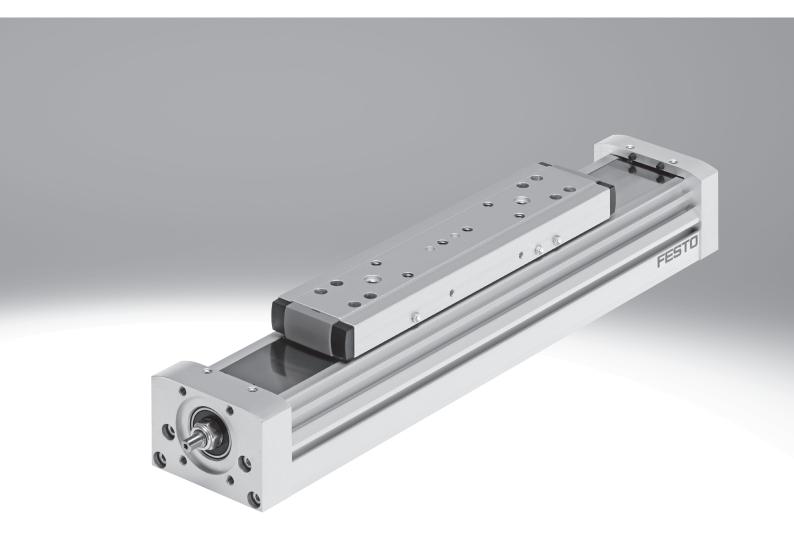
# **Ball screw axes ELGA-BS**

# **FESTO**



### Selection aid

### Overview of toothed belt and ball screw axes

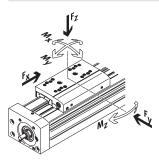
Toothed belt axes

- Speeds of up to 10 m/s
- Acceleration of up to 50 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.08 mm
- Strokes of up to 8500 mm (longer strokes on request)
- Flexible motor mountings

### Ball screw axes

- Speeds of up to 2 m/s
- ullet Acceleration of up to 20 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.003 mm
- Strokes up to 3000 mm

### Coordinate system



ype	F <sub>x</sub>	v	Mx	My	Mz	Characteristics
) F -	[N]	[m/s]	[Nm]	[Nm]	[Nm]	
eavy-duty recirculating b	all bearing gu	ide	· ·	`	'	
EGC-HD-TB						
	450	3	140	275	275	Flat drive unit with rigid, closed profile
	1000	5	300	500	500	Precision DUO guide rail with high load capacity
	1800	5	900	1450	1450	Ideal as a base axis for linear gantries and cantilever axes
locisculating hall bearing	- mulda					
tecirculating ball bearing EGC-TB-KF	guide					
	50	3	3.5	10	10	Rigid, closed profile
	100	5	16	132	132	Precision guide rail with high load capacity
	350	5	36	228	228	Small drive pinions reduce required driving torque
	800	5	144	680	680	Space-saving position sensing
	2500	5	529	1820	1820	Space Saving position sensing
CAPP.	2,000	,	329	1620	1620	
ELGA-TB-KF						
	350	5	16	132	132	Internal guide and toothed belt
	800	5	36	228	228	Precision guide rail with high load capacity
	1300	5	104	680	680	Guide and toothed belt protected by cover strip
	2000	5	167	1150	1150	High feed forces
ELGA-TB-KF-F1	l .			· ·	l	
	260	5	16	132	132	Suitable for use in the food zone
	600	5	36	228	228	"Clean look": smooth, easy-to-clean surfaces
	1000	5	104	680	680	Internal guide and toothed belt
						Precision guide rail with high load capacity
						Guide and toothed belt protected by cover strip
ELGC-TB-KF						
ELGC-1D-KF	75	1.2	5.5	4.7	4.7	Internal guide and toothed belt
	120	1.5	29.1	31.8	31.8	Precision guide and toothed bett     Precision guide rail with high load capacity
	250	1.5	59.8	56.2	56.2	Guide and toothed belt protected by cover strip
	250	1.5	39.0	36.2	36.2	• duide and toothed belt protected by cover strip
ELGR-TB						
LLGK-1D	50	3	2.5	20	20	Cost-optimised rod guide
	100	3	5	40	40	Ready-to-install unit
	350	3	15	124	124	Linear ball bearings with high load capacity for dynamic operation.
	>   >>0	٦	15	124	124	Linear Dati Dearings with high todu capacity for dynamic operation

# Selection aid

### Overview of toothed belt and ball screw axes

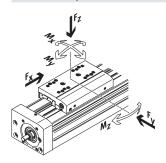
Toothed belt axes

- Speeds of up to 10 m/s
- Acceleration of up to 50 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.08 mm
- Strokes of up to 8500 mm (longer strokes on request)
- Flexible motor mountings

### Ball screw axes

- Speeds of up to 2 m/s
- Acceleration of up to 20 m/s<sup>2</sup>
- Repetition accuracy of up to ±0.003 mm
- Strokes up to 3000 mm

### Coordinate system



200	l e	1,,	l Mx	My	Mz	Characteristics		
pe	F <sub>x</sub> [N]	v [m/s]	[Nm]	[Nm]	[Nm]	Characteristics		
ller bearing guide								
ELGA-TB-RF								
	350	10	11	40	40	Heavy-duty roller bearing guide		
	800	10	30	180	180	Guide and toothed belt protected by cover strip		
	1300	10	100	640	640	Speeds of up to 10 m/s		
						Lower weight than axes with guide rails		
ELGA-TB-RF-F1								
	260	10	8.8	32	32	Suitable for use in the food zone		
	600	10	24	144	144	<ul><li>"Clean look": smooth, easy-to-clean surfaces</li></ul>		
	1000	10	80	512	512	Heavy-duty roller bearing guide		
						Guide and toothed belt protected by cover strip		
						Lower weight than axes with guide rails		
ain-bearing guide								
ELGA-TB-G								
	350	5	5	30	10	Guide and toothed belt protected by cover strip		
	800	5	10	60	20	For simple handling tasks		
	1300	5	120	120	40	As a drive component for external guides		
						Insensitive to harsh ambient conditions		
ELGR-TB-GF								
P	50	1	1	10	10	Cost-optimised rod guide		
	100	1	2.5	20	20	Ready-to-install unit		
	350	1	1	40	40	Heavy-duty plain bearings for use in harsh ambient conditions		

### Selection aid

### Overview of toothed belt and ball screw axes

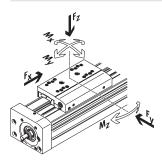
Toothed belt axes

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- Repetition accuracy of up to ±0.08 mm
- Strokes of up to 8500 mm (longer strokes on request)
- Flexible motor mountings

### Ball screw axes

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- Repetition accuracy of up to ±0.003 mm
- Strokes up to 3000 mm

### Coordinate system



pe	F <sub>x</sub>	V	Mx	My	Mz	Characteristics
r -	[N]	[m/s]	[Nm]	[Nm]	[Nm]	
eavy-duty recirculat	ing ball bearing s	guide	· ·			
EGC-HD-BS						
4	400	0.5	140	275	275	Flat drive unit with rigid, closed profile
	650	1.0	300	500	500	Precision DUO guide rail with high load capacity
	1500	1.5	900	1450	1450	Ideal as a base axis for linear gantries and cantilever axes
circulating ball bea	ring guide					
EGC-BS-KF	<u> </u>	10.5	144	100	1400	B)
//	400	0.5	16	132	132	Rigid, closed profile
1.5	650	1.0	36	228	228	Precision guide rail with high load capacity
	1500	1.5	144	680	680	For the highest requirements in terms of feed force and accuracy
	3000	2.0	529	1820	1820	Space-saving position sensing
ELGA-BS-KF						
~	650	0.5	16	132	132	Internal guide and ball screw
	1600	1.0	36	228	228	Precision guide rail with high load capacity
	3400	1.5	104	680	680	For the highest requirements in terms of feed force and accuracy
	6400	2.0	167	1150	1150	Guide and ball screw protected by cover strip
						Space-saving position sensing
ELGC-BS-KF						
	40	0.6	1.3	1.1	1.1	Internal guide and ball screw
	100	0.6	5.5	4.7	4.7	Guide and ball screw protected by cover strip
	200	0.8	29.1	31.8	31.8	Space-saving position sensing
	350	1.0	59.8	56.2	56.2	
EGSK						
	57	0.33	13	3.7	3.7	Ball screw axes with maximum precision, compactness and rigidi
	133	1.10	28.7	9.2	9.2	Recirculating ball bearing guide and ball screw without caged ba
	184	0.83	60	20.4	20.4	bearings
	239	1.10	79.5	26	26	Standard designs in stock
	392	1.48	231	77.3	77.3	

### Key features

### At a glance



### Displacement encoder (optional)



[1] Displacement encoder (optional)

The position of the slide can be sensed directly when using the incremental displacement encoder. This means that all elasticities of the drivetrain can be detected and can be adjusted by the motor controller (→ page 13)

- Stainless steel cover strip with magnetic seal provides basic protection for guide and ball screw. This also makes it possible to reduce particulate emissions for use in clean environments.
- The optional magnetic reversal in the slide guides the stainless steel cover strip through the slide and back onto the profile. The magnets ensure there is no friction on the visible surface of the cover strip.
- The magnetic belt reversal minimises particulate emissions for use in clean rooms.
- Internal, precision recirculating ball bearing guide with high load capacity for high torque loads
- Easy maintenance thanks to easily accessible lubrication connections

### Sealing air connections



- [1] Sealing air connections
- Application of negative pressure minimises the dispersal of abraded particles into the environment
- Application of positive pressure prevents dirt from getting into the axis

### Characteristic values of the axes

The specifications shown in the table are maximum values. The precise values for each of the variants can be found in the relevant data sheet in the catalogue.

Version	Size	Working stroke	Speed	Repetition	Max. feed force	Guide characteristics					
				accuracy		Forces and torques					
					F <sup>-</sup>	Fy	Fz	Mx	Му	Mz	
		[mm]	[m/s]	[mm]	[N]	[N]	[N]	[Nm]	[Nm]	[Nm]	
Recirculating ball bearin	g guide										
	70	50 900	0.5	±0.02	650	1500	1850	16	132	132	
	80	50 1940	1.0	±0.02	1600	2500	3050	36	228	228	
	120	50 2460	1.5	±0.02	3400	5500	6890	104	680	680	
	150	50 3000	2.0	±0.02	6400	5500	11000	167	1150	1150	
					·						



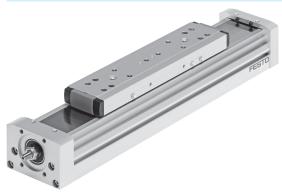
Note

Engineering software Electric Motion Sizing

www.festo.com/x/electric-motion-sizing

# Key features

### Complete system comprising ball screw axis, motor, motor controller and motor mounting kit



### Motor



Servo motor: EMMT-AS Stepper motor: EMMB-ST, EMMT-ST



Note

A range of specially adapted complete solutions is available for the ball screw axis ELGA and the motors.

### Servo drives



Servo drive: CMMT-AS Servo drive for extra-low voltage: CMMT-ST

### Motor mounting kit

### Axial kit



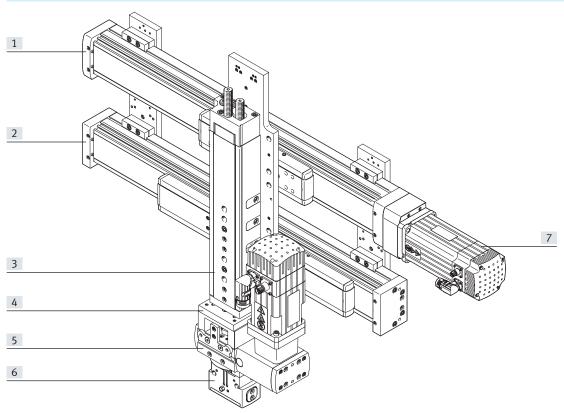
### Parallel kit



Complete kits are available for both parallel and axial motor mounting.

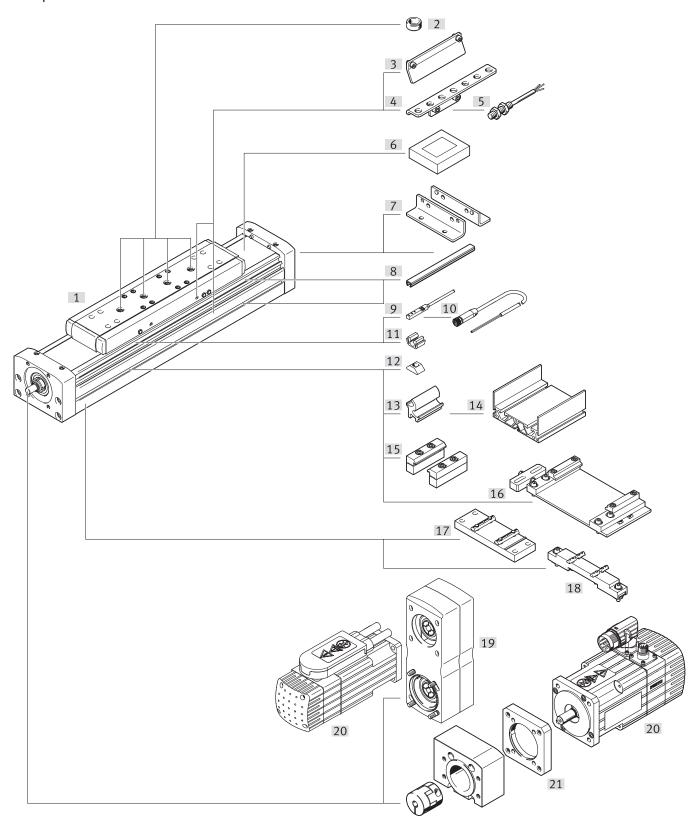
# Key features

# System product for handling and assembly technology



Syste	System components and accessories								
		Description	→ Internet						
[1]	Axes	Wide range of combinations possible within handling and assembly systems	axis						
[2]	Guide axes	For absorbing forces and torques in multi-axis applications	guide axis						
[3]	Drives	Wide range of combinations possible within handling and assembly systems	drive						
[4]	Adapter	For drive/drive and drive/gripper connections	gripper						
[5]	Semi-rotary drive	Wide range of variations possible within handling and assembly technology	semi-rotary drive						
[6]	Gripper	Wide range of variations possible within handling and assembly technology	gripper						
[7]	Motors	Servo and stepper motors, with or without gear unit	motor						

# Peripherals overview



# Peripherals overview

Acces	Accessories								
	Туре	Description	→ Page/Internet						
[1]	Ball screw axis ELGA-BS-KF	Electric drive	10						
[2]	Centring pin/sleeve ZBS, ZBH								
[3]	Switch lug SF-EGC	For sensing the slide position	38						
[4]	Sensor bracket HWS-EGC	For mounting the inductive proximity switches (round design) on the axis	39						
[5]	Proximity switch, M8 SIEN-M8	Inductive proximity switch, round design	42						
[6]	Clamping component EADT	Tool for retensioning the cover strip	40						
[7]	Foot mounting HPE	<ul> <li>For mounting the axis on the end cap</li> <li>With higher forces and torques, the axis should be mounted using the profile</li> </ul>	33						
[8]	Slot cover ABP	For protection against contamination	40						
[9]	Proximity switch, T-slot SIES-8M	Inductive proximity switch, for T-slot	41						
[10]	Connecting cable NEBA	Via proximity switch	42						
[11]	Clip SMBK	For mounting the proximity switch cable in the slot	40						
[12]	Slot nut NST	For mounting attachments	40						
[13]	Adapter kit DHAM	For mounting the support profile on the axis	41						
[14]	Support profile HMIA	For mounting and guiding an energy chain	41						
[15]	Profile mounting MUE	For mounting the axis on the side of the profile	34						
[16]	Adjusting kit EADC-E16	For mounting the axis on a vertical surface. Once mounted, the axis can be aligned horizontally	37						
[17]	Central support EAHF-L5	For mounting the axis on the profile from underneath	35						
[18]	Adjusting kit EADC-E15	Height-adjustable. Can be used to easily compensate for any unevenness in the bearing surface	36						
[19]	Parallel kit EAMM-U	For parallel motor mounting (comprising: housing, clamping sleeve, toothed belt pulley, toothed belt)	eamm-u						
[20]	Motor EMMT	Motors specially matched to the axis, with or without gear unit, with or without brake	emmt						
[21]	Axial kit EAMM-A	For axial motor mounting (consisting of: coupling, coupling housing and motor flange)	eamm-a						

# Ball screw axes ELGA-BS-KF, with recirculating ball bearing guide

# Type codes

001	Series
ELGA	Gantry axis
002	Drive system
BS	Ball screw drive
003	Guide
KF	Recirculating ball bearing guide
004	Size
70	70
80	80
120	120
150	150
005	Stroke range [mm]
	50 3000
006	Stroke reserve
Н	0 999 mm
007	Spindle pitch
10P	10 mm
20P	20 mm
25P	25 mm
40P	40 mm

800	Motor attachment position	
ML	Left	Т
MR	Right	
009	Additional slide	
	None	
ZL	1 slide left	
ZR	1 slide right	
010	Protection against particles	
	Standard	
P11	Cover strip with magnetic deflection	
011	Displacement encoder	
	None	
M1	With displacement encoder, incremental, resolution 2.5 µm	
M2	With displacement encoder, incremental, resolution 10 µm	
012	Displacement encoder attachment position	
	None	
	None	
F	Front	$\top$

Function



- **Ø** - Size

70 ... 150

- | -

Stroke length 50 ... 3000 mm



www.festo.com



Repair service



General technical data							
Size		70	80		120		150
Screw pitch	[mm/rev]	10	10	20	10	25	40
Design		Electromechanical	axis with ball scre	W			
Guide		Recirculating ball b	pearing guide				
Mounting position		Any					
Working stroke	[mm]	50 900	50 194	10	50 246	50	50 3000
Max. feed force F <sub>x</sub> <sup>1)</sup>	[N]	650	1600		3400		6400
No-load torque	[Nm]	0.17	0.3	0.35	1.0	1.0	2.2
at low travel speed	[m/s]	0.05	0.1		0.2		0.2
No-load torque	[Nm]	0.45	0.75	0.75	2.25	2.25	6.5
At max. travel speed	[m/s]	0.5	0.5	1	0.6	1.5	2
Max. radial force <sup>2)</sup>	[N]	220	250		500		4000
Max. speed	[m/s]	0.5	0.5	1	0.6	1.5	2
Max. rotational speed <sup>3)</sup>	[rpm]	3000	3000		3600	*	3000
Max. acceleration	[m/s <sup>2</sup> ]	15	·				
Repetition accuracy	[mm]	±0.02					

- 1) The feed force affects the service life. (→ Page 16)
- At the drive shaft
- 3) Rotational speed and velocity are stroke-dependent

Operating and environmental conditions						
Ambient temperature	[°C]	-10 +60				
Degree of protection		IP40				
Duty cycle	[%]	100				

Weight [g]								
Size	70	80	120	150				
Basic weight with 0 mm stroke <sup>1</sup> )	2160	3800	10500	25100				
Additional weight per 10 mm stroke	33	46	99	210				
Moving mass	Moving mass							
ELGA	804	1370	4459	10514				
ELGAZL/ZR	620	1110	3600	5900				

<sup>1)</sup> Including slide

Ball screw							
Size		70	80		120		150
Diameter	[mm]	12	15		25		40
Pitch	[mm/rev]	10	10	20	10	25	40

# Ball screw axes ELGA-BS-KF, with recirculating ball bearing guide

# Datasheet

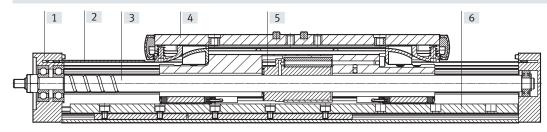
Mass moment of inertia							
Size		70	80		120		150
Screw pitch	[mm/rev]	10	10	20	10	25	40
Jo	[kg mm <sup>2</sup> ]	3.8	9.7	9.7	103.8	103.8	863
J <sub>H</sub> per metre stroke	[kg mm <sup>2</sup> /m]	14.2	34.6	34.6	275.6	275.6	1803.1
J <sub>L</sub> per kg payload	[kg mm²/kg]	2.53	2.53	10.13	2.53	15.83	40.53

The mass moment of inertia  $J_A$  of the rotating parts of the axis is calculated as follows:

 $J_A = J_O + J_H \times I[m] + J_L \times m_{payload}[kg]$ 

### Materials

Sectional view



Axis		
[1]	Drive cover	Anodised wrought aluminium alloy
[2]	Cover strip	Stainless steel strip, non-corroding
[3]	Ball screw	Steel
[4]	Slide	Anodised wrought aluminium alloy
[5]	Ball screw nut	Steel
[6]	Profile with integrated guide	Anodised wrought aluminium alloy
	Note on materials	RoHs-compliant
		Contains paint-wetting impairment substances

Technical data – Displacement end	Dimensions → page 29			
Туре		ELGAM1	ELGAM2	
Resolution	[µm]	2.5	10	
Max. travel speed with displacement encoder	[m/s]	4	4	
Encoder signal		5 V TTL; A/A, B/B; reference signal (N/N) cyclically every 5 mm (zero pulse)		
Signal output		Line driver, alternating, resistant to sustained short circuit		
Electrical connection		8-pin plug, round design, M12		
Cable length	[mm]	160		

Operating and environmental conditions – Displacement encoder		
Ambient temperature	[°C]	-10 +70
Degree of protection		IP64
CE marking (see declaration of conformity)		To EU EMC Directive <sup>1</sup> )

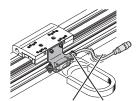
<sup>1)</sup> For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

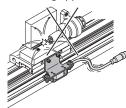
### **Application note**

The ball screw axis with displacement encoder is not designed for the following application examples:

• Magnetic field

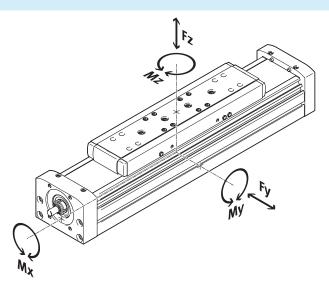


• Welding application

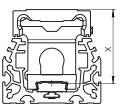


### Characteristic load values

The indicated forces and torques refer to the centre of the guide. The point of application of force is the point where the centre of the guide and the longitudinal centre of the slide intersect. These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



Distance from the slide surface to the centre of the guide



Distance from the slide surface to the centre of the guide					
Size		70	80	120	150
Dimension x	[mm]	51	60	87	111

Max. permissible for	Max. permissible forces and torques for a service life of 5000 km					
Size		70	80	120	150	
Fy <sub>max</sub> .	[N]	1500	2500	5500	5500	
Fz <sub>max</sub> .	[N]	1850	3050	6890	11000	
Mx <sub>max</sub> .	[Nm]	16	36	104	167	
My <sub>max</sub> .	[Nm]	132	228	680	1150	
Mz <sub>max</sub> .	[Nm]	132	228	680	1150	

Basic load ratings							
Size		70	80		120		150
Screw pitch	[mm/rev]	10	10	20	10	25	40
Ball screw							
Dynamic c <sub>dyn,KGT</sub>	[N]	4000	6800	5700	14100	12700	25000



### Note

For a guide system to have a service life of 5000 km, the load comparison factor must have a value of  $fv \le 1$ , based on the maximum permissible forces and torques for a service life of 5000 km.

If the axis is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

Calculating the load comparison factor:

$$f_v = \frac{\left| F_{y1} \right|}{F_{y2}} + \frac{\left| F_{z1} \right|}{F_{z2}} + \frac{\left| M_{x1} \right|}{M_{x2}} + \frac{\left| M_{y1} \right|}{M_{y2}} + \frac{\left| M_{z1} \right|}{M_{z2}} \leq 1$$

 $F_1/M_1 = dynamic value$ 

 $F_2/M_2 = maximum value$ 

### Service life of the guide

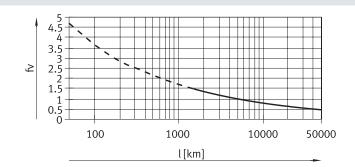
The service life of the guide depends on the load. To be able to make a statement as to the service life of the guide, the graph below plots the load comparison factor fv against the service life.

These values are only theoretical. You must consult your local Festo contact for a load comparison factor fv greater than 1.5.

### Load comparison factor fv as a function of service life

### Example:

A user wants to move an x kg load. Using the formula (→ Seite 14) gives a value of 1.5 for the load comparison factor fv. According to the graph, the guide would have a service life of approx. 1500 km. Reducing the acceleration reduces the My and Mz values. A load comparison factor fv of 1 now gives a service life of 5000 km.



### Note

Engineering software **Electric Motion Sizing** www.festo.com/x/electricmotion-sizing

The engineering software can be used to calculate the guide workload for a service life of

5000 km.

f<sub>v</sub> > 1.5 are only theoretical comparison values for the recirculating ball bearing guide.

### Comparison of the characteristic load values for 5000 km with dynamic forces and torques of recirculating ball bearing guides

The characteristic load values of the bearing guides are standardised to ISO and JIS using dynamic and static forces and torques. These forces and torques are based on an expected service life of the guide system of 100 km to ISO or 50 km to JIS.

As the characteristic load values are dependent on the service life, the maximum permissible forces and torques for a 5000 km service life cannot be compared with the dynamic forces and torques of bearing guides to ISO/JIS.

To make it easier to compare the guide capacity of linear axes ELGA with bearing guides, the table below lists the theoretically permissible forces and torques for a calculated service life of 100 km. This corresponds to the dynamic forces and torques to ISO.

These 100 km values have been calculated mathematically and are only to be used for comparing with dynamic forces and torques to ISO. The drives must not be loaded with these characteristic values as this could damage the axes.

Max. permissible f	Max. permissible forces and torques for a theoretical service life of 100 km (from a guide perspective only)					
Size		70	80	120	150	
Fy <sub>max</sub> .	[N]	5520	9200	20240	20240	
Fz <sub>max</sub> .	[N]	6808	11224	25355	40480	
Mx <sub>max</sub> .	[Nm]	59	132	383	615	
My <sub>max</sub> .	[Nm]	486	839	2502	4232	
Mz <sub>max</sub> .	[Nm]	486	839	2502	4232	

### Ball screw axes ELGA-BS-KF, with recirculating ball bearing guide

### Datasheet

### Service life of the ball screw

- The service life of the ball screw axis depends on the service life of the guide (→ Page 15) also depends on that of the screw drive.
   The operating coefficient plays a considerable role in determining the possible service life. It can be determined with the help of the table (→ page 17)
- The service life ends when the maximum number of switching cycles or maximum running performance has been reached:
  - 5 million switching cycles or 5000 km running performance
- The distance between the foremost and rearmost positions must be at least 2.5 times the screw pitch per travel cycle
- The specifications for the running performance are based on experimentally determined and theoretically calculated data (at room temperature).

The running performance that can be achieved in practice can deviate considerably from the specified curves under different parameters

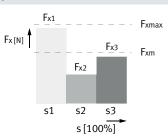
### Calculation of the mean feed force $F_{xm}$ with ball screw

$$F_{xm} = \sqrt[3]{\frac{F_{x1}^3 \cdot s_1 + \dots + F_n^3 \cdot s_n}{s_1 + \dots + s_n}}$$

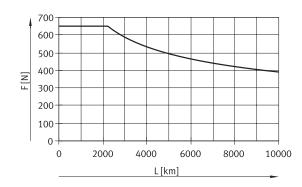
 $F_{xm}$  = Mean feed force

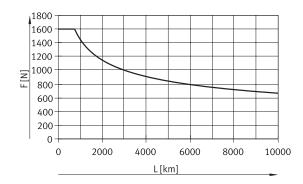
 $F_{x1/n}$  = Feed force of section

 $s_{1/n}$  = Part of the movement cycle that is travel

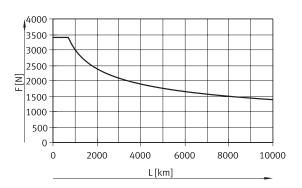


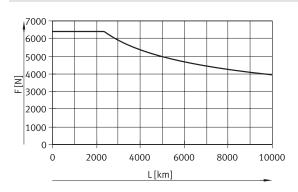
Mean feed force  $F_{xm}$  as a function of running performance L, with an operating coefficient  $f_B$  of 1.0, at room temperature Size 70 Size 80





 $Mean\ feed\ force\ F_{xm}\ as\ a\ function\ of\ running\ performance\ L,\ with\ an\ operating\ coefficient\ f_B\ of\ 1.0,\ at\ room\ temperature$ Size 150 Size 120





Service life taking into account the operating coefficient

$$L_1 = \frac{L}{f_B^3}$$

= Actual service life

= Target service life

(→ diagrams)

= Operating coefficient

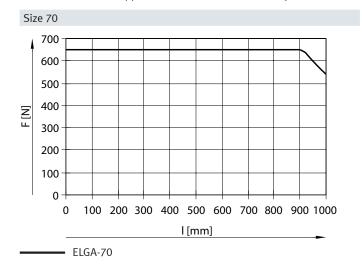
Load <sup>1)</sup>	Operating coefficient f <sub>B</sub>	Application example
None	1.0 1.2	Measuring machine
Light	1.2 1.4	Handling, robot technology
Medium	1.4 1.6	Press-in operations
High	1.6 2.0	Construction, agriculture

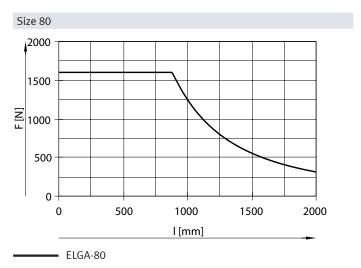
1) Loads caused by impact, temperature, contamination, shock and vibrations  ${\bf r}$ 

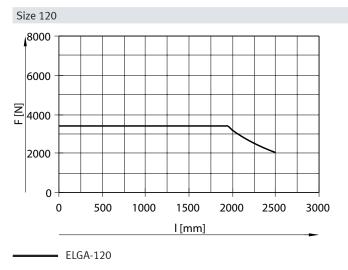
### Max. feed force F as a function of the working stroke l

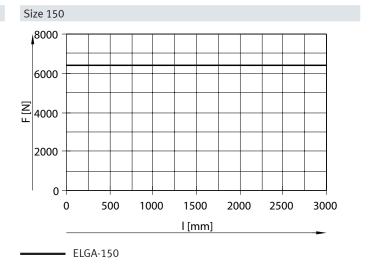
The feed force that pushes the ball screw in the direction of the motor must be limited depending on the stroke due to possible buckling (e.g. acceleration of a load mass away from the motor, deceleration of a load moving towards the motor).

The feed force in the opposite direction is not affected by this.

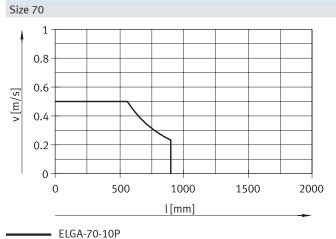


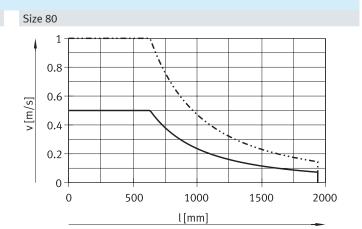




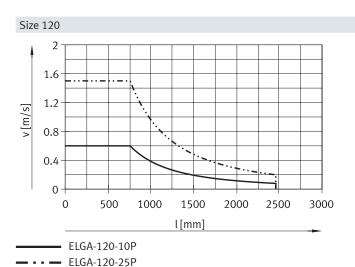


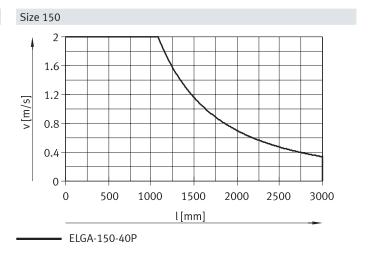
### Speed v as a function of working stroke l



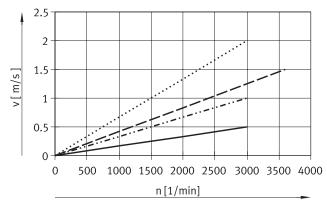


ELGA-80-10P
ELGA-80-20P





Speed  $\boldsymbol{v}$  as a function of rotational speed  $\boldsymbol{n}$ 

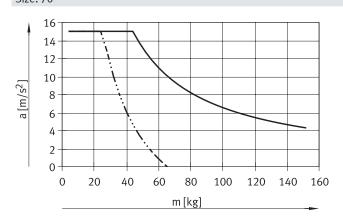


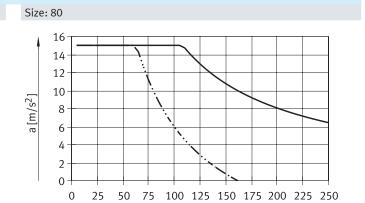
- Note

Rotational speed is strokedependent. Note maximum rotational speed.

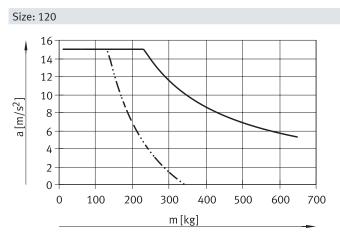
### Max. acceleration a as a function of payload m

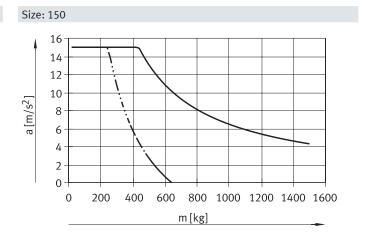
Size: 70





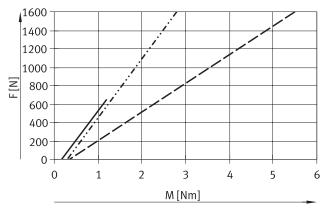
m[kg]

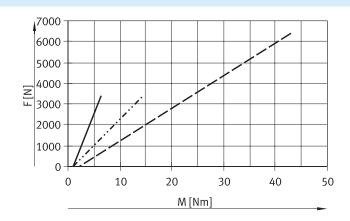




Horizontal mounting positionVertical mounting position

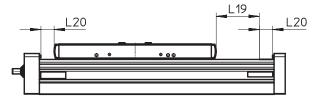
### Theoretical feed force F as a function of the input torque M





ELGA-70-10P
---- ELGA-80-10P
---- ELGA-80-20P

### Stroke reserve



L19 = Nominal stroke L20 = Stroke reserve

- The stroke reserve is a safety distance from the mechanical end position and is not used in normal operation
- The sum of the nominal stroke and 2x stroke reserve must not exceed the maximum permissible working stroke
- The length can be freely selected
- The stroke reserve is defined via the "stroke reserve" characteristic in the modular product system

### Example:

Type ELGA-BS-KF-70-500-20H-...

Nominal stroke = 500 mm

2x stroke reserve = 40 mm

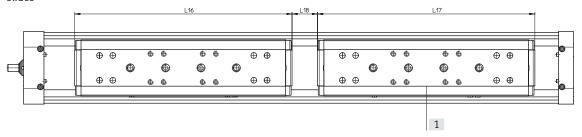
Working stroke = 540 mm

(540 mm = 500 mm + 2x 20 mm)

### **Working stroke reduction**

With axis ELGA with additional slide ZL/ZR

For a ball screw axis with additional slide, the working stroke is reduced by the length of the additional slide and the distance between both slides



L16 = Slide length
L17 = Additional slide length
L18 = Distance between the two slides

[1] Additional slide

### **Example:**

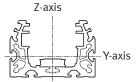
Type ELGA-BS-KF-70-500-...-ZR Working stroke without

additional slide = 500 mmL18 = 50 mmL16, L17 = 221 mmWorking stroke with additional slide = 229 mm

(500 mm - 50 mm - 221 mm)

### Dimensions - Additional slide Size 70 80 120 150 Length L17 246 [mm] 221 335 378.4 Min. distance between the ≥ 50 ≥ 50 ≥ 50 slides L18

### Second moment of area

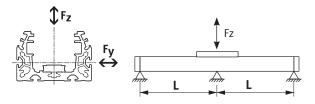


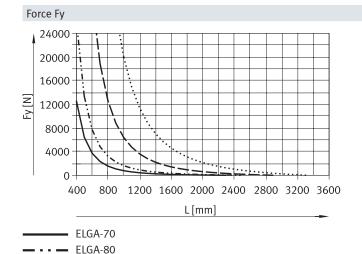
S	ize	70	80	120	150
ly	(mm <sup>4</sup> ]	165x10 <sup>3</sup>	310x10 <sup>3</sup>	1.24x10 <sup>6</sup>	4.70x10 <sup>6</sup>
lz	z [mm <sup>4</sup> ]	472x10 <sup>3</sup>	977x10 <sup>3</sup>	3.80x10 <sup>6</sup>	11.81x10 <sup>6</sup>

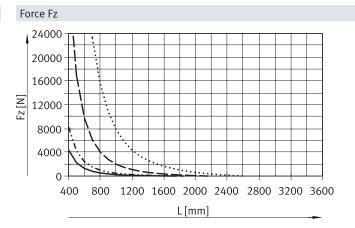
### Maximum permissible support spacing L (without profile mounting MUE/central support EAHF) as a function of force F

The axis may need to be supported in order to limit deflection in the case of long strokes.

The following graphs can be used to determine the maximum permissible support spacing l as a function of force F acting on the axis. The deflection is  $f=0.5\,$  mm.







### Recommended deflection limits

ELGA-120ELGA-150

Adherence to the following deflection limits is recommended so as not to impair the functionality of the axes.

Greater deformation can result in increased friction, greater wear and reduced service life.

Size	Dynamic deflection (load moves)	Static deflection (stationary load)
70 150	0.05% of the axis length, max. 0.5 mm	0.1% of the axis length

### Central lubrication system

The lubrication connections enable the guide and the ball screw of the ball screw axis ELGA-BS-KF to be permanently lubricated in applications in humid or wet ambient conditions using semi- or fully automatic relubrication devices.

- The axes are suitable for oils and greases
- The connection options are already available in the standard design of the axes
- There is a dedicated lubrication connection for the ball screw nut and the two ball cassettes

Slide dimensions

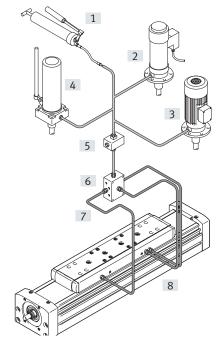
→ page 24

### Design of a central lubrication system

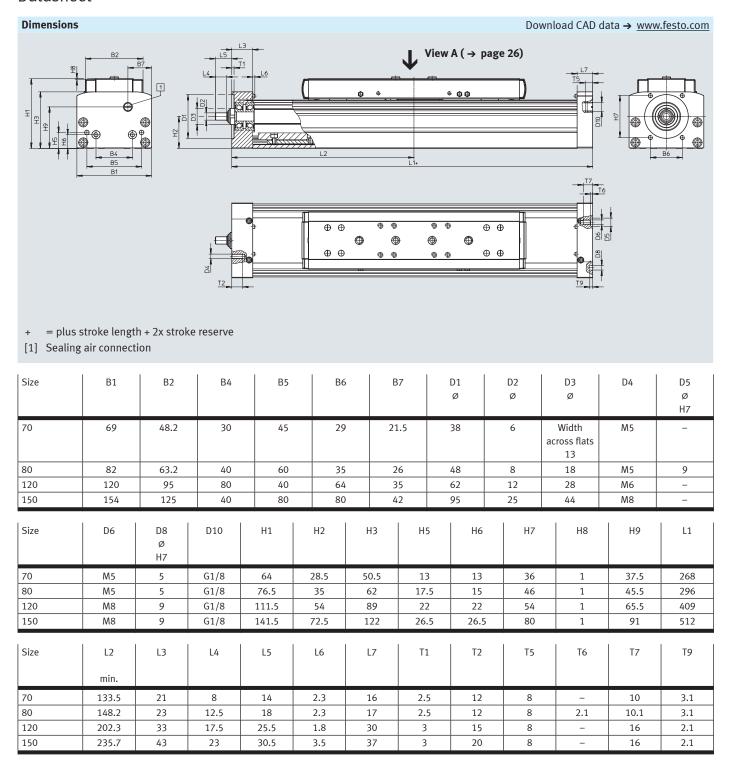
A central lubrication system requires various additional components. The illustration shows different options (using a hand pump, pneumatic container pump or electric container pump) required as a minimum for designing a central lubrication system. Festo does not sell these additional components; however, they can be obtained from the following companies:

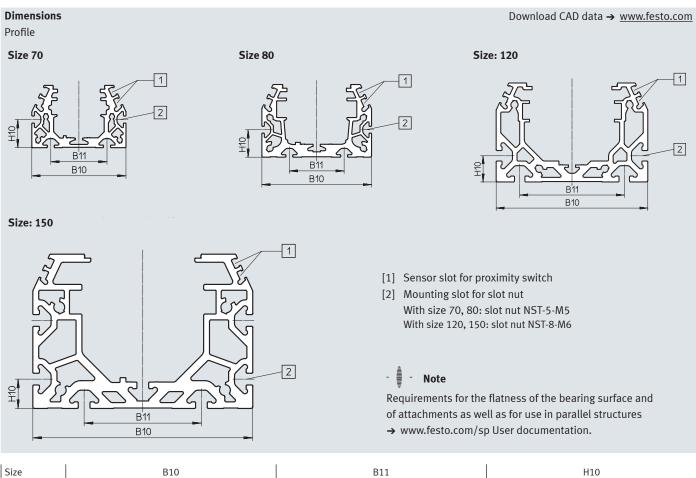
- Lincoln
- Bielomatik
- SKF (Vogel)

Festo recommends these companies because they can supply all the necessary components.

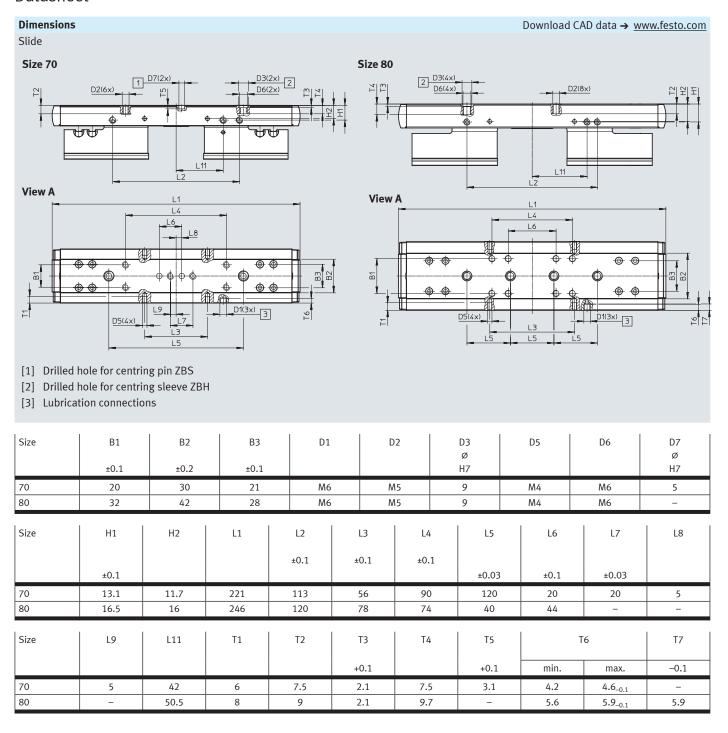


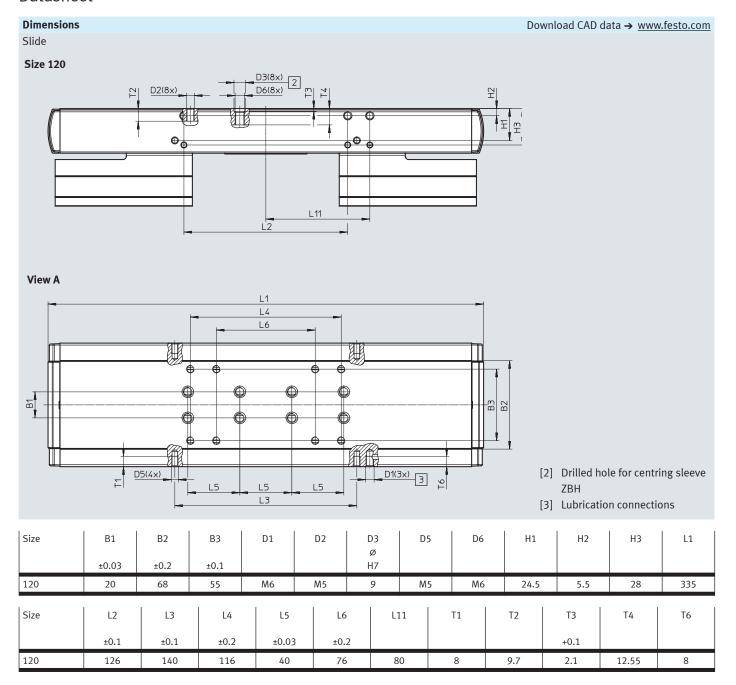
- [1] Hand pump
- [2] Pneumatic container pump
- [3] Electric container pump
- [4] Manually operated container pump
- [5] Nipple block
- [6] Distributor block
- [7] Tubing or piping
- [8] Fittings

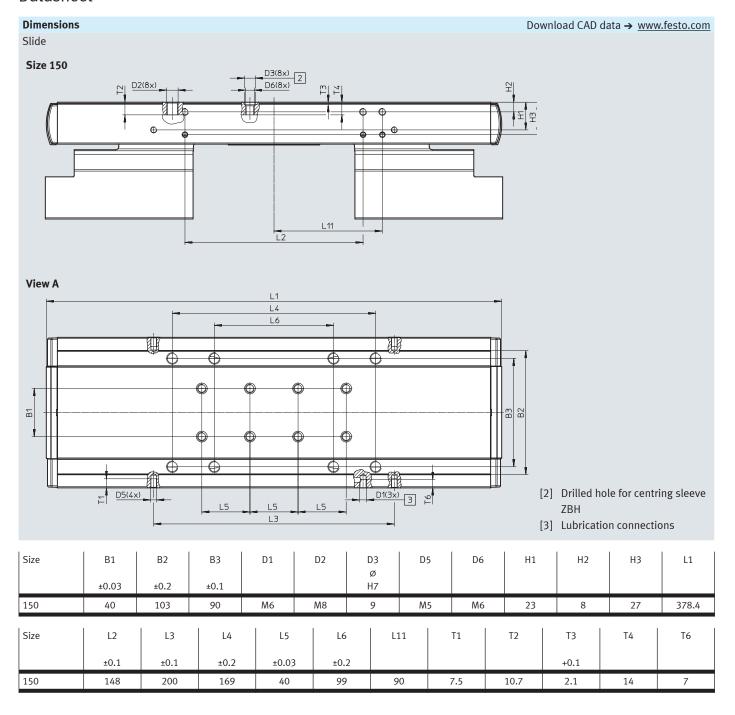




Size	B10	B11	H10
70	67	40	20
, ·	<u> </u>	, -	
80	80	40	20
120	116	80	20
150	150	80	20

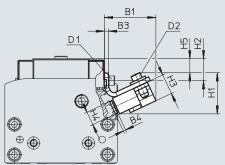




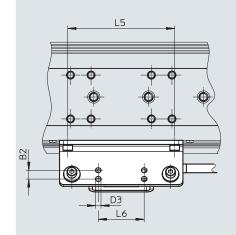


# Dimensions

ELGA-...-M1/M2 – With incremental displacement encoder



Download CAD data → www.festo.com



L4 L3 L2

Encoder cable (connection to motor controller/ safety system)

🗩 rage 42	<b>→</b>	Page	42
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Size	B1	B2	В3	B4	D1	D2	D3 Ø	H1	H2
70	40	7	3	1.8	M4x8	M4x14	4	35	11.7
80	40	7	3	1.8	M4x14	M4x14	4	35	16
120	41	7	3	1.8	M4x14	M4x14	4	35	24.5
150	42	7	3	1.8	M5x10	M4x14	4	35	23
Size	H3	H4	H5	L1	L2	L3	L4	L5	L6
70	15	10	3.5	86	82	72	47	56	33.5
80	15	10	9	90	82	72	47	78	33.5
120	15	10	21	170	82	72	47	140	33.5
150	15	10	22.4	220	82	72	47	200	33.5

### Ordering data – Standard design

Key features:

• Stroke reserve: 0 mm

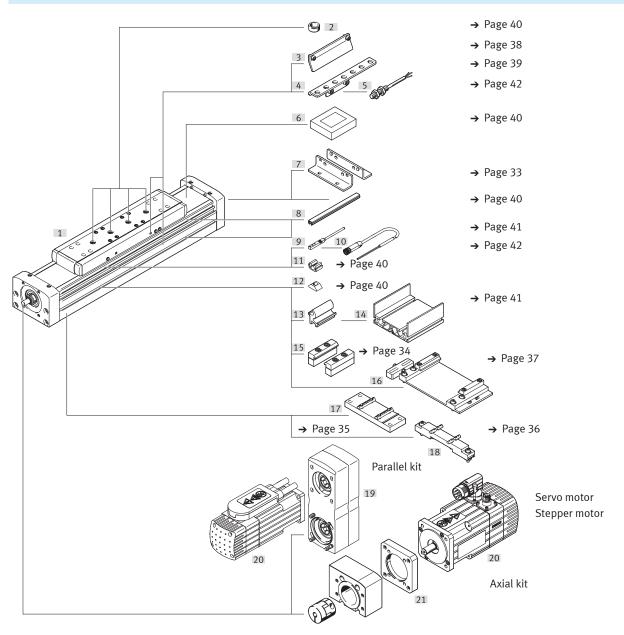
• Motor attachment position: left

Size	Pitch	Stroke	Part no.	Туре
	[mm/rev]	[mm]		
70	10	100	8041816	ELGA-BS-KF-70-100-0H-10P-ML
		200	8041817	ELGA-BS-KF-70-200-0H-10P-ML
		300	8041818	ELGA-BS-KF-70-300-0H-10P-ML
		400	8041819	ELGA-BS-KF-70-400-0H-10P-ML
		500	8041820	ELGA-BS-KF-70-500-0H-10P-ML
		600	8041821	ELGA-BS-KF-70-600-0H-10P-ML
80	10	100	8041822	ELGA-BS-KF-80-100-0H-10P-ML
80	10	200	8041823	ELGA-BS-KF-80-200-0H-10P-ML
		300	8041824	ELGA-BS-KF-80-300-0H-10P-ML
		400	8041825	ELGA-BS-KF-80-400-0H-10P-ML
		500	8041826	ELGA-BS-KF-80-500-0H-10P-ML
		600	8041827	ELGA-BS-KF-80-600-0H-10P-ML
		800	8041828	ELGA-BS-KF-80-800-0H-10P-ML
	20	100	8041829	ELGA-BS-KF-80-100-0H-20P-ML
		200	8041830	ELGA-BS-KF-80-200-0H-20P-ML
		300	8041831	ELGA-BS-KF-80-300-0H-20P-ML
		400	8041832	ELGA-BS-KF-80-400-0H-20P-ML
		500	8041833	ELGA-BS-KF-80-500-0H-20P-ML
		600	8041834	ELGA-BS-KF-80-600-0H-20P-ML
		800	8041835	ELGA-BS-KF-80-800-0H-20P-ML
120	10	100	8041836	ELGA-BS-KF-120-100-0H-10P-ML
120	10	200	8041837	ELGA-BS-KF-120-100-0H-10P-ML
		300	8041838	ELGA-BS-KF-120-300-0H-10P-ML
		400	8041839	ELGA-BS-KF-120-400-0H-10P-ML
		500	8041840	ELGA-BS-KF-120-500-0H-10P-ML
		600	8041841	ELGA-BS-KF-120-600-0H-10P-ML
		800	8041842	ELGA-BS-KF-120-800-0H-10P-ML
	25	100	8041843	ELGA-BS-KF-120-100-0H-25P-ML
		200	8041844	ELGA-BS-KF-120-200-0H-25P-ML
		300	8041845	ELGA-BS-KF-120-300-0H-25P-ML
		400	8041846	ELGA-BS-KF-120-400-0H-25P-ML
		500	8041847	ELGA-BS-KF-120-500-0H-25P-ML
		600	8041848	ELGA-BS-KF-120-600-0H-25P-ML
		800	8041849	ELGA-BS-KF-120-800-0H-25P-ML

# Ordering data – Modular product system

# Orientation guide O Top U Bottom R Right L Left V Front H Rear ELGA-...-ZL Lubrication connections

### Accessories



# Ball screw axes ELGA-BS-KF, with recirculating ball bearing guide

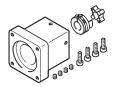
# Ordering data – Modular product system

<b>Ordering table</b> Size		70	80	120	150	Conditions	Code	Enter code
Module no.		8024918	8024919	8024920	8024921			
Design		Linear axis					ELGA	ELGA
Function		Ball screw					-BS	-BS
Guide		Recirculating bal	l bearing guide				-KF	-KF
Size	[mm]	70	80	120	150			
Stroke length Standard (without stroke reserve)	[mm]	100, 200, 300, 400, 500, 600, 700, 900	100, 200, 300, 400, 500, 600, 700, 800, 900, 1300, 1440, 1740, 1940	100, 200, 300, 400, 500, 600, 700, 800, 900, 1300, 1400, 1960, 2460	200, 400, 500, 900, 1400, 1900, 2500, 3000			
Variable	[mm]	50 880	50 1920	50 2440	50 2980			
Stroke reserve	0 999 (0 = no s	[1]	H					
Screw pitch		10	10	10	_		-10P	
		-	20	-	-		-20P	
		-	_	25	_		-25P	
		-	_	_	40		-40P	
Motor attachment position		Left					-ML	
		Right					-MR	
Additional slide		None						
		1 slide on the left					-ZL	
		1 slide on the right					-ZR	
Protection against particles		Standard						
		Cover strip with r	nagnetic deflection	1			P11	
Displacement encoder, incremental		None						
		Resolution 2.5 μm					-M1	
		Resolution 10 µm	1				-M2	
Displacement encoder attachment position		None						
		Rear				[2]	В	
		Advanced				[2]	F	

 $<sup>[1] \;\; \</sup>dots \, H \quad \text{ The sum of the nominal stroke and } 2x \, \text{stroke reserve must not exceed the maximum stroke length}$ 

<sup>[2]</sup> B, F Only with displacement encoder M1, M2

### Permitted axis/motor combinations for axial and parallel kits



Under the following links you will find all information about:

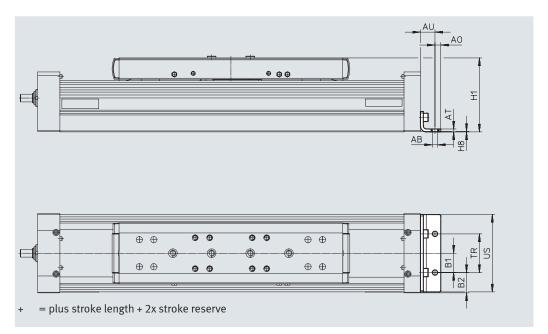
- Axis/motor combinations
- Permitted third-party motors
- Technical data
- Dimensions

For axial kits → Internet: <u>eamm-a</u>
For parallel kits → Internet: <u>eamm-u</u>

### Foot mounting HPE

Material: Galvanised steel RoHs-compliant





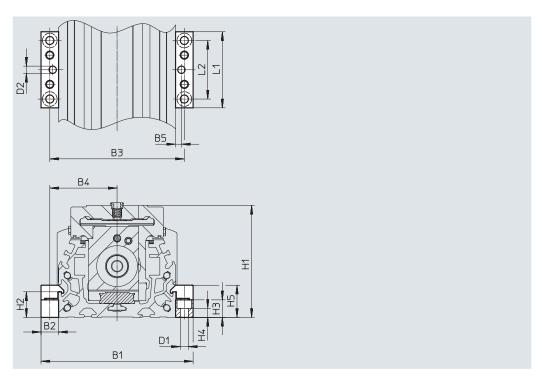
Dimensions and	Dimensions and ordering data												
For size	AB Ø	A0	AT	AU	B1	B2	H1	H8					
70	5.5	6	3	13	20	14.5	64	0.5					
80	5.5	6	3	15	20	21	76.5	0.5					
120	9	8	6	22	40	20	111.5	1					
150	9	12	8	25	40	35	141.5	1					

For size	TR	US	Weight	Part no.	Туре
			[g]		
70	40	67	115	558321	HPE-70
80	40	80	150	558322	HPE-80
120	80	116	578	558323	HPE-120
150	80	150	1181	3002636	HPE-150

### Profile mounting MUE

Material: Anodised aluminium RoHs-compliant





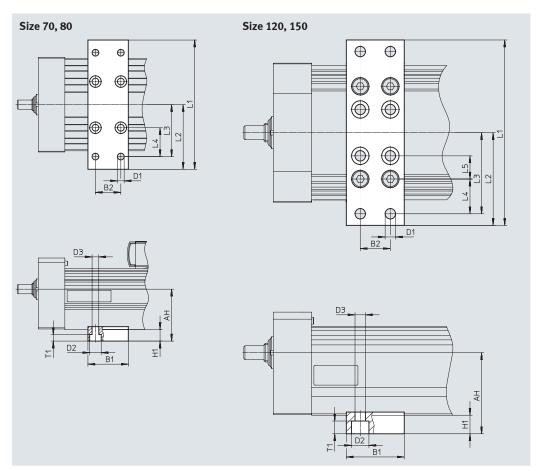
Dimensions and o	Dimensions and ordering data												
For size	B1	B2	В3	B4	B5	D1	D2	H1	H2				
						Ø	Ø						
							H7						
70	91	12	79	39.5	4	5.5	5	64	17.5				
70 80	91 104	12 12	79 92	39.5 46	4	5.5 5.5	5	64 76.5	17.5 17.5				
					4 4		5 5 5						

For size	Н3	H4	H5	L1	L2	Weight	Part no.	Туре
						[g]		
70	12	6.2	22	52	40	80	558043	MUE-70/80
80	12	6.2	22	52	40	80	558043	MUE-70/80
120	14	5.5	29.5	90	40	290	558044	MUE-120/185
150	14	5.5	29.5	90	40	290	558044	MUE-120/185

### Central support EAHF

Material: Anodised aluminium RoHs-compliant





Dimensions and o	Dimensions and ordering data											
For size	AH	B1	B2	D1	D2	D3	H1	L1				
				ø	ø	ø						
70	38.5	35	22	5.8	10	5.8	10	102				
80	45							112				
120	70	50	26	9	15	9	16	160				
150	88.5							200				

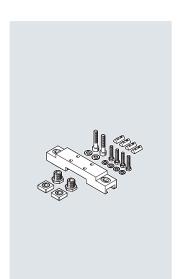
For size	L2	L3	L4	L5	T1	Weight [g]	Part no.	Туре
70	51	45	25	-	5.7	113	2349256	EAHF-L5-70-P
80	62	50		_		123	3535188	EAHF-L5-80-P
120	80	70	30	20	11	384	2410274	EAHF-L5-120-P
150	100	90	50	_		495	3535189	EAHF-L5-150-P

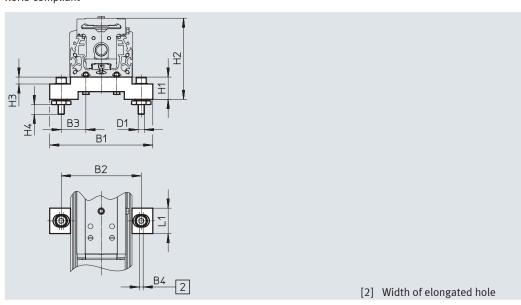
### Adjusting kit EADC-E15

Material:

EADC-E15-80: wrought aluminium alloy

EADC-E15-185: Steel RoHs-compliant



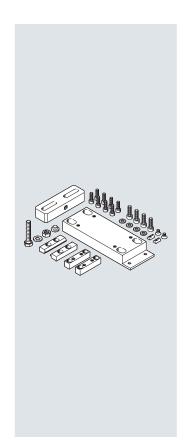


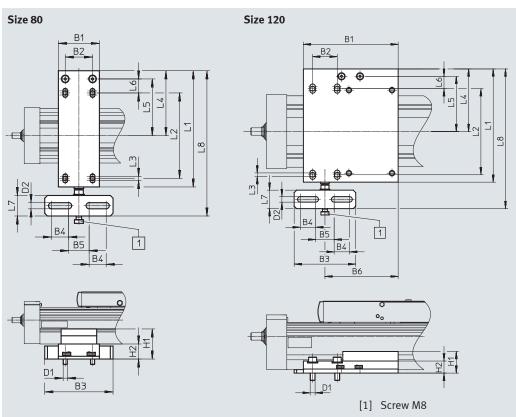
Dimensions and o	Dimensions and ordering data											
For size	B1	B2	В3	B4	D1	H1						
70	134	104	32	5	M8	29						
80	134	104	32	5	M8	29						
120	236	209	64.5	5	M8	29						
150	236	209	64.5	5	M8	29						

For size	H2	Н3	H4	L1	Weight [g]	Part no.	Туре
70	93	9	12.6	33	386	8047566	EADC-E15-80-E7
80	105.5	9	12.6	33	386	8047566	EADC-E15-80-E7
120	140.5	9	12.6	33	569	8047568	EADC-E15-185-E7
150	170.5	9	12.6	33	569	8047568	EADC-E15-185-E7

### Adjusting kit EADC-E16

Material: Wrought aluminium alloy RoHs-compliant



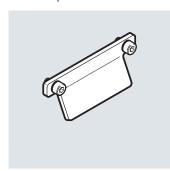


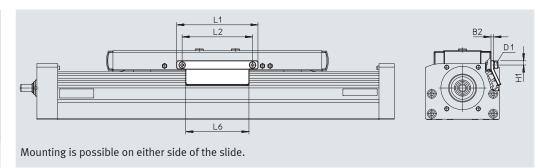
Dimensions and o	Dimensions and ordering data											
For size	B1	B2	В3	B4	B5	B6	D1	D2	H1	H2	L1	L2
80	60	40	100	25	30	_	M6	9	44	22	170	125
120	154	40	100	25	30	119	M8	9	35.1	19.6	184	140

For size	L3	L4	L5	L6	L7	L8	Weight [g]	Part no.	Туре
80	6	95	83	20.5	30	212.5	828	8047577	EADC-E16-80-E7
120	6	101.7	89.7	20	30	227	1134	8047578	EADC-E16-120-E7

### Switch lug SF-EGC-1

Material: Galvanised steel RoHs-compliant





Dimensions and o	Dimensions and ordering data											
For size	B2	D1	H1	L1	L2	L6	Weight [g]	Part no.	Туре			
70	3	M4	4.65	70	56	50	50	558047	SF-EGC-1-70			
80	3	M4	4.65	90	78	70	63	558048	SF-EGC-1-80			
120	3	M5	8	170	140	170	147	558049	SF-EGC-1-120			
150	3	M5	10	230	200	230	246	558051	SF-EGC-1-185			

### Switch lug SF-EGC-2

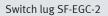
For sensing with proximity sensor SIEN-M8B or SIES-8M

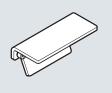
### Sensor bracket HWS-EGC

For proximity switch SIEN-M8B

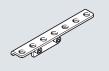
Material: Galvanised steel RoHs-compliant Material: Galvanised steel RoHS-compliant

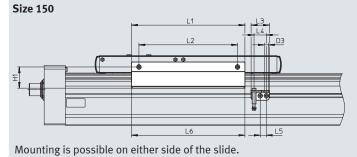
Size 70, 80, 120

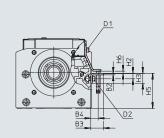




Sensor bracket HWS-EGC







Dimensions and o	Dimensions and ordering data											
For size	B1	B2	В3	B4	D1	D2	D3	H1	H2			
							Ø					
70	31.5	3	25.5	18	M4	M5	8.4	9.5	35			
80	31.5	3	25.5	18	M4	M5	8.4	9.5	35			
120	32	3	25.5	18	M5	M5	8.4	13.2	65			
150	33	3	25.5	15	M5	M5	8.4	43	20			

For size	Н3	H5	H6 max.	L1	L2	L3	L4	L5	L6
70	25	45	13.5	70	56	135	20	35	50
80	25	45	23.5	90	78	135	20	35	70
120	55	75	24	170	140	215	20	35	170
150	11	71	4.5	230	200	37	25	12.5	230

For size	Weight [g]	Part no.	Туре
	Switch lug		
70	100	558052	SF-EGC-2-70
80	130	558053	SF-EGC-2-80
120	277	558054	SF-EGC-2-120
150	390	558056	SF-EGC-2-185

For size	Weight	Part no.	Туре
	[g]		
	Sensor bracke	t	
70	110	558057	HWS-EGC-M5
80	110	558057	HWS-EGC-M5
120	217	570365	HWS-EGC-M8-B
150	58	560517	HWS-EGC-M8: KURZ (SHORT)

# Ball screw axes ELGA-BS-KF, with recirculating ball bearing guide

# Accessories

Ordering data	l .				
	For size	Description	Part no.	Туре	PU <sup>1</sup>
lot nut NST					
510t Hut N51	70,80	For mounting slot	150914	NST-5-M5	1
	,		8047843	NST-5-M5-10	10
<b>₩</b>			8047878	NST-5-M5-50	50
	120, 150	For mounting slot	150915	NST-8-M6	1
			8047868	NST-8-M6-10	10
			8047869	NST-8-M6-50	50
Centring nin 7	BS/centring sleeve	7RH			
Economic pin 2	70	For slide	150928	ZBS-5	10
	70, 80, 120, 150		8137184	ZBH-9-B	
Slot cover ABI	1			1-	
	70, 80	For mounting slot	151681	ABP-5	2
	120, 150	Every 0.5 m	151682	ABP-8	
9					
Slot cover ABI	p-S				
	70 150	For sensor slot	563360	ABP-5-S1	2
		• Every 0.5 m			
1					
Clip SMBK	-				
	70 150	For sensor slot, for mounting the proximity switch cables	534254	SMBK-8	10
Clamping com	ponent EADT	I			
	70, 80	Tool for retensioning the cover strip	8058451	EADT-S-L5-70	1
$\langle \langle \rangle \rangle$	120, 150		8058450	EADT-S-L5-120	_
<b>Y</b> /	, -	_L			

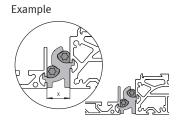
<sup>1)</sup> Packaging unit

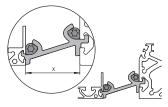
### Mounting options between axis and support profile

Depending on the adapter kit, the spacing between the axis and the support profile is:

x = 20 mm or 50 mm

The support profile must be mounted using at least 2 adapter kits. For longer strokes, an adapter kit must be used every 500 mm.





For size	Description	Part no.	Туре	PU <sup>1)</sup>
M				
80	For mounting the support profile on the axis	562241	DHAM-ME-N1-CL	1
120, 150	Spacing between axis and profile is 20 mm	562242	DHAM-ME-N2-CL	
70, 80	For mounting the support profile on the axis     Spacing between axis and profile is 50 mm	574560	DHAM-ME-N1-50-CL	
120, 150		574561	DHAM-ME-N2-50-CL	
IMIA				
70 150	For guiding an energy chain	539379	HMIA-E07-	1
	80 120, 150 70, 80 120, 150	80 • For mounting the support profile on the axis • Spacing between axis and profile is 20 mm  70, 80 • For mounting the support profile on the axis • Spacing between axis and profile is 50 mm  120, 150	80 For mounting the support profile on the axis 120, 150 Spacing between axis and profile is 20 mm  70, 80 For mounting the support profile on the axis Spacing between axis and profile is 50 mm  574560  120, 150  574561	80 For mounting the support profile on the axis 120, 150 Spacing between axis and profile is 20 mm  70, 80 For mounting the support profile on the axis Spacing between axis and profile is 50 mm  70, 80 For mounting the support profile on the axis Spacing between axis and profile is 50 mm  120, 150 DHAM-ME-N1-50-CL  574561 DHAM-ME-N2-50-CL

<sup>1)</sup> Packaging unit

Ordering data	– Proximity switches for T-slot, inducti	ve ·				Datasheets → Internet: sies
	Type of mounting	Electrical connection	Switching output	Cable length	Part no.	Туре
			output	[m]		
N/O						
	Inserted in the slot from above, flush	Cable, 3-core	PNP	7.5	551386	SIES-8M-PS-24V-K-7.5-OE
SEE ALL DESCRIPTION OF THE PERSON OF THE PER	with the cylinder profile	Plug M8x1, 3-pin		0.3	551387	SIES-8M-PS-24V-K-0.3-M8D
		Cable, 3-core	NPN	7.5	551396	SIES-8M-NS-24V-K-7.5-OE
		Plug M8x1, 3-pin		0.3	551397	SIES-8M-NS-24V-K-0.3-M8D
N/C						
	Inserted in the slot from above, flush	Cable, 3-core	PNP	7.5	551391	SIES-8M-PO-24V-K-7.5-OE
ST. W.	with the cylinder profile	Plug M8x1, 3-pin	]	0.3	551392	SIES-8M-PO-24V-K-0.3-M8D
(Marian)		Cable, 3-core	NPN	7.5	551401	SIES-8M-NO-24V-K-7.5-OE
		Plug M8x1, 3-pin		0.3	551402	SIES-8M-NO-24V-K-0.3-M8D

# Ball screw axes ELGA-BS-KF, with recirculating ball bearing guide

# Accessories

Ele	ectrical connection	LED	I	ering data – Proximity switch M8 (round design), inductive									
		LLD	Switching output	Cable length [m]	Part no.	Туре							
N/O													
Cal	able, 3-core		PNP	2.5	150386	SIEN-M8B-PS-K-L							
		•	NPN	2.5	150384	SIEN-M8B-NS-K-L							
Plu	ug M8x1, 3-pin		PNP	_	150387	SIEN-M8B-PS-S-L							
		•	NPN	_	150385	SIEN-M8B-NS-S-L							
N/C													
Cal	able, 3-core		PNP	2.5	150390	SIEN-M8B-PO-K-L							
		•	NPN	2.5	150388	SIEN-M8B-NO-K-L							
Plu	ug M8x1, 3-pin		PNP	-	150391	SIEN-M8B-PO-S-L							
		•	NPN	-	150389	SIEN-M8B-NO-S-L							

Ordering data	- Connecting cable	s					Datasheets → Internet: neba
	Electrical connection 1, connection technology	Electrical connection 1, cable outlet	Electrical connection 2, connection technology	Electrical connection 2, number of pins/ cores	Cable length [m]	Part no.	Туре
	M8x1 A-coded to	Straight	Open end	3	2.5	8078223	NEBA-M8G3-U-2.5-N-LE3
	EN 61076-2-104				5.0	8078224	NEBA-M8G3-U-5-N-LE3
	M8x1 A-coded to	Angled	Open end	3	2.5	8078230	NEBA-M8W3-U-2.5-N-LE3
	EN 61076-2-104				5.0	8078231	NEBA-M8W3-U-5-N-LE3

Ordering data – Encoder cables for displacement encoder, ELGAM1/-M2  Datasheets → Internet						
	Electrical connection, left	Electrical connection, right	Cable length	Part no.	Туре	
			[m]			
	Displacement encoder ELGA	Motor controller CMMP-AS and	5	1599105	NEBM-M12G8-E-5-S1G9-V3	
	M1/-M2	CMMT-AS	10	1599106	NEBM-M12G8-E-10-S1G9-V3	
			15	1599107	NEBM-M12G8-E-15-S1G9-V3	
			X <sup>1)</sup>	1599108	NEBM-M12G8-ES1G9-V3	

<sup>1)</sup> Max. cable length: 25 m.

Ordering data – Adapter						
		Description	Part no.	Туре		
<b>S</b>		Required in combination with the servo drive CMMT-AS as adapter between encoder cable NEBM-M12G8V3 and interface X3 (position encoder 2)	8106112	NEFM-S1G9-K-0.5-R3G8		