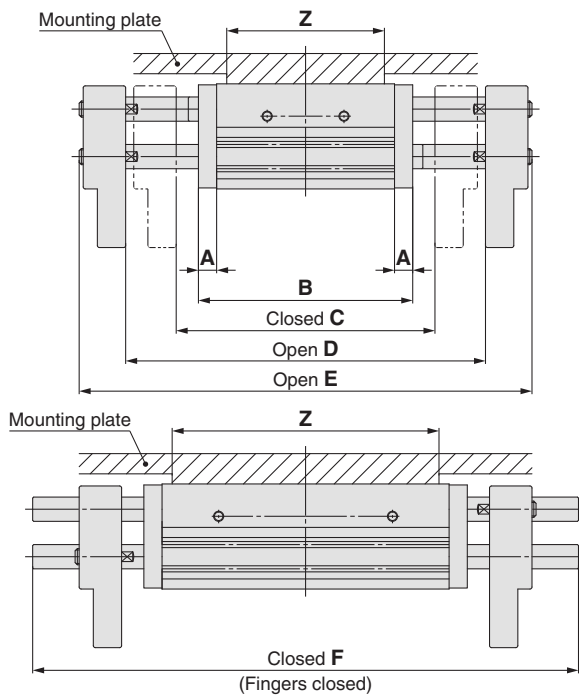
MHL2-40D₂Z-X85



9 Fine-particle Proof Specification

Symbol
-X85

Dimensions (The dimensions other than specified below are the same as the standard type.)



Model	A	B	C	D	E	F	Z	Weight [g]
MHL2-10DZ-X85	8	67	88	108	132	112	49	350
MHL2-10D1Z-X85	8	83	104	144	168	131	65	420
MHL2-10D2Z-X85	8	101	122	182	206	169	83	495
MHL2-16DZ-X85	9.5	79	96	126	156	126	58	650
MHL2-16D1Z-X85	9.5	109	126	186	216	179	88	840
MHL2-16D2Z-X85	9.5	129	146	226	256	219	108	965
MHL2-20DZ-X85	9	89	108	148	186	146	69	1115
MHL2-20D1Z-X85	9	131	150	230	268	221	111	1490
MHL2-20D2Z-X85	9	151	170	270	308	261	131	1675
MHL2-25DZ-X85	9	106	128	178	224	174	86	1815
MHL2-25D1Z-X85	9	160	182	282	328	270	140	2500
MHL2-25D2Z-X85	9	178	200	320	366	308	158	2730
MHL2-32DZ-X85	11.5	133	161	231	283	213	108	3255
MHL2-32D1Z-X85	11.5	181	209	329	381	311	156	4145
MHL2-32D2Z-X85	11.5	225	253	413	465	395	200	4960
MHL2-40DZ-X85	10	168	198	298	358	278	146	5685
MHL2-40D1Z-X85	10	226	256	416	476	396	204	7220
MHL2-40D2Z-X85	10	266	296	496	556	476	244	8270

* The customer's mounting plate should be attached with the Z-dimension.

10 With Heavy Duty Scraper + Stable Lubrication Function (Lube-retainer) (Seal Material: NBR, Fluororubber)

Symbol
-X86

- The cylinders are suitable for use in environments with significant amounts of dust with the heavy duty scraper on the wiper ring. In addition, the Lube-retainer creates a grease coating around the rod, which improves lubrication.
- Seal material can be NBR or fluororubber.

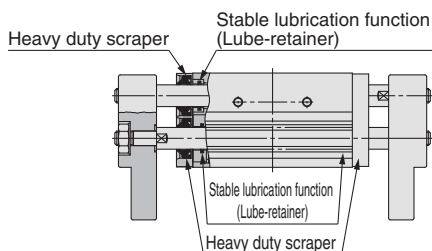
How to Order

Standard model no. **- X86**

With heavy duty scraper + Stable lubrication function (NBR seals)

Standard model no. **- X86A**

With heavy duty scraper + Stable lubrication function (Fluororubber seals)



Specifications

Symbol	-X86			-X86A		
Bore size [mm]	25	32	40	25	32	40
Dust prevention method	Heavy duty scraper + Stable lubrication function (Lube-retainer) type (8 locations)					
Heavy duty scraper material	NBR			Fluororubber		
Operating pressure [MPa]	0.3 to 0.6					
Repeatability	±0.1					
Effective gripping force [N]*1 at 0.5 MPa	131	228	396	131	228	396

*1 Gripping point distance: 40 mm

* For water resistant type, please contact SMC local sales representative.

Specifications other than the above	Same as the standard type
Dimensions	Refer to the dimensions on page 24.

10 With Heavy Duty Scraper + Stable Lubrication Function (Lube-retainer) (Seal Material: NBR, Fluororubber)

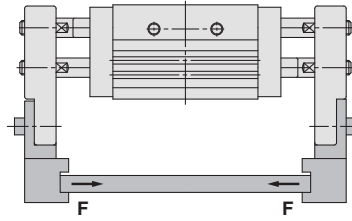
Symbol
-X86 □

Effective Gripping Force

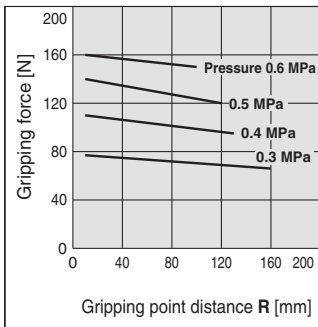
● **Indication of effective gripping force**

The gripping force shown in the tables represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.

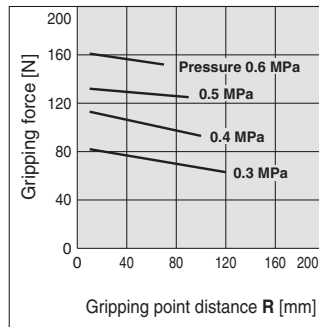
F = One finger thrust



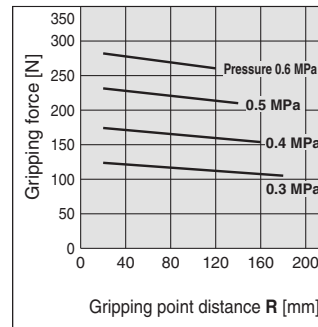
MHL2-25DZ-X86/X86A



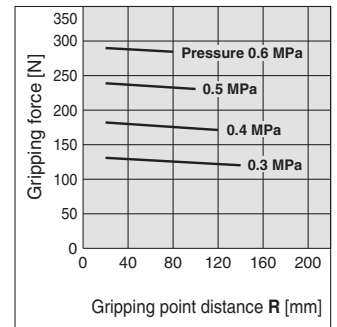
MHL2-25D¹/₂Z-X86/X86A



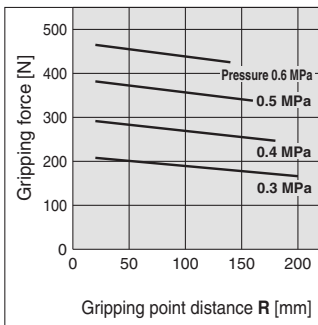
MHL2-32DZ-X86/X86A



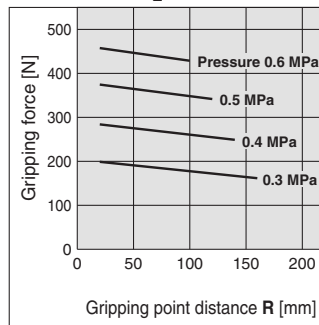
MHL2-32D¹/₂Z-X86/X86A



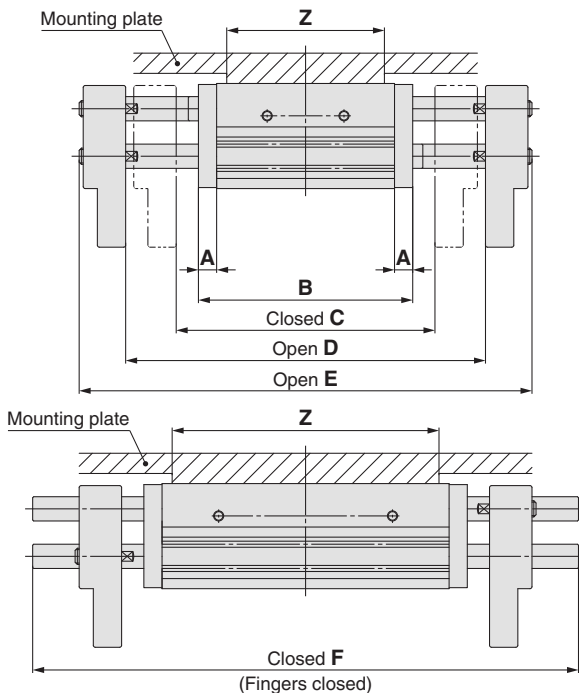
MHL2-40DZ-X86/X86A



MHL2-40D¹/₂Z-X86/X86A



Dimensions (The dimensions other than specified below are the same as the standard type.)



Model	A	B	C	D	E	F	Z	Weight [g]
MHL2-25DZ-X86(A)	9	106	128	178	224	174	86	1835
MHL2-25D ¹ / ₂ Z-X86(A)	9	160	182	282	328	270	140	2520
MHL2-25D2Z-X86(A)	9	178	200	320	366	308	158	2750
MHL2-32DZ-X86(A)	11.5	133	161	231	283	213	108	3250
MHL2-32D ¹ / ₂ Z-X86(A)	11.5	181	209	329	381	311	156	4150
MHL2-32D2Z-X86(A)	11.5	225	253	413	465	395	200	4960
MHL2-40DZ-X86(A)	10	168	198	298	358	278	146	5765
MHL2-40D ¹ / ₂ Z-X86(A)	10	226	256	416	476	396	204	7295
MHL2-40D2Z-X86(A)	10	266	296	496	556	476	244	8340

* The customer's mounting plate should be attached with the Z-dimension.